

## Research paper

# Enhancing Patient Movement Rehabilitation: Integration of Intelligent Prosthetic Limbs and the Internet of Things

**Mohammad Reza Einollahi Asgarabad\*<sup>1</sup>, Mohammad Mahdi Amirbeigi<sup>1</sup>, Ramin Ardalani<sup>1</sup>  
Seyedeh Fatemeh Arfaee Zarandi<sup>1</sup>, Ali Jamali Nazari<sup>2</sup>**

<sup>1</sup>Department of Health and Medical Engineering, Tehran Medical Sciences, Islamic Azad University, Tehran, Iran

<sup>2</sup>Department of Engineering, Shahrood Branch, Islamic Azad University, Shahrood, Iran,

## Article Info

### Article History:

Received: October 12, 2023

Revised: December 08, 2023

Accepted: December 30, 2023

### Keywords:

Intelligent Prosthetic Limbs

Internet of Things (IoT)

Patient Movement Rehabilitation

Motor Function Enhancement

## Extended Abstract

Medical technology has made incredible strides in recent years, altering the way we approach patient care. Intelligent prosthetic limbs have emerged as a game-changer in terms of enhancing patients' motor function among these ground-breaking inventions. These innovative prostheses are pushing the limits of what people with limb loss or disability can do by seamlessly interacting with the Internet of Things (IoT). This review explores the crucial role technology plays in improving patients' motor abilities and provides a look into a future in which prosthetic limbs would automatically adapt to their users' demands and enable them to reclaim their independence.

\* Corresponding Author's Email  
Address:

[mohammadrezaeinollahiasgarabad@mailfa.com](mailto:mohammadrezaeinollahiasgarabad@mailfa.com)

## Introduction

By enabling people with limb loss or disability to reclaim their freedom and enhance their motor skills, intelligent prosthetic limbs coupled with the Internet of Things have transformed patient care [1]. This technology benefits patients' emotional and physical health in addition to their physical skills [2,3]. The success of these technologies is also influenced by ongoing developments in sensor technology, machine learning algorithms, and collaborative design projects [4-6]. Intelligent prosthetic limbs have a critical role in enhancing patients; mental well-being, according to experts in the area [7]. People notice an increase in self-confidence and a decrease in emotions of frustration or loneliness by recovering movement and carrying out everyday tasks more easily [8]. Their general quality of life can be much improved if they can continue to participate in the activities they formerly loved without restrictions [9]. Real-time data gathering and analysis are made possible by the Internet of Things connection with prosthetic limbs [10]. Remote care can be delivered by medical experts who can also modify treatment regimens and check on patients, progress [9-14]. Clinicians can enhance the performance and comfort of prosthetic devices, improving patient outcomes, by

monitoring numerous characteristics such as walking patterns, pressure distribution, and muscle activation [15]. Artificial limb functioning and control have been considerably improved by ongoing advancements in sensor technology and machine learning algorithms [16]. Algorithms may predict users; intents and modify the limb's reaction accordingly by evaluating data from embedded sensors [17]. This improves motor performance and shortens the learning curve for people getting used to new prosthetic limbs [18]. Intelligent artificial limb development uses an interdisciplinary approach to guarantee that the technology satisfies the unique requirements and preferences of patients. Patients, opinions and ideas are used to create prosthetic devices that are not only functional but also visually beautiful and pleasant to wear by incorporating them into the design process. The technology is customized to meet the needs of specific patients thanks to the cooperation of medical specialists, engineers, and designers, further boosting the patient experience [19,20]. In conclusion, the Internet of Things; integration with intelligent prosthetic limbs has revolutionized patient care by empowering those who have lost or have impaired use of a limb. With the help of these developments, patients can reclaim their independence, better their motor function, and improve their general quality of life.

## Smart artificial limbs and their importance in improving patients' movement performance

Throughout history, the challenge of limb loss has led to innovation in prosthetic technology, as evidenced by ancient attempts to address this issue, such as the use of primitive prostheses and adaptive strategies, demonstrating the continued importance of advances in prosthetic limbs show to increase mobility and mobility [22]. Research in the field of rehabilitation robots by combining the fields of rehabilitation medicine, biomechanics, mechanics, electronics, material science, computer science robotics, and other fields has become one of the hot spots in the world [22-24]. The development of artificial intelligent devices and advanced biomedical technologies, emphasizing the fundamental importance of machine intelligence in the integration and analysis of sensory data, will promote the improvement of mobility and motor performance of patients in the future

[25]. The use of smart artificial limbs in rehabilitation after amputation has improved, but according to the type of prosthesis and the ability of each person, it will have different requirements and results, which indicates the great importance of these limbs in improving motor performance. Patients have [26-30] Prosthetic limb technology has improved to increase the motor function of patients [31]. The use of monitoring technologies such as electronic step counters in rehabilitation programs for people with artificial limbs facilitates the improvement of assessment and promotion of motor performance of these patients [32-35]. Government-sponsored free procurement and distribution of advanced artificial limbs enables effective and economical rehabilitation of amputees, facilitating patients' motor recovery [26].

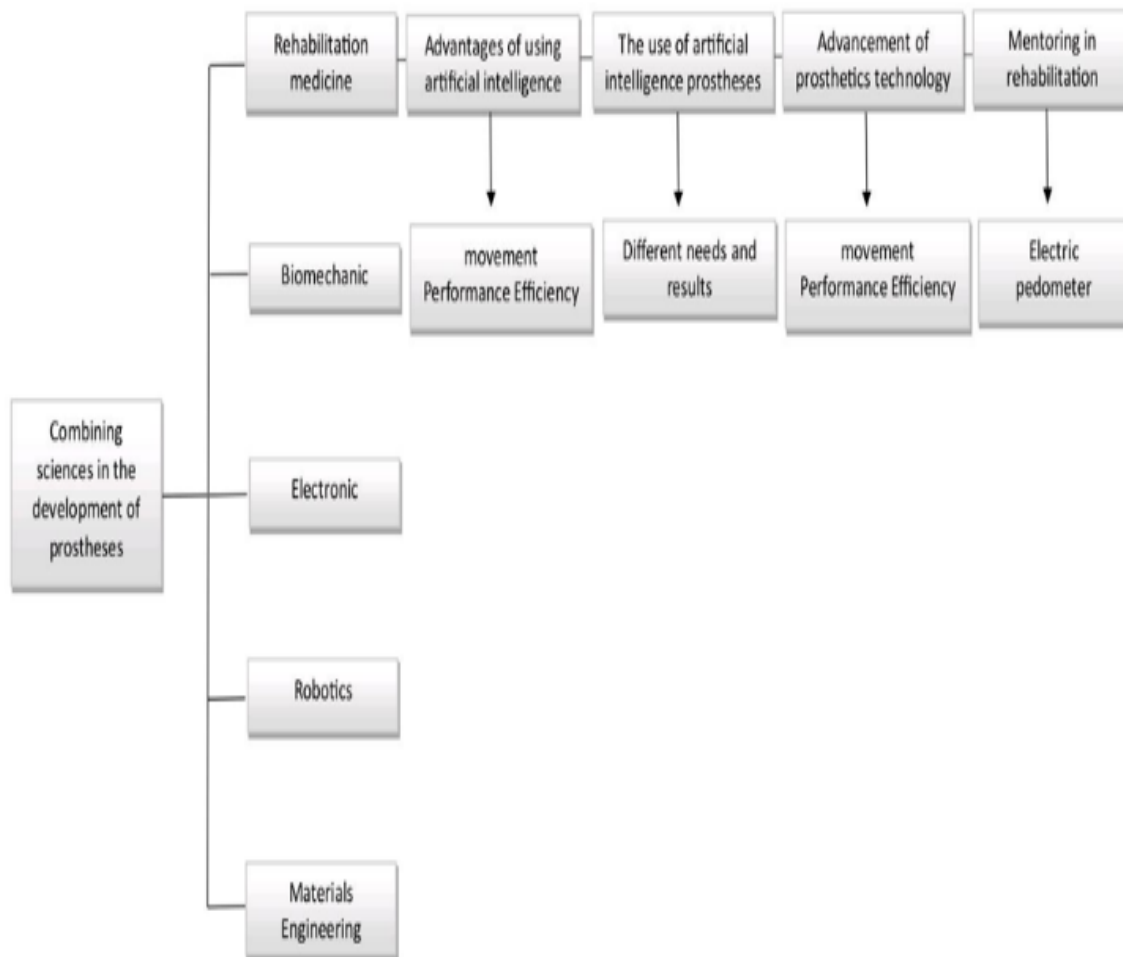


Fig. 1: Development of prostheses with medical rehabilitation

### **Intelligent artificial limb technology: Improving capabilities and applications in motor rehabilitation**

The combination of industrial and medical robots in the field of rehabilitation robots leads to the improvement of capabilities and intelligent applications in motor rehabilitation [22, 36, and 37]. The development of smart rehabilitation systems such as smart artificial organs in order to increase rehabilitation and improve the movement of body parts, from the upper to the lower and lower limbs of the human skeletal system [38, 39]. The evolution of smart prosthetic technology, including advances in design, fabrication, and collaborative interdisciplinary approaches, has significantly improved the functional and rehabilitative aspects of limb loss [40]. The development of intelligent and multifunctional artificial organs in different eras in order to improve motor rehabilitation and the development of facilities in the technology of intelligent artificial organs is visible [38-40]. Advances in smart prostheses support the evolving needs of users in locomotion rehabilitation by improving capabilities, increasing sensory feedback, and more intuitive control through collaborative research and machine learning techniques [35]. Intelligent artificial devices play a vital role in improving patients' movement performance; because they express the effectiveness of factors such as employment, continuous use of a prosthesis, age, and the use of auxiliary devices in regulating the member's urine and compatibility with the prosthesis. The importance of paying attention to these factors through support programs is also determined to improve their condition [41].

### **The role of the Internet of Things in the improvement and development of intelligent artificial limbs**

The global impact of limb loss has profound implications, affecting millions and giving rise to significant challenges in the daily lives of individuals with limb differences [42]. The Internet of Things (IoT) and robotics are also used in various fields such as elderly care, rehabilitation, and assisting people with disabilities, remote surgery, prosthetics, disinfection, and prescription. These technologies lead to a reduction in the burden of treatment and care, resulting in significant advances and improvements in medical services. [43-46]. However, the Internet of Things (IoT) has emerged as a pivotal factor in the enhancement and development of intelligent artificial limb technologies tailored to the needs of those grappling with these challenges. For instance, IoT has ushered in a paradigm shift in the realm of smart artificial limbs and their controllers. The capacity of prostheses and controllers to function autonomously marks a pivotal advancement. Their ability to seamlessly connect with cloud servers via Wi-Fi connectivity represents a pivotal breakthrough. This newfound capability extends the horizons of potential applications, encompassing functions such as data uploading, update reception, and streamlined integrated remote control [47]. Furthermore, the transformation of the methodology employed in the

control and manipulation of robotic arms serves as another notable example of IoT's impact. IoT technologies have introduced a constellation of innovative features, including wireless control mechanisms, real-time data transmission capabilities, platform-agnostic functionalities, and remote access capabilities. These advancements collectively contribute to elevating the efficacy, precision, and adaptability of robotic arm operations [48, 49]. Internet of Things (IoT) technology has also been able to play a pivotal role during the Covid-19 pandemic, especially in helping people with physical disabilities. It achieved this by introducing a set of technological solutions designed to effectively deal with the challenges that arise. In essence, its impact during that period included facilitating data-driven decision-making, increasing remote monitoring and evaluation capacities, facilitating call-tracing procedures, optimizing communication channels, and providing valuable insights that peaked significantly. The simple answer to this increase in productivity has shown itself prominently in the participation of the Internet of Things at this critical juncture [50, 51].

### **Sensors and wireless communication: improving the efficiency and accuracy of the interaction of artificial limbs with patients through artificial intelligence and machine learning**

The synergy between sensors and wireless communication has the potential to revolutionize the realm of prosthetics, elevating the interaction between artificial limbs and patients to new heights of efficiency and accuracy. This convergence of cutting-edge technologies not only addresses the functional deficits associated with limb loss but also envisions a future where prosthetic devices are imbued with multi-functionality, self-identification, durability, and intuitive control [52]. Indeed, the conceptualization of sensor integration in prostheses stems from neurotechnological paradigms. This approach strives to elucidate a diverse array of strategies capable of conveying intricate neural signals. These signals are derived from the intricate information gleaned by cutaneous receptors, muscular dynamics, and joint kinematics, with the ultimate objective of emulating human movement. Through the meticulous decoding and replication of these neural cues, the primary aim is to engender a sensory encounter that closely approximates the innate physiological state [53, 54]. In fact, the spectrum of sensors, encompassing pressure transducers and electromyography (EMG) sensors, plays a pivotal role in capturing essential information concerning muscular dynamics, articulatory angles, and the distribution of pressure. These sensors function as a pivotal conduit connecting the prosthetic apparatus with the volitional motives of the user, thereby facilitating a more seamless and organic range of movements [55]. Furthermore, the incorporation of wireless communication mechanisms fosters instantaneous data interchange between the prosthetic apparatus and external peripherals, exemplified by smartphones or computers. This capability not only enables incessant monitoring but also permits

dynamic adjustments to be made in real-time [56]. Furthermore, artificial intelligence plays a pivotal role in augmenting this process, showcasing one of its most compelling manifestations: predictive modeling. Through the adept deployment of machine learning algorithms, the prognostication of user actions becomes plausible, affording the prospect to preemptively tailor the responses of the artificial apparatus. This culmination engenders an encounter distinguished by its discreetness and inherent authenticity. To illustrate, consider the manipulation of objects: the perceptive acumen of artificial intelligence algorithms facilitates the extrapolation of requisite force by diligently incorporating variables such as the object's mass and surface attributes. This augmentation significantly amplifies precision in handling, giving rise to an illusion of command and an ambiance of vivacity [57, 58].

### **Information security and protection in the use of intelligent artificial limbs with the Internet of Things**

When using intelligent artificial limbs coupled with the Internet of Things (IoT), information security and protection are key factors to take into account [59]. Strong security measures must be put in place since these devices gather and send sensitive data in order to protect patient information and guarantee the accuracy and privacy of their personal information [60]. The security of data while it is being transmitted is one of the main issues with IoT-enabled prosthetic limbs [61,62]. To avoid illegal access to or interception of important information, communications between the prosthetic device and external systems should be encrypted [63]. To create a secure connection and encrypt the data being communicated, secure protocols like Transport Layer Security (TLS) or Secure Sockets Layer (SSL) can be used [64]. The safeguarding of patient information kept in the prosthetic device or related systems is another facet of information security [65]. In order to guarantee that only authorized users may access and alter the device's settings or patient data, adequate authentication procedures should be put in place [66]. These devices may be made more secure by using two-factor authentication, biometric authentication, or strong passwords [67]. In addition, precautions need to be taken against potential cybersecurity concerns like malware or hacking attempts. To fix any vulnerabilities and make sure the devices are using the most recent secure firmware, regular software upgrades and patches should be implemented [68]. The use of intrusion detection and prevention systems can also assist in spotting and minimizing any possible security breaches [69]. Another

crucial component of information security in the deployment of intelligent artificial limbs is data privacy [70]. Patients should be able to manage their personal data and be aware of how it is gathered, kept, and utilized [71]. There should be clear privacy rules in place that describe the reason for data collection, the organizations that have access to the data, and the steps taken to get patient consent [72]. Healthcare providers and manufacturers should follow industry standards and best practices for information security to guarantee compliance with data protection legislation [73]. Regular audits and assessments can assist in finding any security protocol flaws or vulnerabilities and enable preventative action to close them [74].

### **Successful case studies in improving movement performance using intelligent artificial limbs and the Internet of Things: Challenges and solutions in movement rehabilitation**

The rapid increase in using artificial intelligence to control prostheses has significantly improved the functionality of these devices for amputees, allowing them to operate the prosthetics more effectively; adaptive control involves adjusting input based on feedback to achieve closer alignment with the desired output, and a recent example of this is the introduction of a mind-controlled limb using myoelectric control, representing a cutting-edge advancement in AI-assisted control systems [58]. The main focus of prosthetic control research in the past ten years has been on analyzing and identifying patterns in myoelectric signals. While many studies report how accurately they can predict specific movements, differences in study variables make it challenging to directly compare results between studies. To address this, the authors introduce BioPatRec, an open-source software designed to establish a shared research platform for developing and assess algorithms in prosthetic control [75-77]. Electromyography is a method to assess and record the electrical activity of skeletal muscles, detecting signals from the brain's muscle cell movement [78]. Utilizing Electromyography for the analysis of muscle electrical activity and Myo-electric controlled prosthetic limbs that react to muscle signals, the goal is to leverage Machine Learning and Deep Learning to forecast hand gestures for an affordable and precise prosthetic hand [57]. Another method use of artificial intelligence (AI) in processing and controlling mobile robotic exoskeletons has led to significant enhancements in upper-limb motor rehabilitation [52].

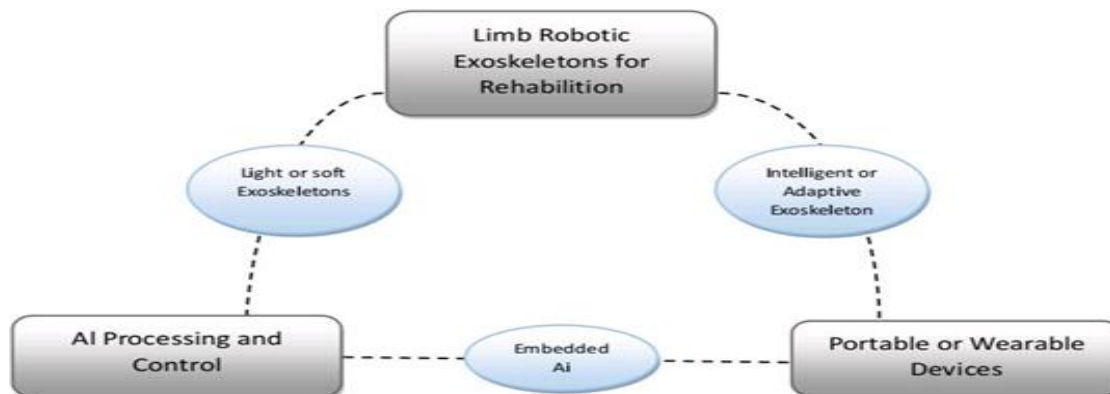


Fig. 2: The main axes of the systematic review of intelligent artificial organs

### The future of intelligent artificial limbs: Perspective and leading developments in patient movement rehabilitation

Major progress has been made in prosthetic limb capabilities, especially lower limbs, due to engineering advances over the past 20 years. However, areas like socket comfort and interfacing require more work. Exciting innovations in fields like materials, mechatronics, and neurotechnology promise continued enhancements in artificial limb function and user experience. The future is challenging but should bring better prosthetics and improved quality of life for amputees. The ability to sense various torques enables features like CVT, slip-based auto-grasping, advanced control strategies (impedance control, minimum jerk trajectories), optimal power efficiency, and adaptive knee stance control. Sensor-driven control transforms robotics into mechatronics, expected to drive prosthetics advancements. Shrinking microcontrollers facilitate precise control schemes. Integrated microprocessors enable component communication and

feedback, potentially adapting socket shape based on the gait phase. Mechatronic tech isolates power transmission from signal acquisition, leading to lighter yet more powerful prostheses. Amid increasing complexity and fragility, mechatronics and novel power sources (e.g., fuel cells) are poised to fuel innovation in prosthetics [79]. In recent years, significant research has aimed to extract valuable insights from biological signals to effectively control Upper Limb Prostheses (ULPs) [80]. Patients with spinal cord injuries (SCI) and amputees face significant challenges in daily life due to limb impairments. Functional electrical stimulation (FES) using implantable microstimulators shows promise for restoring muscle function in SCI patients, while powered arm-hand prostheses offer potential for amputees. Despite ongoing research, effective coordination algorithms and practical solutions are lacking. To expedite development, a virtual reality environment (VRE) has been designed for simulated arm interaction and training, allowing gradual complexity adjustments and error correction to enhance patient outcomes [81-83].

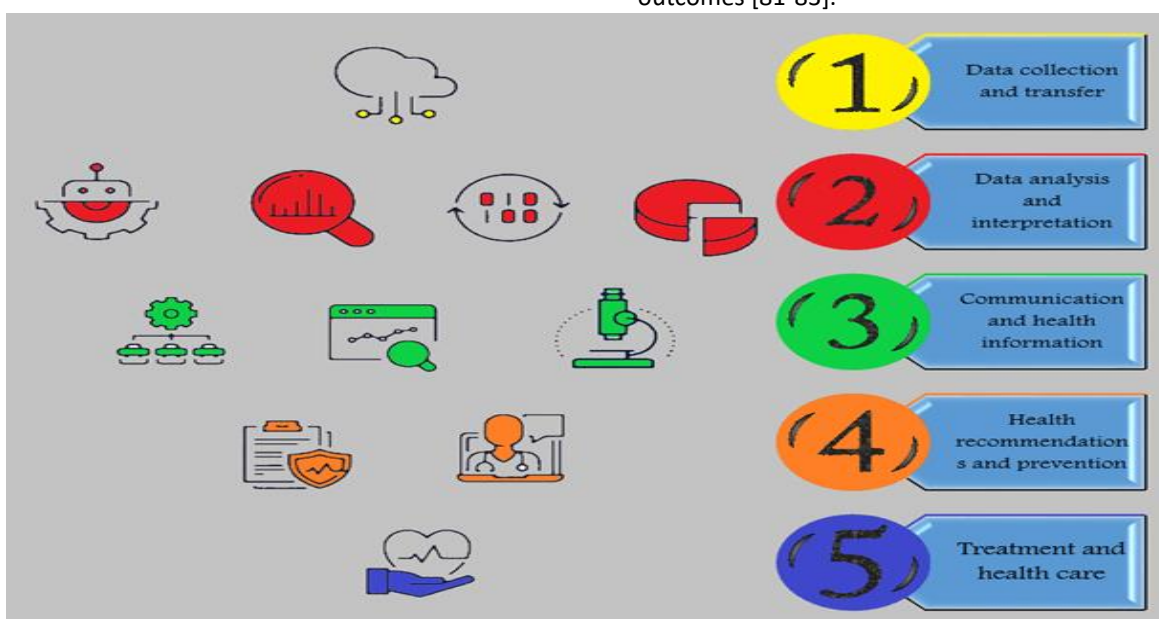


Fig. 3: Treatment and health care process

### Conclusion

The integration of intelligent prosthetic limbs with the Internet of Things (IoT) and rehabilitation robots, along with advancements in artificial intelligence and monitoring technologies, has led to remarkable progress in the field of prosthetics. These innovations have revolutionized patient

care, empowering individuals with limb loss or disability to regain independence, enhance motor function, and improve overall quality of life. The IoT has played a pivotal role in enabling real-time data gathering, remote care, and improved control experiences. However, challenges like information security and socket comfort still require attention. Nevertheless, the future of prosthetic

technology appears promising, with continued advancements aimed at enhancing natural movement, sensory feedback, and precision in limb control for users with limb loss.

## Reference

- [1] Haras M, Skotnicki T. Thermoelectricity for IoT—A review. *Nano Energy*. 2018 Dec 1;54:461-76.
- [2] Madakam S, Lake V, Lake V, Lake V. Internet of Things (IoT): A literature review. *Journal of Computer and Communications*. 2015;3(05):164.
- [3] Farooq MU, Waseem M, Mazhar S, Khairi A, Kamal T. A review on internet of things (IoT). *International journal of computer applications*. 2015 Mar 18;113(1):1-7.
- [4] Gokhale P, Bhat O, Bhat S. Introduction to IOT. *International Advanced Research Journal in Science, Engineering and Technology*. 2018 Jan;5(1):41-4.
- [5] Van Kranenburg R, Bassi A. IoT challenges. *Communications in Mobile Computing*. 2012 Nov 28;1(1):9.
- [6] Zhao JC, Zhang JF, Feng Y, Guo JX. The study and application of the IOT technology in agriculture. In 2010 3rd international conference on computer science and information technology 2010 Jul 9 (Vol. 2, pp. 462-465). IEEE.
- [7] Qian ZH, Wang YJ. IoT technology and application. *Acta Electronica Sinica*. 2012 May 25;40(5):1023.
- [8] Liu T, Lu D. The application and development of IoT. In 2012 International symposium on information technologies in medicine and education 2012 Aug 3 (Vol. 2, pp. 991-994). IEEE.
- [9] Krčo S, Pokrić B, Carrez F. Designing IoT architecture (s): A European perspective. In 2014 IEEE world forum on internet of things (WF-IoT) 2014 Mar 6 (pp. 79-84). IEEE.
- [10] Laghari AA, Wu K, Laghari RA, Ali M, Khan AA. A review and state of art of Internet of Things (IoT). *Archives of Computational Methods in Engineering*. 2021 Jul:1-9.
- [11] Sharma N, Shamkuwar M, Singh I. The history, present and future with IoT. *Internet of things and big data analytics for smart generation*. 2019:27-51.
- [12] Hassan WH. Current research on Internet of Things (IoT) security: A survey. *Computer networks*. 2019 Jan 15;148:283-94.
- [13] Yadav EP, Mittal EA, Yadav H. IoT: Challenges and issues in indian perspective. In 2018 3rd International Conference On Internet of Things: Smart Innovation and Usages (IoT- SIU) 2018 Feb 23 (pp. 1-5). IEEE.
- [14] Xu J, Gu B, Tian G. Review of agricultural IoT technology. *Artificial Intelligence in Agriculture*. 2022 Jan 1;6:10-22.
- [15] Soumyalatha SG. Study of IoT: understanding IoT architecture, applications, issues and challenges. In 1st International Conference on Innovations in Computing & Net-workin (ICIN16), CSE, RRCE. *International Journal of Advanced Networking & Applications* 2016 May 12 (Vol. 478).
- [16] Kim TH, Ramos C, Mohammed S. Smart city and IoT. *Future Generation Computer Systems*. 2017 Nov 1;76:159-62.
- [17] Tekeste Habte T, Saleh H, Mohammad B, Ismail M, Tekeste Habte T, Saleh H, Mohammad B, Ismail M. IoT for healthcare. *Ultra Low Power ECG Processing System for IoT Devices*. 2019:7-12.
- [18] Koohang A, Sargent CS, Nord JH, Paliszkiwicz J. Internet of Things (IoT): From awareness to continued use. *International Journal of Information Management*. 2022 Feb 1;62:102442.
- [19] Ploennigs J, Cohn J, Stanford-Clark A. The future of IoT. *IEEE Internet of Things Magazine*. 2018 Sep;1(1):28-33.
- [20] Al-Sarawi S, Anbar M, Alieyan K, Alzubaidi M. Internet of Things (IoT) communication protocols. In 2017 8th International conference on information technology (ICIT) 2017 May 17 (pp. 685-690). IEEE.
- [21] WILSON JR, A. BENNETT. "In order to meet the many requests for reprints of" *Limb Prosthetics—1967*" (Artificial Limbs, Spring 1967), the supply of which has been exhausted, the article is offered again, with revisions to reflect the recent advances in prosthetics technology."
- [22] Li, Bei, et al. "A review of rehabilitation robot." 2017 32nd Youth Academic Annual Conference of Chinese Association of Automation (YAC). IEEE, 2017.
- [23] Bermúdez i Badia, Sergi, and Mónica S. Cameirão. "The neurorehabilitation training toolkit (NTT): a novel worldwide accessible motor training approach for at-home rehabilitation after stroke." *Stroke Research and Treatment* 2012 (2012).
- [24] Michnik, Andrzej, et al. "Rehabilitation robot prototypes developed by the ITAM Zabrze." *Archive of Mechanical Engineering* (2014): 433-444.
- [25] PILARSKI, PATRICK M. "INTELLIGENT ARTIFICIAL LIMBS."
- [26] Lakkireddy, Maheshwar, et al. "State-sponsored institute-based provision of advanced artificial limbs for rehabilitation of amputees." *Journal of Orthopaedics, Trauma and Rehabilitation* 29.2 (2022): 22104917221123340.
- [27] Esquenazi, Alberto. "Amputation rehabilitation and prosthetic restoration. From surgery to community reintegration." *Disability and rehabilitation* 26.14-15 (2004): 831-836.
- [28] Resnik, Linda, et al. "Advanced upper limb prosthetic devices: implications for upper limb prosthetic rehabilitation." *Archives of physical medicine and rehabilitation* 93.4 (2012): 710-717.
- [29] Lange, Reinhild, and Unn Ljøstad. "Benamputasjon og rehabilitering." *Tidsskrift for Den norske legeforening* (2017).
- [30] Matrone, Giulia C., et al. "Principal components analysis based control of a multi-dof underactuated prosthetic hand." *Journal of neuroengineering and rehabilitation* 7.1 (2010): 1-13.
- [31] Perry, Heather R. "Re-arming the disabled: WWI and the revolution in artificial limbs." *Recycling the disabled*. Manchester University Press, 2015. 45-83.
- [32] Holden, Jean M., and Geoffrey R. Fernie. "Extent of artificial limb use following rehabilitation." *Journal of orthopaedic research* 5.4 (1987): 562-568.
- [33] Finch, D. R. A., et al. "Amputation for vascular disease: the experience of a peripheral vascular unit." *Journal of British Surgery* 67.4 (1980): 233-237.
- [34] Holden, J., and G. Fernie. "Minimal walking levels for amputees living at home." *Physiother Can* 35.6 (1983): 317-20.
- [35] Milner, M. "An Overview of the Current Status of Existing Gait Laboratories." *NIH Gait Research Workshop*. DHEW Publication, 1977.
- [36] Dazhai, XIAO Jingjing YANG Yang LI, and HUANG Long ZHANG Leiyu. "Advances and key techniques of ophthalmic microsurgical robots." *Journal of Mechanical Engineering* 49.1 (2013): 1.
- [37] Sun, H. T., Q. G. Li, and X. Q. Liu. "The active and passive movement of limb rehabilitation robot." *Manufacturing Automation* 34.4 (2012): 69-72.
- [38] Sun, Cuilian, et al. "A simulation method for walking gait of human daily activity oriented on intelligent artificial limbs and exoskeleton." 2015 IEEE International Conference on Cyber Technology in Automation, Control, and Intelligent Systems (CYBER). IEEE, 2015.
- [39] Perry, Jacquelin, and E. E. Bleck. "Gait analysis: normal and pathological function." *Developmental Medicine and Child Neurology* 35 (1993): 1122-1122.
- [40] Kirkup, John. "Artificial Limbs and Rehabilitation." *A History of Limb Amputation* (2007): 155-172. *Academic Annual Conference of Chinese Association of Automation (YAC)*. IEEE, 2017.
- [41] Sinha, Richa, Wim JA van den Heuvel, and Perianayagam Arokiasamy. "Adjustments to amputation and an artificial limb in lower limb amputees." *Prosthetics and orthotics international* 38.2 (2014): 115-121.
- [42] Asgarabad, Mohammad Reza Einollahi, et al. "Biomedical engineering and its aspects through IOT."
- [43] Pradhan, Bikash, et al. "Internet of things and robotics in transforming current-day healthcare services." *Journal of healthcare engineering* 2021 (2021): 1-15.
- [44] Akkaş, M. Alper, Radosveta Sokullu, and H. Ertürk Çetin. "Healthcare and patient monitoring using IoT." *Internet of Things* 11 (2020): 100173.

- [45] Joseph, Azeta, et al. "A review on humanoid robotics in healthcare." *MATEC Web of Conferences*. Vol. 153. EDP Sciences, 2018.
- [46] Engdahl SM, Christie BP, Kelly B, Davis A, Chestek CA, Gates DH. 2015 Surveying the interest of individuals with upper limb loss in novel prosthetic control techniques. *J. Neuroeng. Rehabil.* 12, 1–11. (doi:10.1186/s12984-015-0044-2)
- [47] Wu, H., Dyson, M. and Nazarpour, K., 2022. Internet of Things for beyond-the-laboratory prosthetics research. *Philosophical Transactions of the Royal Society A*, 380(2228), p.20210005.
- [48] Fu, S. and Bhavsar, P.C., 2019, May. Robotic arm control based on internet of things. In *2019 IEEE Long Island Systems, Applications and Technology Conference (LISAT)* (pp. 1-6). IEEE.
- [49] M. B. P. Srivastava, "Ankur Singh Rana "IOT based controlling of hybrid energy system using ESP8266"", 2018.
- [50] V. Jahmunah, V. K. Sudharshan, S. Lih Oh et al., "Future IoT tools for COVID-19 contact tracing and prediction: a review of the state-of-the-science," *International Journal of Imaging Systems and Technology*, 2021.
- [51] Pradhan, B., Bharti, D., Chakravarty, S., Ray, S.S., Voinova, V.V., Bonartsev, A.P. and Pal, K., 2021. Internet of things and robotics in transforming current-day healthcare services. *Journal of healthcare engineering*, 2021, pp.1-15.
- [52] Vélez-Guerrero, M.A., Callejas-Cuervo, M. and Mazzoleni, S., 2021. Artificial intelligence-based wearable robotic exoskeletons for upper limb rehabilitation: A review. *Sensors*, 21(6), p.2146.
- [53] Raspopovic, S., Valle, G. and Petrini, F.M., 2021. Sensory feedback for limb prostheses in amputees. *Nature Materials*, 20(7), pp.925-939.
- [54] Hao, M., Chou, C.H., Zhang, J., Yang, F., Cao, C., Yin, P., Liang, W., Niu, C.M. and Lan, N., 2020. Restoring finger-specific sensory feedback for transradial amputees via non-invasive evoked tactile sensation. *IEEE Open Journal of Engineering in Medicine and Biology*, 1, pp.98-107.
- [55] Kwak, J.W., Han, M., Xie, Z., Chung, H.U., Lee, J.Y., Avila, R., Yohay, J., Chen, X., Liang, C., Patel, M. and Jung, I., 2020. Wireless sensors for continuous, multimodal measurements at the skin interface with lower limb prostheses. *Science translational medicine*, 12(574), p.eabc4327.
- [56] Miao, S., Shen, C., Feng, X., Zhu, Q., Shorfuzzaman, M. and Lv, Z., 2021. Upper limb rehabilitation system for stroke survivors based on multi-modal sensors and machine learning. *IEEE Access*, 9, pp.30283-30291.
- [57] Sree, K.S., Bikku, T., Mounika, S., Ravinder, N., Kumar, M.L. and Prasad, C., 2021, November. EMG controlled bionic robotic arm using artificial intelligence and machine learning. In *2021 Fifth International Conference on I-SMAC (IoT in Social, Mobile, Analytics and Cloud)(I-SMAC)* (pp. 548-554). IEEE.
- [58] Nayak, S. and Das, R.K., 2020. Application of artificial intelligence (AI) in prosthetic and orthotic rehabilitation. In *Service Robotics*. IntechOpen.
- [59] Kotha HD, Gupta VM. IoT application: a survey. *Int. J. Eng. Technol.* 2018 Mar 18;7(2.7):891-6.
- [60] Al-Qaseemi SA, Almulhim HA, Almulhim MF, Chaudhry SR. IoT architecture challenges and issues: Lack of standardization. In *2016 Future technologies conference (FTC)* 2016 Dec 6 (pp. 731-738). IEEE.
- [61] Tawalbeh LA, Muheidat F, Tawalbeh M, Quwaider M. IoT Privacy and security: Challenges and solutions. *Applied Sciences*. 2020 Jun 15;10(12):4102.
- [62] Balaji S, Nathani K, Santhakumar R. IoT technology, applications and challenges: a contemporary survey. *Wireless personal communications*. 2019 Sep 15;108:363-88.
- [63] Gurunath R, Agarwal M, Nandi A, Samanta D. An overview: security issue in IoT network. In *2018 2nd international conference on I-SMAC (IoT in social, Mobile, analytics and cloud)(I-SMAC)* I-SMAC (IoT in social, Mobile, analytics and cloud)(I-SMAC), 2018 2nd international conference on 2018 Aug 30 (pp. 104-107). IEEE.
- [64] Shah SH, Yaqoob I. A survey: Internet of Things (IOT) technologies, applications and challenges. 2016 *IEEE Smart Energy Grid Engineering (SEGE)*. 2016 Aug 21:381-5.
- [65] Mouha RA. Internet of things (IoT). *Journal of Data Analysis and Information Processing*. 2021 Mar 18;9(2):77-101.
- [66] Chaudhary S, Johari R, Bhatia R, Gupta K, Bhatnagar A. CRAIoT: concept, review and application (s) of IoT. In *2019 4th international conference on internet of things: Smart innovation and usages (IoT-SIU)* 2019 Apr 18 (pp. 1-4). IEEE.
- [67] Dudhe PV, Kadam NV, Hushangabade RM, Deshmukh MS. Internet of Things (IOT): An overview and its applications. In *2017 International conference on energy, communication, data analytics and soft computing (ICECDS)* 2017 Aug 1 (pp. 2650- 2653). IEEE.
- [68] Lee SK, Bae M, Kim H. Future of IoT networks: A survey. *Applied Sciences*. 2017 Oct 16;7(10):1072.
- [69] Zhong CL, Zhu Z, Huang RG. Study on the IOT architecture and gateway technology. In *2015 14th International Symposium on Distributed Computing and Applications for Business Engineering and Science (DCABES)* 2015 Aug 18 (pp. 196-199). IEEE.
- [70] Shenoy J, Pingle Y. IOT in agriculture. In *2016 3rd International Conference on Computing for Sustainable Global*
- [71] *Development (INDIACom)* 2016 Mar 16 (pp. 1456- 1458). IEEE.
- [72] Asghar MH, Negi A, Mohammadzadeh N. Principle application and vision in Internet of Things (IoT). In *International Conference on Computing, Communication & Automation* 2015 May 15 (pp. 427-431). IEEE.
- [73] Abdul-Qawy AS, Pramod PJ, Magesh E, Srinivasulu T. The internet of things (iot): An overview. *International Journal of Engineering Research and Applications*. 2015 Dec;5(12):71-82.
- [74] Khan MA. Challenges facing the application of IoT in medicine and healthcare. *International Journal of Computations, Information and Manufacturing (IJCIM)*. 2021 Dec 19;1(1).
- [75] Kashani MH, Madanipour M, Nikravan M, Asghari P, Mahdipour E. A systematic review of IoT in healthcare: Applications, techniques, and trends. *Journal of Network and Computer Applications*. 2021 Oct 15;192:103164.
- [76] Ortiz-Catalan, Max, Rickard Brånemark, and Bo Håkansson.
- [77] "BioPatRec: A modular research platform for the control of artificial limbs based on pattern recognition algorithms." *Source code for biology and medicine* 8.1 (2013): 1-18.
- [78] Scheme, Erik, and Kevin Englehart. "Electromyogram pattern recognition for control of powered upper-limb prostheses: state of the art and challenges for clinical use." *Journal of Rehabilitation Research & Development* 48.6 (2011).
- [79] Peerdeman, Bart, et al. "Myoelectric forearm prostheses: state of the art from a user-centered perspective." *Journal of Rehabilitation Research & Development* 48.6 (2011).
- [80] Raza, Sayyed Jaffar AIL. "Development of a Local Prosthetic Limb Using Artificial Intelligence."
- [81] Sensinger, Jonathon, PAUL F. Pasquina, and Todd Kuiken. "The future of artificial limbs." *Care of the combat amputee*. Frederick: US Army Medical Department Borden Institute (2009): 721-30.
- [82] Marinelli, Andrea, et al. "Active upper limb prostheses: A review on current state and upcoming breakthroughs." *Progress in Biomedical Engineering* (2022).
- [83] Hauschild, Markus, Rahman Davoodi, and Gerald E. Loeb. "A virtual reality environment for designing and fitting neural prosthetic limbs." *IEEE Transactions on Neural Systems and Rehabilitation Engineering* 15.1 (2007): 9-15.
- [84] G. E. Loeb and F. J. R. Richmond, "Implants for therapeutic and functional electrical stimulation," in *Neural Prosthesis for Restoration of Sensory and Motor Function*. Boca Raton, FL: CRC, 2000, pp.75–99.
- [85] D. J. Atkins, D. C. Y. Heard, and W. H. Donovan, "Epidemiologic overview of individuals with upper-limb loss and their reported research priorities," *J. Prosthetics Orthotics*, vol. 8, pp. 2–11, 1996.