

Available online at http://ijim.srbiau.ac.ir/ Int. J. Industrial Mathematics (ISSN 2008-5621) Vol. 6, No. 2, 2014 Article ID IJIM-00499, 8 pages Research Article



Application of iterative method for solving fuzzy Bernoulli equation under generalized H-differentiability

Sh. Sadigh Behzadi * [†]

Abstract

In this paper, the Picard method is proposed to solve the Bernoulli equation with fuzzy initial condition under generalized H-differentiability. The existence and uniqueness of the solution and convergence of the proposed method are proved in details. Finally an example shows the accuracy of this method.

Keywords: Bernoulli equation; Fuzzy-valued function; h-difference; Generalized differentiability; Picard method.

1 Introduction

s we know the fuzzy differential equations A_{FDE} are one of the important part of the fuzzy analysis theory that play major role in numerical analysis. For example, population models [5], the golden mean [52], quantum optics and gravity [54], control chaotic systems [50, 61], medicine [11, 26]. Recently, some mathematicians have studied FDE [1, 2, 3, 4, 15, 19, 20, 21, 22, 23, 29, 34, 35, 36, 37, 44, 45, 47, 48,58, 59, 60, 64, 65, 66, 57, 42, 24, 43, 31, 46, 16, 56, 25, 67, 41, 51, 63, 9]. The fuzzy partial differential equations FPDE are very important in mathematical models of physical, chemical, biological, economics and other fields. Some mathematicians have studied solution of FPDE by numerical methods [62, 8, 27, 39, 53, 68, 12, 13, 28]. The Bernoulli differential equation is named after the Switzerland nobleman Count Jakob Bernoulli (1655-1705). The book of Hoffman [18] contains the fundamental theories of Bernoulli equation,

with applications to random processes, optimal control, and diffusion problems. Besides important engineering science applications that today are considered classical, such as stochastic realization theory, optimal control, robust stabilization, and network synthesis, the newer applications include such areas as financial mathematics [14, 55, 40, 6]. In this work, we present the Picard method to solve the Bernoulli equation with fuzzy condition as follows:

$$\widetilde{u}'(t) = \widetilde{Q}(t)\widetilde{u}(t) + \widetilde{R}(t)\widetilde{u}^n(t), \quad 0 \le t \le T, T \in \mathbb{R},$$
(1.1)

with fuzzy initial condition:

$$\widetilde{u}(0) = \widetilde{a}_0, \tag{1.2}$$

where $\widetilde{Q}(t)$, $\widetilde{R}(t)$ and $\widetilde{P}(t)$ are fuzzy functions and \widetilde{a}_0 is fuzzy constant value.

The structure of this paper is organized as follows: In Section 2, some basic notations and definitions in fuzzy calculus are brought. In Section 3, Eq.(1.1) and Eq.(1.2) are solved by Picard method. The existence and uniqueness of the solution and convergence of the proposed method are proved in Section 4 respectively. Finally, in Section 5, the accuracy of method by solving a nu-

^{*}Corresponding author. shadan_behzadi@yahoo.com

[†]Department of Mathematics, Qazvin Branch, Islamic Azad University, Qazvin, Iran.

merical examples are illustrated and a brief conclusion is given in Section 6.

2 Basic concepts

Here basic definitions of a fuzzy number are given as follows, [32, 33, 49, 10, 17]

Definition 2.1 An arbitrary fuzzy number \tilde{u} in the parametric form is represented by an ordered pair of functions $(\underline{u}, \overline{u})$ which satisfy the following requirements:

(i) $\overline{u} : r \to \underline{u}(r) \in \mathbb{R}$ is a bounded leftcontinuous non-decreasing function over [0, 1], (ii) $\underline{u} : r \to \overline{u}(r) \in \mathbb{R}$ is a bounded left-continuous non-increasing function over [0, 1], (iii) $\underline{u}(r) \leq \overline{u}(r)$, $0 \leq r \leq 1$.

Definition 2.2 For arbitrary fuzzy numbers $\tilde{u}, \tilde{v} \in E$, we use the distance (Hausdorff metric) [30]

 $D(u(r), v(r)) = \max\{\sup_{r \in [0,1]} | \underline{u}(r) - \overline{v}(r) | \},\$

and it is shown [7] that (E, D) is a complete metric space and the following properties are well known:

$$\begin{split} D(\widetilde{u}+\widetilde{w},\widetilde{v}+\widetilde{w}) &= D(\widetilde{u},\widetilde{v}), \forall \ \widetilde{u},\widetilde{v}\in E, \\ D(k\widetilde{u},k\widetilde{v}) &= \mid k \mid D(\widetilde{u},\widetilde{v}), \\ \forall \ k\in\mathbb{R}, \widetilde{u},\widetilde{v}\in E, \\ D(\widetilde{u}+\widetilde{v},\widetilde{w}+\widetilde{e}) &\leq D(\widetilde{u},\widetilde{w}) + D(\widetilde{v},\widetilde{e}), \\ \forall \ \widetilde{u},\widetilde{v},\widetilde{w},\widetilde{e}\in E. \end{split}$$

Definition 2.3 Consider $x, y \in E$. If there exists $z \in E$ such that x = y + z then z is called the H- difference of x and y, and is denoted by $x \ominus y$. [19]

Proposition 2.1 If $f: (a,b) \to E$ is a continuous fuzzy-valued function then $g(x) = \int_a^x f(t) dt$ is differentiable, with derivative g'(x) = f(x) [19].

Definition 2.4 (see [19]) Let $f : (a, b) \to E$ and $x_0 \in (a, b)$. We say that f is generalized differentiable at x_0 (Bede-Gal differentiability), if there exists an element $f'(x_0) \in E$, such that:

i) for all h > 0 sufficiently small, $\exists f(x_0 + h) \ominus f(x_0), \exists f(x_0) \ominus f(x_0 - h)$ and the following limits hold:

$$\lim_{h \to 0} \frac{f(x_0 + h) \ominus f(x_0)}{h} = \lim_{h \to 0} \frac{f(x_0) \ominus f(x_0 - h)}{h}$$

or

ii) for all h > 0 sufficiently small, $\exists f(x_0) \ominus f(x_0 + h), \exists f(x_0 - h) \ominus f(x_0)$ and the following limits hold:

 $= f'(x_0)$

$$\lim_{h \to 0} \frac{f(x_0) \ominus f(x_0 + h)}{-h} = \lim_{h \to 0} \frac{f(x_0 - h) \ominus f(x_0)}{-h}$$
$$= f'(x_0)$$

or

iii) for all h > 0 sufficiently small, $\exists f(x_0 + h) \ominus f(x_0), \exists f(x_0 - h) \ominus f(x_0)$ and the following limits hold:

$$\lim_{h \to 0} \frac{f(x_0 + h) \ominus f(x_0)}{h} = \lim_{h \to 0} \frac{f(x_0 - h) \ominus f(x_0)}{-h}$$
$$= f'(x_0)$$

or

iv) for all h > 0 sufficiently small, $\exists f(x_0) \ominus f(x_0 + h), \exists f(x_0) \ominus f(x_0 - h)$ and the following limits hold:

$$\lim_{h \to 0} \frac{f(x_0) \ominus f(x_0 + h)}{-h} = \lim_{h \to 0} \frac{f(x_0) \ominus f(x_0 - h)}{h}$$
$$= f'(x_0)$$

Definition 2.5 Let $f : (a, b) \to E$. We say f is (i)-differentiable on (a, b) if f is differentiable in the sense (i) of Definition (2.4) and similarly for (ii), (iii) and (iv) differentiability.

Definition 2.6 A triangular fuzzy number is defined as a fuzzy set in E, that is specified by an ordered triple $u = (a, b, c) \in \mathbb{R}^3$ with $a \leq b \leq c$ such that $u(r) = [\underline{u}(r), \overline{u}(r)]$ are the endpoints of rlevel sets for all $r \in [0, 1]$, where $\underline{u}(r) = a + (b-a)r$ and $\overline{u}(r) = c - (c - b)r$. Here, $\underline{u}(0) = a, \overline{u}(0) =$ $c, \underline{u}(1) = \overline{u}(1) = b$, which is denoted by u(1). The set of triangular fuzzy numbers will be denoted by E.

Definition 2.7 (see [29]) The mapping $f: T \rightarrow E$ for some interval T is called a fuzzy process. Therefore, its r-level set can be written as follows:

$$\begin{split} f(t)(r) &= [\underline{f}(t,r), \overline{f}(t,r)],\\ t \in T, \quad \overline{r} \in [0,1]. \end{split}$$

Definition 2.8 (see [29]) Let $f : T \to E$ be Hukuhara differentiable and denote $f(t)(r) = [\underline{f}(t,r), \overline{f}(t,r)]$. Then, the boundary function $\underline{f}(t,r)$ and $\overline{f}(t,r)$ are differentiable (or Seikkala differentiable) and

$$(f'(t))(r) = [\underline{f}'(t,r), \overline{f}'(t,r)], \quad t \in T,$$

 $r \in [0,1].$

If f is (ii)-differentiable then

$$\begin{aligned} f'(t)(r) &= [\overline{f}'(t,r), \underline{f}'(t,r)], \quad t \in T, \\ r &\in [0,1]. \end{aligned}$$

3 Description of the method

In this section we are going to solve the Bernoulli equation with fuzzy initial condition under generalized H-differentiability.

To obtain the approximation solution of Eq.(1.1), based on Definition (2.4) we have two cases as follows:

Case (1):

 \widetilde{u}' is (i)-differentiable, in this case we have,

$$\widetilde{u}(t) = \widetilde{a}_0 + \int_0^t \widetilde{Q}(s)\widetilde{u}(s) \, ds + \int_0^t \widetilde{R}(s)\widetilde{u}^n(s) \, ds.$$
(3.3)

Case (2):

 \widetilde{u}' is (*ii*)-differentiable, in this case we have,

$$\widetilde{u}(t) = \widetilde{a}_0 \ominus (-1) [\int_0^t \widetilde{Q}(s) \widetilde{u}(s) \, ds + \\ \int_0^t \widetilde{R}(s) \widetilde{u}^n(s) \, ds].$$
(3.4)

Now, we can write successive iterations (by using Picard method) as follows:

Case (1):

$$\widetilde{u}_{0}(t) = \widetilde{a}_{0},
\widetilde{u}_{n+1}(t) = \widetilde{a}_{0} + \int_{0}^{t} \widetilde{Q}(s) \widetilde{u}_{n}(s) \, ds +
\int_{0}^{t} \widetilde{R}(s) \widetilde{u}_{n}^{n}(s) \, ds, \quad n \ge 0.$$
(3.5)

Case (2):

$$\begin{aligned} \widetilde{u}_0(t) &= \widetilde{a}_0, \\ \widetilde{u}_{n+1}(t) &= \widetilde{a}_0 \ominus (-1) [\int_0^t \widetilde{Q}(s) \widetilde{u}_n(s) \ ds + \\ \int_0^t \widetilde{R}(s) \widetilde{u}_n^n(s) \ ds], \quad n \ge 0. \end{aligned}$$
(3.6)

4 Existence and convergence analysis

In this Section we are going to prove the existence and uniqueness of the solution and convergence of the method by using the following assumptions.

$$D(\widetilde{u}^{n}(t), \widetilde{u}^{*^{n}}(t)) \leq MD(\widetilde{u}(t), \widetilde{u}^{*}(t)).$$
$$D(\widetilde{Q}(t), \widetilde{0}) \leq L_{1},$$
$$D(\widetilde{R}(t), \widetilde{0}) \leq L_{2}.$$

Let,

$$\alpha = T(L_1 + ML_2).$$

Lemma 4.1 If $\widetilde{u}, \widetilde{v}, \widetilde{w} \in E^n$ and $\lambda \in \mathbb{R}$, then, (i) $D(\widetilde{u} \ominus \widetilde{v}, \widetilde{u} \ominus \widetilde{w}) = D(\widetilde{v}, \widetilde{w}),$ (ii) $D(\ominus \lambda \widetilde{u}, \ominus \lambda \widetilde{v}) = |\lambda| D(\widetilde{u}, \widetilde{v}).$

Proof. (i): By the definition of *D*, we have,

$$\begin{array}{l} D(\widetilde{u} \ominus \widetilde{v}, \widetilde{u} \ominus \widetilde{w}) = \\ \max\{\sup_{r \in \underline{[0,1]}} \mid \underline{u}(r) - v(r) - \underline{u}(r) - w(r) \\ \sup_{r \in [0,1]} \mid \overline{u}(r) - v(r) - \overline{u}(r) - w(r) \\ \mid \} = \end{array}$$

 $\max\{\sup_{r\in[0,1]} \mid (\underline{u}(r) - \underline{v}(r)) - (\underline{u}(r) - \underline{w}(r) \mid,$

$$\sup_{r \in [0,1]} | (\overline{u}(r) - \overline{v}(r)) - (\overline{u}(r) - \overline{w}(r)) | \} =$$

$$\max\{\sup_{r\in[0,1]} | \underline{w}(r) - \underline{v}(r) |,$$

$$\sup_{r \in [0,1]} | \overline{w}(r) - \overline{v}(r) | \} =$$

 $\max\{\sup_{r\in[0,1]} | \underline{v}(r) - \underline{w}(r) |,$

 $\sup_{r \in [0,1]} |\overline{v}(r) - \overline{w}(r)| \} = D(\widetilde{v}, \widetilde{w}). \qquad \Box$

Proof. (ii):

$$D(\ominus \lambda \widetilde{u}, \ominus \lambda \widetilde{v})$$

$$= \max\{\sup_{r \in [0,1]} | \frac{\lambda u(r)}{\lambda u(r)} - \frac{\lambda v(r)}{\lambda v(r)} |, \\ \sup_{r \in [0,1]} | \frac{\lambda u(r)}{\lambda u(r)} - \frac{\lambda v(r)}{\lambda v(r)} | \} =$$

 $\max\{\sup_{r\in[0,1]} | \lambda u(r) - \lambda v(r) |,$

 $\sup_{r \in [0,1]} | \overline{\lambda u(r)} - \overline{\lambda v(r)} | \} = D(\lambda \widetilde{u}, \lambda \widetilde{v}) = |\lambda| D(\widetilde{u}, \widetilde{v}). \square$

Table 1: Numerical results for Example 5.1.

t	$(\underline{u}, n = 15, r = 0.4)$	$(\overline{u}, n = 15, r = 0.4)$
0.1	0.3439415	0.3724523
0.2	0.4047319	0.4432258
0.3	0.5164142	0.5572326
0.4	0.6324056	0.6671443
0.5	0.7228925	0.7551642
0.6	0.8337827	0.8534658

Table 2: Numerical results for Example 5.1.

x	$(\underline{u}, n = 13, r = 0.4)$	$(\overline{u}, n = 13, r = 0.4)$
0.1	0.4214517	0.4545184
0.2	0.5332087	0.5568476
0.3	0.6427321	0.6777483
0.4	0.7659784	0.7856309
0.5	0.8208448	0.8427544
0.6	0.8736665	0.8974806

Theorem 4.1 Let $0 < \alpha < 1$, then Eq.(1.1), hase an unique solution and the solution $\tilde{u}_n(t)$ obtained from the Eq.(3.4) using Picard method converges to the exact solution of the Eq.(1.1) when \tilde{u}' is (ii)-differentiable.

Proof. Let \tilde{u} and \tilde{u}^* be two different solutions of Eq.(1.1) then

$$D(\widetilde{u}(t), \widetilde{u}^*(t)) = D(\widetilde{a}_0 \ominus (-1) [\int_0^t \widetilde{Q}(s)\widetilde{u}(s) \ ds +$$

$$\int_0^t \widetilde{R}(s)\widetilde{u}^n(s) \ ds], \widetilde{a}_0$$

 $\ominus (-1) [\int_0^t \widetilde{Q}(s) \widetilde{u}^*(s) \ ds +$

$$\int_0^t \widetilde{R}(s)\widetilde{u}^{*^n}(s) \ ds]) =$$

$$D(\ominus(-1)[\int_0^t \widetilde{Q}(s)\widetilde{u}(s) \ ds + \int_0^t \widetilde{R}(s)\widetilde{u}^n(s) \ ds],$$

$$\ominus (-1) [\int_0^t \widetilde{Q}(s) \widetilde{u}^*(s) \, ds +$$

$$\int_0^t \widetilde{R}(s)\widetilde{u}^{*^n}(s) \ ds])$$

$$\leq TL_1(D(\widetilde{u}(t),\widetilde{u}^*(t))) +$$

$$TL_2M(D(\widetilde{u}(x,t),\widetilde{u}^*(x,t)))$$

$$= \alpha D(\widetilde{u}(t), \widetilde{u}^*(t)).$$

From which we get $(1 - \alpha)D(\widetilde{u}(t), \widetilde{u}^*(t)) \leq 0$. Since $0 < \alpha < 1$, then $D(\widetilde{u}(t), \widetilde{u}^*(t)) = 0$. Implies $\widetilde{u}(t) = \widetilde{u}^*(t)$. Also, we have

$$D(\widetilde{u}_{n+1}(t), \widetilde{u}(t)) \le \alpha D(\widetilde{u}_n, \widetilde{u}).$$

Since, $0 < \alpha < 1$, then $D(\widetilde{u}_n(t), \widetilde{u}(t)) \to 0$ as $n \to \infty$. Therefore, $\widetilde{u}_n(t) \to \widetilde{u}(t)$. \Box

Remark 4.1 The proof of other case is similar to the previous theorem.

5 Numerical examples

In this section, we solve the fuzzy Bernoulli equation by using the Picard method. The program has been provided with Mathematica 6 according to the following algorithm where ε is a given positive value.

Algorithm :

Step 1. Set $n \leftarrow 0$.

Step 2. Calculate the recursive relations (5) and (6).

Step 3. If $D(\widetilde{u}_{n+1}(t), \widetilde{u}_n(t)) < \varepsilon$ then go to step 4,

else $n \leftarrow n+1$ and go to step 2.

Step 4. Print $\tilde{u}_n(t)$ as the approximate of the exact solution.

Example 5.1 Consider the Riccati equation as follows:

$$\widetilde{u}' = \widetilde{u}(t) + \widetilde{u}^3(t). \tag{5.7}$$

With fuzzy initial condition:

$$\widetilde{u}(0) = (0.15, 0.23, 0.36).$$
(5.8)

 $\varepsilon = 10^{-4},$

Table 1 shows that the approximation solution of the fuzzy Bernoulli equation is convergent with 15 iterations by using the Picard method when u' is (i)-differentiable.

 $\alpha = 0.568792.$

$$\alpha = 0.625643.$$

Table 2 shows that the approximation solution of the fuzzy Bernoulli equation is convergent with 13 iterations by using the Picard method when u' is (ii)-differentiable.

Acknowledgments

The author would like to express her sincere appreciation to the Department of Mathematics, Islamic Azad University, Qazvin Branch for their cooperation.

6 Conclusion

The fuzzy Bernoulli Equation is the most important and applicable equation in financial mathematics. Since solution of this equation under generalized H-differentiability has not been reviewed before. In this paper we are going to achieve the approximated solutions of this equation by using iterative method with the new and important definition in the fuzzy field, so proving the existence, solution singularity and method convergence on this equation is one of the new jobs that has been done on this paper. Up to now there was only reviewed of first definition of generalized Hdifferentiability on fuzzy Bernoulli equation and not in general case.

References

 S. Abbasbandy, T. Allahviranloo, Numerical solutions of fuzzy differential equations by Taylor method, J. Comput. Meth. Appl. Math. 2 (2002) 113-124.

- [2] S. Abbasbandy, T. Allahviranloo, O. Lopez-Pouso, J. J. Nieto, Numerical methods for fuzzy differential inclusions, Comput. Math. Appl. 48 (2004) 1633-1641.
- [3] S. Abbasbandy, J. J. Nieto, M. Alavi, Tuning of reachable set in one dimensional fuzzy differential inclusions, Chaos Soliton and Fractals 26 (2005) 1337-1341.
- [4] T. Allahviranloo, N. Ahmady, E. Ahmady, Numerical solution of fuzzy differential equations by predictor-corrector method, Inform. Sci. 177 (2007) 1633-1647.
- [5] T. Allahviramloo, The Adomian decomposition method for fuzzy system of linear equations, Appl. Math. Comput. 163 (2005) 553-563.
- [6] MF. Abbod, DG. Von Keyserlingk, DA. Linkens, M. Mahfouf, Survey of utilisation of fuzzy technology in medicine and healthcare, Fuzzy Sets Syst. 120 (2001) 331-349.
- T. Allahviranloo, Difference methods for fuzzy partial differential equations, Comput. Methods. Appl. Math. 2 (2002) 233-242.
- [8] M. Afshar Kermani, F. Saburi, Numerical method for fuzzy partial differential equations, Appl. Math. Sci. 1 (2007) 1299-1309.
- [9] B. D. Anderson, J. B. Moore, *Optimal control-linear quadratic methods*, Prentice-Hall, New Jersey. 1999.
- [10] B. Bede, Note on Numerical solutions of fuzzy differential equations by predictorcorrector method, Inform. Sci. 178 (2008) 1917-1922.
- [11] B. Bede, S. G. Gal, Generalizations of the differentiability of fuzzy number valued functions with applications to fuzzy differential equation, Fuzzy Set. Syst. 151 (2005) 581-599.
- [12] B. Bede, J. Imre, C. Rudas, L. Attila, First order linear fuzzy differential equations under generalized differentiability, Inform. Sci. 177 (2007) 3627-3635.
- [13] J. J. Buckley, T. Feuring, Fuzzy differential equations, Fuzzy Set. Syst. 110 (2000) 43-54.

- [14] J. J. Buckley, T. Feuring, Y. Hayashi, Linear systems of first order ordinary differential equations: fuzzy initial conditions, Soft Comput. 6 (2002) 415-421.
- [15] J. J. Buckley, L. J. Jowers, Simulating Continuous Fuzzy Systems, Springer-Verlag, Berlin Heidelberg, 2006.
- [16] S. Barro, R. Marin, *Fuzzy logic in medicine*, Heidelberg: Physica-Verlag. 2002.
- [17] J. J. Buckley, T. Feuring, Introduction to fuzzy partial differential equations, Fuzzy Set Syst. 105 (1999) 241-248.
- [18] M. Barkhordari Ahmadi, N. A. Kiani, Solving fuzzy partial differential equation by differential transformation method, J.Appl Math. 7 (2011) 1-16.
- [19] Y. Chalco-Cano, H. Roman-Flores, On new solutions of fuzzy differential equations, Chaos Soliton and Fractals. 38(2006) 112-119
- [20] Y. Chalco-Cano, Roman-Flores, M. A. Rojas-Medar, O. Saavedra, M. Jimnez-Gamero, *The extension principle and a decomposition of fuzzy sets*, Inform. Sci. 177 (2007) 5394-5403.
- [21] C. K. Chen, S. H. Ho, Solving partial differential equations by two-dimensional differential transform method, Appl. Math. Comput. 106 (1999) 171-179.
- [22] Y. J. Cho, H. Y. Lan, The existence of solutions for the nonlinear first order fuzzy differential equations with discontinuous conditions, Dyn. Contin. Discrete. 14 (2007) 873-884.
- [23] W. Congxin, S. Shiji, Exitance theorem to the Cauchy problem of fuzzy differential equations under compactance-type conditions, Inform. Sci. 108 (1993) 123-134.
- [24] Y. Chalco-Cano, H.Roman-Flores, M.D.Jimnez-Gamero, Generalized derivative and π-derivative for set-valued functions, Inform. Sci. 181(2011) 2177-2188.
- [25] Y. Y. Chen, Y. T. Chang, Bor-Sen Chen, Fuzzy solutions to partial differential equations: adaptive approach, IEEE Trans. Fuzzy Syst 17 (2009) 116-127.

- [26] P. Diamond, Time-dependent differential inclusions, cocycle attractors and fuzzy differential equations, IEEE Trans. Fuzzy Syst. 7 (1999) 734-740.
- [27] P. Diamond, Brief note on the variation of constants formula for fuzzy differential equations, Fuzzy Set Syst. 129 (2002) 65-71.
- [28] Z. Ding, M. Ma, A. Kandel, Existence of solutions of fuzzy differential equations with parameters, Inform. Sci. 99 (1997) 205-217.
- [29] D. Dubois, H. Prade, Towards fuzzy differential calculus: Part 3, differentiation, Fuzzy Set Syst. 8 (1982) 225-233.
- [30] D. Dubois, H. Prade, Theory and application, Academic Press. 1980.
- [31] DP. Datta, The golden mean, scale free extension of real number system, fuzzy sets and 1/f spectrum in physics and biology, Chaos Solitons and Fractals 17 (2003) 781-788.
- [32] MS. El Naschie, From experimental quantum optics to quantum gavity via a fuzzy Kahler manifold, Chaos Solitons and Fractals 25 (2005) 969-977.
- [33] C. Orgaz, O. Chanson, Bernoulli Theorem, Minimum Specific Energy and Water Wave Celerity in Open Channel Flow, Journal of Irrigation and Drainage Engineering, ASCE, 135 (2009) 773-778.
- [34] O. S. Fard, Z. Hadi, N. Ghal-Eh, A. H. Borzabadi, A note on iterative method for solving fuzzy initial value problems, J. Adv. Res. Sci. Comput. 1 (2009) 22-33.
- [35] O. S. Fard, A numerical scheme for fuzzy cauchy problems, J. Uncertain Syst. 3 (2009) 307-314.
- [36] O. S. Fard, An iterative scheme for the solution of generalized system of linear fuzzy differential equations, World Appl. Sci. J. 7 (2009) 1597-1604.
- [37] O. S. Fard, A. V. Kamyad, Modified k-step method for solving fuzzy initial value problems, Iran. J. Fuzzy Syst. 8 (2011) 49-63.

- [38] O. S. Fard, T. A. Bidgoli, A.H. Borzabadi, Approximate-analytical approach to nonlinear FDEs under generalized differentiability, J. Adv. Res. Dyn. Control Syst. 2 (2010) 56-74.
- [39] W. Fei, Existence and uniqueness of solution for fuzzy random differential equations with non-Lipschitz coefficients, Inform. Sci. 177 (2007) 329-4337.
- [40] G. Feng, G. Chen, Adaptative control of discrete-time chaotic system: a fuzzy control approach, Chaos Solitons and Fractals. 23 (2005) 459-467.
- [41] A. Farajzadeh, A. Hossein Pour, M. Amini, An Explicit Method for Solving Fuzzy Partial Differential Equation, Int. Math. Forum 5(2010) 1025-1036.
- [42] R. Goetschel, W. Voxman, *Elementary cal*culus, Fuzzy Sets Systems. 18 (1986) 31-43.
- [43] M. Guo, X. Xue, R. Li, Impulsive functional differential inclusions and fuzzy population models, Fuzzy Sets Syst. 138 (2003) 601-615.
- [44] M. J. Jang, C. L. Chen, Y. C. Liy, On solving the initial-value problems using the differential transformation method, Appl. Math. Comput. 115 (2000) 145-160.
- [45] L. J. Jowers, J. J. Buckley, K. D. Reilly, Simulating continuous fuzzy systems, Inform. Sci. 177 (2007) 436-448.
- [46] W. Jiang, Q. Guo-Dong, D. Bin, H_{∞} variable universe adaptative fuzzy control for chaotic systems, Chaos Solitons and Fractals. 24 (2005) 1075-1086.
- [47] O. Kaleva, Fuzzy differential equations, Fuzzy Set Syst. 24 (1987) 301-317.
- [48] O. Kaleva, The Cauchy problem for fuzzy differential equations, Fuzzy Set Syst. 35 (1990) 389-396.
- [49] O. Kaleva, A note on fuzzy differential equations, Nonlinear Anal. 64 (2006) 895-900.
- [50] A. Kauffman, M. M. Gupta, Introduction to Fuzzy Arithmetic: Theory and Application, Van Nostrand Reinhold, New York. 1991.

- [51] H. Chanson, Applied Hydrodynamics: An Introduction to Ideal and Real Fluid Flows, CRC Press, Taylor and Francis Group, Leiden, The Netherlands. 2009. ISBN 978-0-415-49271-3.
- [52] R.R. Lopez, Comparison results for fuzzy differential equations, Inform. Sci. 178 (2008) 1756-1779.
- [53] I. Lasiecka, R. Triggiani, Differential and algebraic Riccati equations with application to boundary/point control problems: continuous theory and approximation theory (Lecture notes in control and information sciences), Berlin: Springer. 1991.
- [54] M. Ma, M. Friedman, A. Kandel, Numerical solutions of fuzzy differential equations, Fuzzy Set Syst. 105 (1999) 133-138.
- [55] M.T. Mizukoshi, L. C. Barros, Y. Chalco-Cano, H. Roman-Flores, R. C. Bassanezi, *Fuzzy differential equations and the exten*sion principle, Inform. Sci. 177 (2007) 3627-3635.
- [56] M. M. Moghadam, I. Jalal, Finite Volume Methods for Fuzzy Parabolic Equations, J. Math. Comput. Sci. 2 (2011) 546-558.
- [57] H. T. Nguyen, A note on the extension principle for fuzzy sets, J. Math. Anal. Appl. 64 (1978) 369-380.
- [58] M. Oberguggenberger, S. Pittschmann, Differential equations with fuzzy parameters, Math. Mod. Syst. 5 (1999) 181-202.
- [59] G. Papaschinopoulos, G. Stefanidou, P. Efraimidi, Existence uniqueness and asymptotic behavior of the solutions of a fuzzy differential equation with piecewise constant argument, Inform. Sci. 177 (2007) 3855-3870.
- [60] M. L. Puri, D. A. Ralescu, Differentials of fuzzy functions, J. Math. Anal. Appl. 91 (1983) 552-558.
- [61] M.L. Puri, D. Ralescu, *Fuzzy random variables*, J. Math. Anal. Appl. 114 (1986) 409-422.
- [62] H. Rouhparvar, S. Abbasbandy, T. Allahviranloo, Existence and uniqueness of solution of an uncertain characteristic cauchy

reaction-diffusion equation by Adomian decomposition method, Math. Comput Appl. 15 (2010) 404-419.

- [63] Hoffman, J.E. Bernoulli, I. Jakob, Dictionary of Scientific Biography. 2, New York: Charles Scribner's Sons. 80(1970) 46-51.
- [64] S. Seikkala, On the fuzzy initial value problem, Fuzzy Set Syst. 24 (1987) 319-330.
- [65] S. Song, L. Guo, C. Feng, Global existence of solutions to fuzzy differential equations, Fuzzy Set. Syst. 115 (2000) 371-376.
- [66] O. Solaymani Fard, N. Ghal. Eh, Numerical solutions for linear system of first-order fuzzy differential equations with fuzzy constant coefficients, Infor. Sci. 181 (2011) 4765-4779.
- [67] P. Verma, P. Sing, K. V. George, H. V. Singh, S. Devotta, R. N. Singh, Uncertainty analysis of transport of water and pesticide in an unsaturated layered soil profile using fuzzy set theory, Appl. Math. Modelling 33 (2009) 770-782.
- [68] L. A. Zadeh, Information and Control, Fuzzy Set Syst. 8 (1965) 338-353.



Shadan Sadigh Behzadi she has born in Tehran- Iran in 1983. Got B.Sc and M.Sc degrees in applied mathematics, numerical analysis field from Islamic Azad University, Central Tehran Branch and PHD degree in applied mathemat-

ics, here numerical analysis field from Science and Research Branch, Islamic Azad University. Main research interest includ numerical solution of nonlinear Fredholm- Volterra integro-differential equation systems, ordinary differential equation, partial differential equation, fuzzy system and some equations in fluid dynamics.