



Analysis and Simulation of the Static Synchronous Compensation Effect in the Distribution System with Wind Farms Based on SCIG

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Abstract

Wind energy is one of the renewable energy sources. Using the maximum power available in the wind is necessary to achieve the performance of the wind turbine at maximum power. One of the ways to control the voltage at the connection point of the wind turbine to the power grid is to use flexible ac transmission systems (FACTS) controller. In this paper, the effect of static synchronous compensator (STATCOM) in a distribution system with induction generator wind farm is analyzed and simulated. The studied system consists of a 9 MW wind farm connected to a 25 kV distribution system that delivers power to the grid through a 25 kV feeder. The results show that the STATCOM can, in addition to providing active power in short-circuit fault conditions, adjust the voltage changes at the common connection point between the wind farm and the grid in normal and fault conditions.

Keywords: Distribution System, Wind Turbine, Static Synchronous Compensator.

1. INTRODUCTION

Wind energy is one of the main types of renewable energy, and it is geographically widely distributed and decentralized and it is almost always available [1,2].

The kinetic energy in wind turbines is converted into mechanical energy and then into electrical energy.

The kinetic energy of the wind is proportional to the second power of the wind speed and the wind power is proportional to the cube of the wind speed [3,4]. Therefore, as the wind speed increases, the wind power will also increase. Technical use of wind

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energy is possible when the average wind speed is in the range of 5 m/s to 25 m/s (90 km/h) [5,6]. Relatively less wind energy compared to fossil energy in the long term and high maneuverability in exploitation (from several watts to several megawatts) are the advantages of wind energy.

In addition to providing a part of the electricity demand, wind energy has other advantages such as the wind turbine does not consume fuel, diversifies energy sources and creates a sustainable energy system, does not need water, and does not pollute the environment [7,8].

Flexible ac transmission systems are used for proper control to achieve power system flexibility [9,10]. These controllers can be used to improve system performance [11,12]. Among their effects, we can mention increasing the power transmission capacity, improving the stability of the power system, increasing the control capability, and increasing the power transmission capability of the network [13,14].

Static synchronous compensator (STATCOM) is one of the FACTS devices, whose structure is based on the voltage source converter and is installed in parallel in the power system to control the transmission line voltage. The static synchronous compensator can inject active and reactive power into the system in a short time and affect the steady state and dynamic performance of the system and improve the system damping and voltage profile [15].

Common types of wind generators used in wind energy conversion systems are [16]: induction generator including squirrel cage induction generator (SCIG) [17,18], wound rotor induction generator with variable

resistance in the rotor [19], double-fed induction generator (DFIG) [20,21] and synchronous generators including classically excited (wound rotor) synchronous generator (WRSG) [22] and permanent magnet synchronous generator (PMSG) [23,24].

So far, various studies have been conducted on the application of FACTS devices in wind farm [25,26].

The optimal location of the static synchronous compensator to increase the transient voltage stability of a distribution network with wind power generation is proposed in [27], which is the studied network of fixed and variable speed wind turbines connected to a rural load center. Also, the dynamic reactive power requirement of wind turbines has been considered to determine the compensating rating.

Two non-linear control methods based on differential smoothness for static synchronous compensator to adjust the voltage in the 9-bus network of wind energy conversion system including wind farms based on dual feeding induction generator have been compared in [28], which results are similar. It shows the effectiveness of two control methods compared to the traditional PI linear control method.

The performance of wind farm with squirrel cage induction generator, wind farm with double fed induction generator, and hybrid wind farm during three-phase grid fault is studied in [29], which SCIG and DFIG wind farms are series compensators. Static Synchronous series compensators (SSSC) are equipped, but the combined wind farm (with the equal number of DFIG and SCIG) has no compensator. The result of the

study has shown that during a three-phase grid fault, although SSSC has improved the performance of DFIG and SCIG wind farms, the hybrid wind farm without SSSC controller has the best performance.

A stability analysis based on impedance network of wind turbine generator sequence for wind farms is presented in [30] and the compensating effect on damping is evaluated quantitatively. An innovative intelligence algorithm has been used to solve the STATCOM controller parameters to obtain the optimal stability margin of the wind farm under optimal performance constraints.

In various contexts of wind energy conversion system performance, voltage changes at the connection point of the generator to the network is a very important indicator, and voltage control at this point is important and necessary. In this paper, the effect of one of the FACTS devices called static synchronous compensator in the distribution system with wind farms is analyzed and simulated. The structure of the paper is as follows. In the second part, a brief

description of wind energy conversion system and wind turbine performance in four different areas is given. In the third part, the compensatory structure and its functioning are mentioned. In the fourth part, the studied system is mentioned. In the fifth part, the results of system simulation using Matlab Simulink software are presented. At the end, the conclusion is stated.

2. WIND ENERGY CONVERSION SYSTEM

The components of a wind energy conversion system are: wind generator, diode rectifier, power converter, and power control system. The wind generator consists of a wind turbine and a generator connected to it. Power production in wind energy conversion systems has a direct relationship with the rotary machines used in them [31,32]. The output power of the wind energy conversion system changes with the wind speed [33,34]. The power produced by wind turbine is [35,36]:

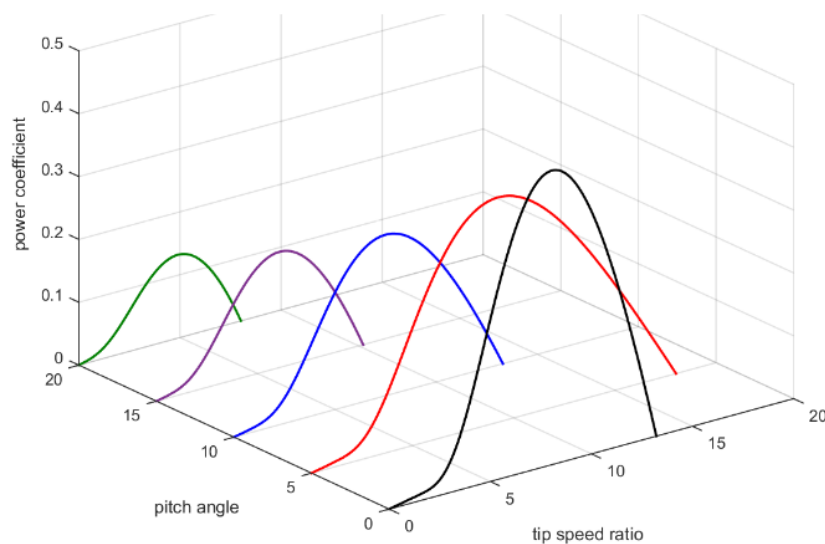


Fig. 1. The power factor curve of a wind turbine in terms of blade tip speed ratio.

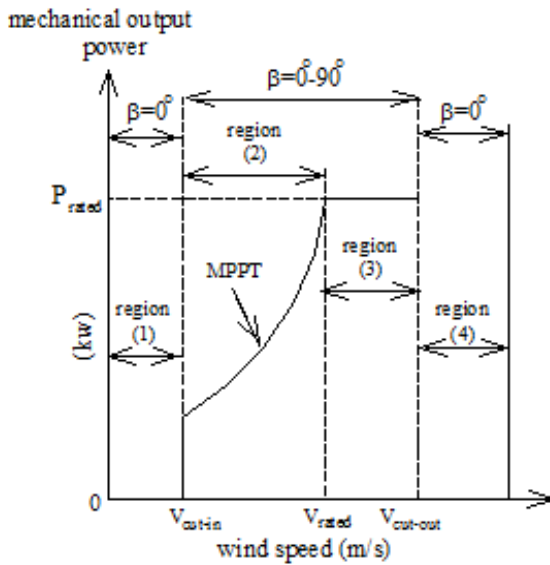


Fig. 2. Wind turbine performance areas according to wind speed.

$$P_w = \frac{1}{2} \pi \rho C_p(\lambda, \beta) R^2 V_w^3 \quad (1)$$

where R is the turbine radius (m), V_w is the wind speed (m/s), ρ is the air density (kg/m^3), C_p is the power factor, λ is the tip speed ratio (TSR), and β is the pitch angle [37,38].

The turbine power factor $C_p(\lambda, \beta)$ is a non-linear function of λ and β . The power factor for a particular choice has a maximum value of λ_{opt} . For large wind turbines, the optimal TSR value is about 6 [39,40]. In common modern wind turbine systems, the maximum power factor is about 0.45 [41,42]. The higher the power factor, the greater the aerodynamic efficiency of the blades. Fig. 1 shows the power factor curve of a wind turbine according to the blade tip speed ratio.

Wind speed is the determining factor of reference power, torque, or turbine speed. Based on the wind speed, turbine performance can be divided into four general modes. Fig. 2 shows the mechanical output

power of the wind turbine in terms of wind speed in four different areas, which are (1) wind speed less than the low cutoff speed, (2) speed, torque and power control function, (3) wind speed more than the nominal value and less than the high cutoff value and (4) wind speed exceeding the high cutoff speed [43,44]. If the wind speed is higher than the cut-off speed (V_{co}), the rotor is braked both electrically and mechanically so that it is stationary and the wind turbine is prevented from being damaged due to excessive speed.

3. STATIC SYNCHRONOUS COMPENSATOR

The static synchronous compensator consists of three main parts: voltage converter, transformer, and controller which is connected to the network in parallel and acts as a synchronous voltage source [45,46]. This compensator is capable of compensating a certain reactive power regardless of the system voltage level. Among the characteristics of this compensator, we can mention the reduction of fluctuations of active power and reactive power consumed by the load, no harmonic production, and reduction of voltage filter [47,48].

The one-line diagram of the compensator connection to the bus is shown in Fig. 3, where the static compensator consists of a voltage source converter (VSC) connected to the grid through a transformer. The reactive power of the exchange between the converter and the ac system is controlled by changing the three-phase output voltage range of the converter, and the reactive power of the exchange changes. The power exchange of

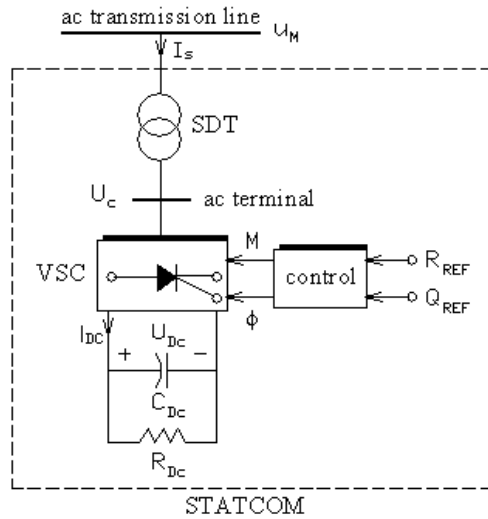


Fig. 3. One-line diagram of the compensating connection to the bus.

the converter with the system is the charging and discharging of the capacitor, and the function of the capacitor is to provide the voltage level of the converter and the dc voltage level of the capacitor must remain constant in all stages of operation. P_{REF} and Q_{REF} signals determine the size of the generated voltage and its phase angle. The

R_{DC} parallel resistance shows the sum of the switching losses of the inverter and the power losses in the parallel capacitor C_{DC} .

Fig. 4 shows the changes in compensator output power for three states without compensator, maximum, and minimum compensator current.

4. STUDIED SYSTEM

The studied system, is a wind farm consisting of six 1.5 MW wind turbines (three pairs of 1.5 MW wind turbines), which are connected to a 25 kV distribution system and fed through a 25 kV-25 km feeder. It exports electricity to a 120 kV network. Squirrel cage induction generators are used in wind turbines, whose stator winding is directly connected to the 60 Hz grid, and the rotor is driven by a variable pitch wind turbine. The rated speed is 9 m/s and the pitch angle is controlled to limit the output power of the generator in its rated value for winds higher

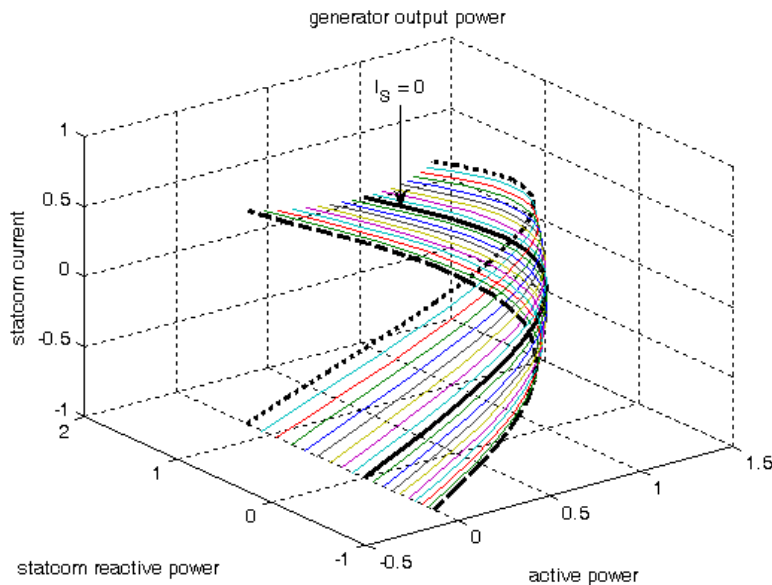
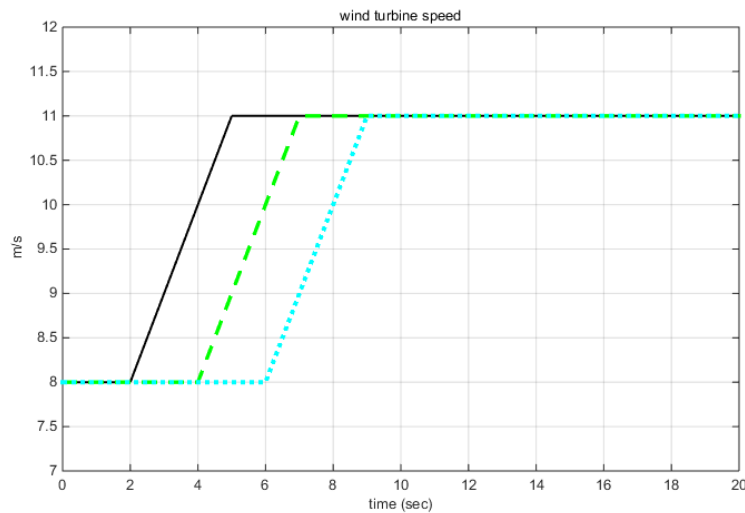


Fig. 4. Effect of compensating current on output power.

Table 1. Set parameters of turbines.

Parameter	Value
Proportional gain of pitch angle controller	5
The gain of the pitch angle controller integrator	25
Maximum pitch angle change rate	2 deg/s
Nominal mechanical output power of the wind turbine	$2 \times 1.5 \times 10^6$ W
Base wind speed	9 m/s
Base rotation speed	1 pu/base generator speed

**Fig. 5. Wind turbine speed.**

than the rated speed. To generate power, the speed of the induction generator should be slightly higher than the synchronous speed. The speed varies between approximately 1 pu at no load and 1.005 pu at full load. Each wind turbine has a protection system to monitor voltage, current, and machine speed. The reactive power absorbed by the induction generators is partially compensated by the capacitor banks connected to each low voltage bus of the wind turbine. For each pair of 1.5 MW turbines, this power is 400 KW. The rest of the reactive power required to

maintain the voltage of 25 kV in the 25 kV distribution bus close to one unit is supplied by a 3 MW static synchronous compensator with a 3% droop setting. The basic power is considered to be 3 MVA. The rated speed of the wind that creates the rated mechanical power is 9 m/s.

5. SIMULATION RESULTS

In this section, the simulation results for a period of 20 seconds using Simulink Matlab software are shown.

In the simulation results, the behavior of three turbines is shown with a solid line

(black color) for turbine 1, a dashed line (green color) for turbine 2, and a dotted line (blue color) for turbine 3, respectively. At first, the wind speed for all turbines is considered to be 8 m/s. The speed of turbines one, two, and three change to 11 m/s in 2, 4, and 6 seconds respectively for three seconds (Fig. 5). During 15 seconds a temporary fault is applied to the wind turbine terminal 2 (low voltage 575 volts). Table 1 shows the

parameters set for three pairs of turbines for simulation.

Figs. 6 and 7 show the voltage of bus 25 without and with compensator. As can be seen, without the compensator, the voltage drop in the steady state has increased.

Figures 8 and 9 show active bass power in two modes. As you can see, in steady state, one of the turbines is out of the circuit and the throughput is 6 MW.

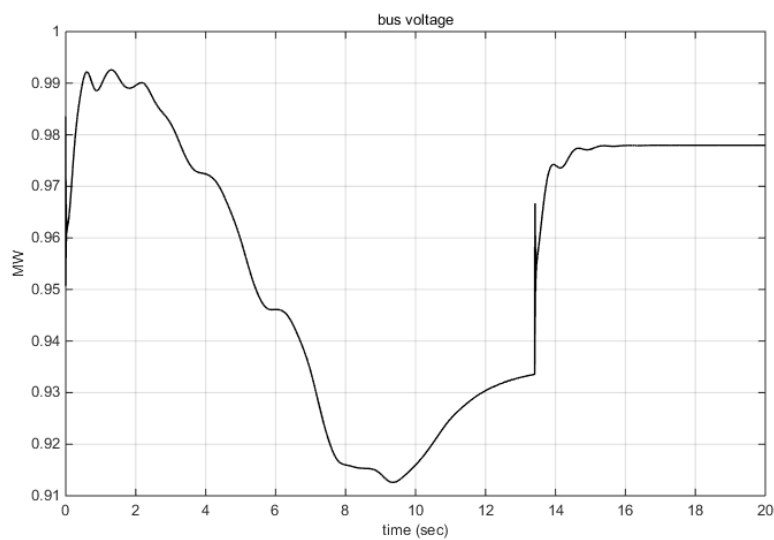


Fig. 6. Bus voltage (without compensator).

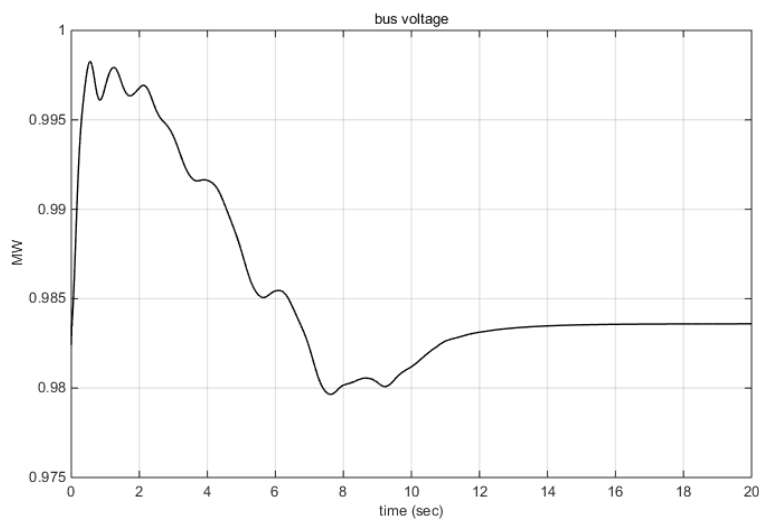


Fig. 7. Voltage bus (with compensator).

The Figs. 10 and 11 show the productive active power and the Figs. 12 and 13 show the productive reactive power of wind turbines in two states. With the presence of the compensator, the turbines are in the circuit and each of them produces 1.5 MW.

Figs. 14 and 15 show the pitch angle for two cases. Figs. 16 and 17 show the size of the compensator bass and the reactive power produced by the compensator. The compensator prevents voltage drop by generating reactive power and injecting it into the network.

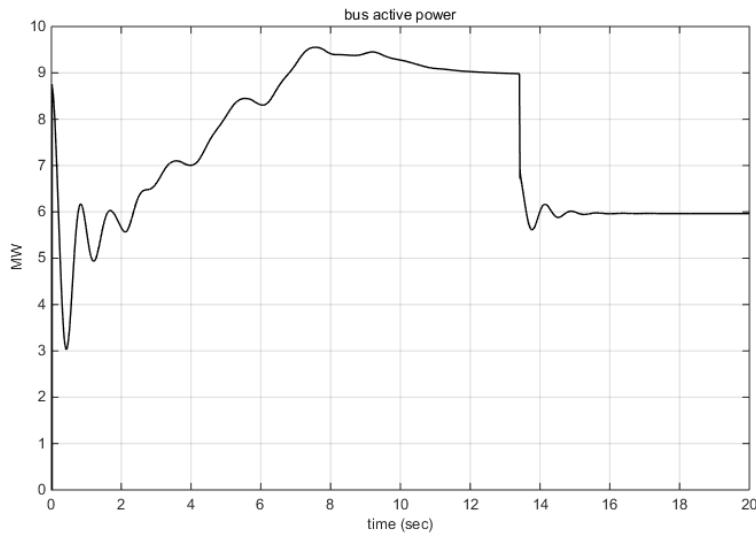


Fig. 8. Bus voltage active power (without compensator).

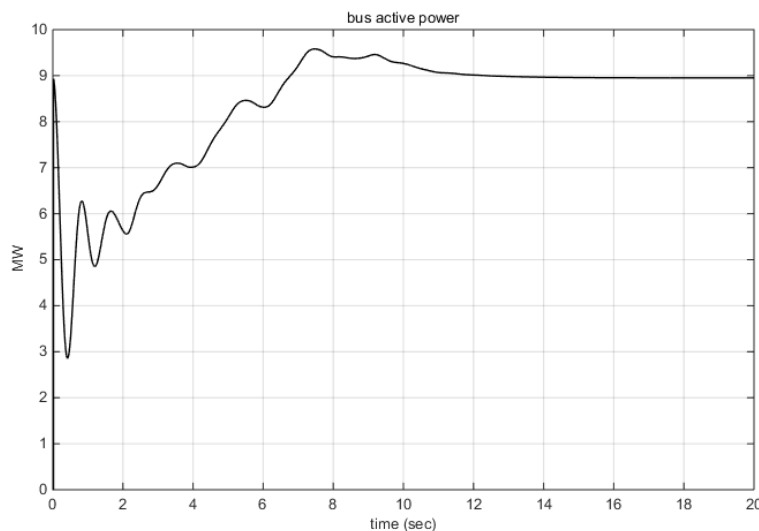


Fig. 9. Bus active power (with compensator).

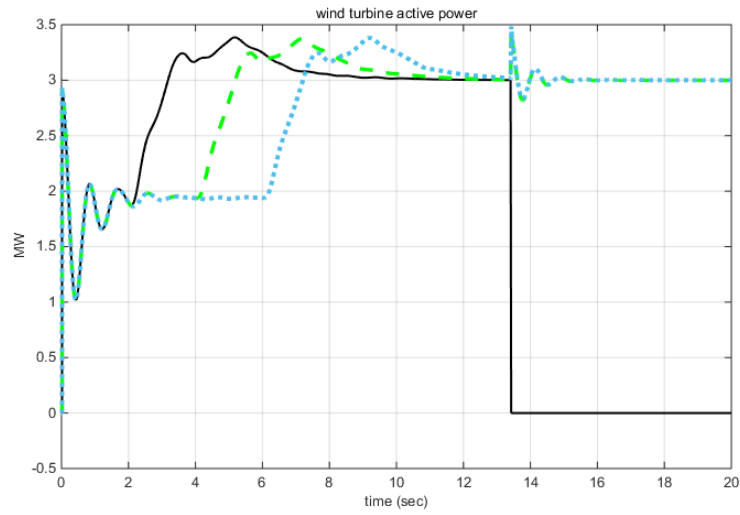


Fig. 10. Wind turbine active power (without compensator).

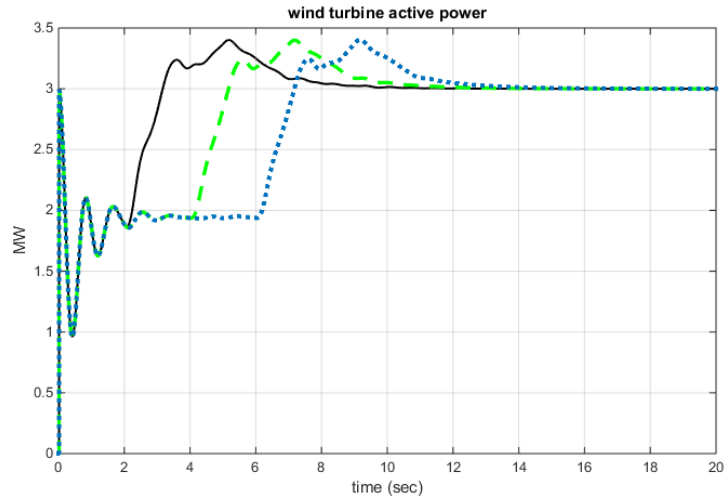


Fig. 11. Wind turbine active power (with compensator).

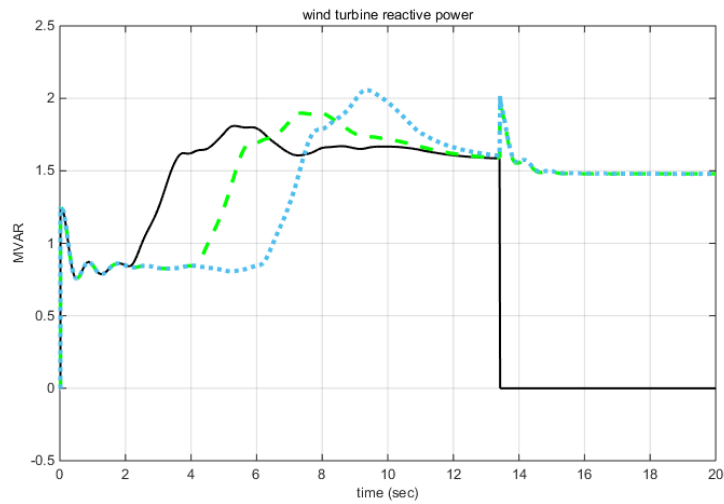


Fig. 12. Wind turbine reactive power (without compensator).

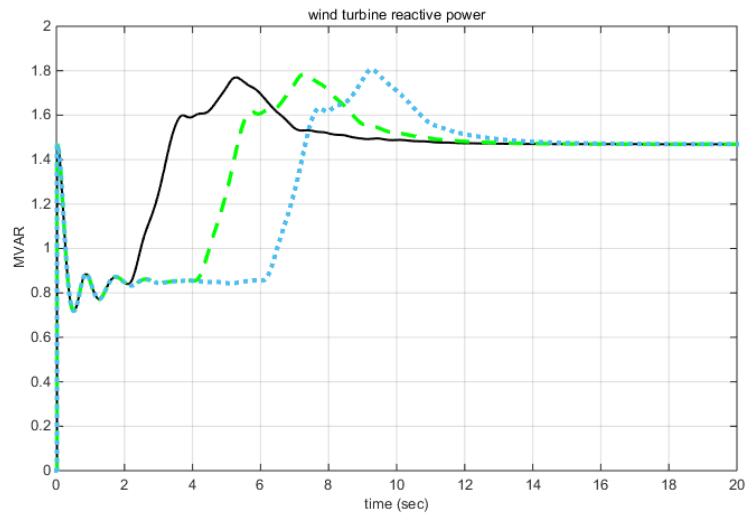


Fig. 13. Wind turbine reactive power (with compensator).

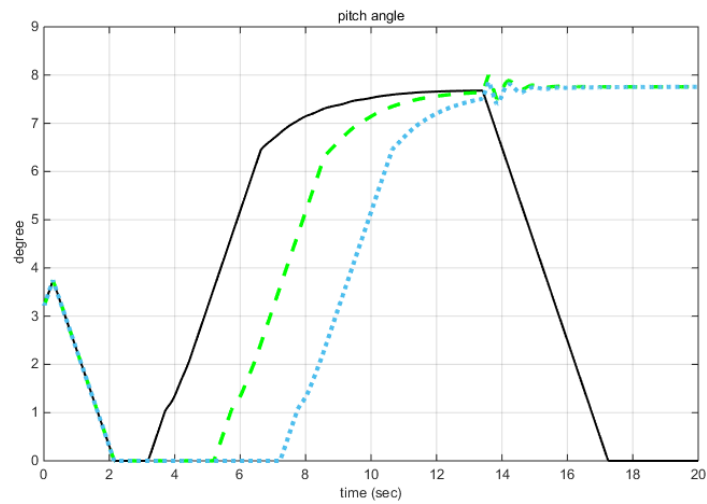


Fig. 14. Pitch angle (without compensator).

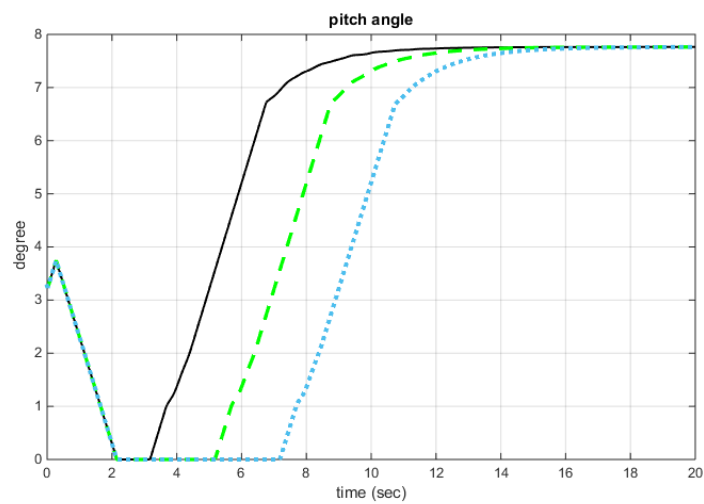


Fig. 15. Pitch angle (with compensator).

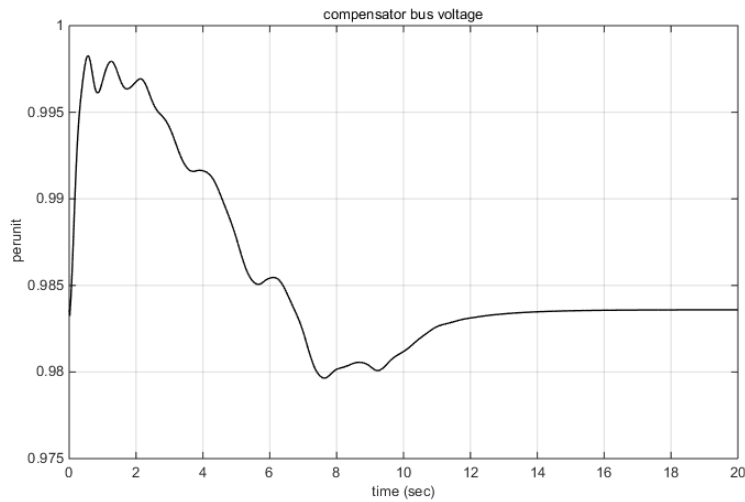


Fig. 16. Compensator bus voltage.

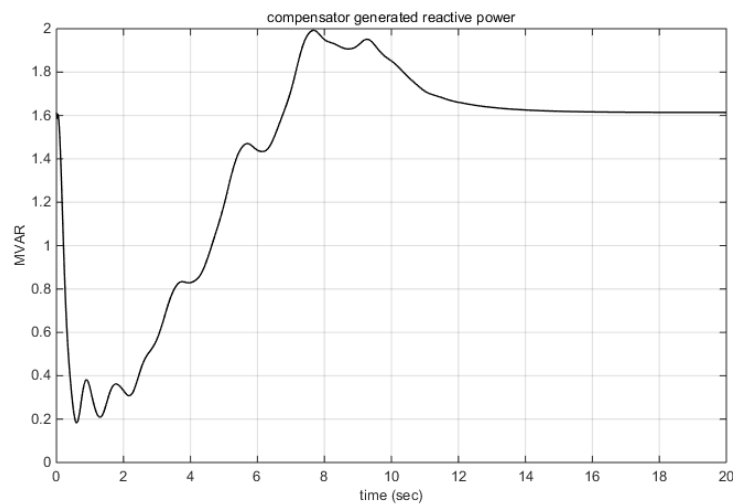


Fig. 17. Compensator generated reactive power.

6. CONCLUSION

Wind energy changes continuously with the change in wind speed during the day. The amount of power output from a wind energy production system depends on the accuracy of tracking the peak power points, regardless of the type of generator used.

In this paper, the effect of static synchronous compensator on the behavior of the distribution system was shown. Three pairs of turbines with speed variations were

considered. The simulation results showed the compensatory effect of preventing the voltage drop and the exit of the turbines from the circuit.

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