A Topology of Class-AB OTA with Increased DC-Gain and Slew-Rate

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Abstract – The Operational Trans- conductance Amplifier (OTA) is a main building block in several analog signal and mixed- signal integrated circuits. This paper, a novel low power Class- AB CMOS Operational trans- conductance amplifier (OTA) with High gain and high slew rate is presented. The proposed two-stage OTA, the characteristics of class-AB are applied in both of the stages. The Use of active loads for the first stage provides the effective trans-conductance boosting and increased,DC-gain product. The nonlinear current mirrors boost the current of the second stage leading to the increase of the slew rate. The OTA canbe employed in low- voltage low- power circuits requiring a good performance/power tradeoff. Theoretical analysis and Cadence simulations prove the performance of the new OTA. The simulation results indicate that the DC gain is improved by abot 13db. The UGBW and phase margin of the proposed OTA are 305 MHZ and 65°, respectively.

Keywords: Operational Trans- conductance Amplifier (OTA), Class- AB circuits, CMOS integrated circuits, Adaptive biasing

1. Introduction

OTA is a very important building block and is often used in many systems, such as sample-and-hold circuits and data converters in electronic circuits. In such applications, OTAs should have high values for DC-gain, slew rate (SR), and unity-gain bandwidth (UGBW) [1-3]. The continuously growing market of mobile and portable electronic devices and the evolution of CMOS technologies have made the OTA a critical design analog block in many systems, in terms of overall power consumption and performance [4–6]. Obtaining these aims may be difficult by the class-A OTAs. In the class-A OTAs, increasing of SR and UGBW are achieved with the cost of increasing the circuit power. In order to overcome the shortcomings of the class-A OTAs, the class-AB OTA can be useful. Several techniques for class-AB OTAs have been reported in the literatures [7-21].

Class-AB OTAs suggested in [7] have high values for current efficiency (CE) factors. This improvement in CE is

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obtained by increasing the maximum value of the signal current both in the input and output branches. However, these methods suffer from low open loop gain. A technique to achieve class AB operation is suggested with the cost of increasing the power consumption and silicon area of the circuit [8]. Some class-AB techniques have been applied to the recycling folded cascode (RFC) OTA [9-10]. But, the OTAs need additional local common-mode feedback loops at the active load of the differential pair which should be implement by passive or active matched resistors. In another method [11], adaptive biasing circuit (ABC) for classic fully differential circuits have been introduced using dynamically control the bias current of the amplifier. However, circuit area and power dissipation have been increased due to auxiliary blocks. In [12], a class-AB OTA based on single-stage topology with non-linear current amplifiers has been introduced. But, some target specifications such as DC-gain and SR have not been improved significantly. Some low-current OTAs have been suggested in [13-19]. But, technology or temperature sensitivity in the proposed class-AB OTAs are the main drawback of these techniques. The organization of this paper is as follows. In Section 2, the proposed circuit is briefly described. The performance evaluations of the OTA and simulation results are given in Section 3. Finally conclusions are drawn in section 4.

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2. Proposed OTA Structure

In this section, a new family of OTA topologies suitable for low-voltage and low-power operation is proposed. The conventional two-stage OTA using hybrid-cascode compensation technique is shown in Figure 1 [22]. The first and second stages are folded-cascode and common-source amplifiers, respectively. The Figure 2 shows the diagram of the proposed OTA. Two matched transistors M_1 and M_2 form the differential pair in the first stage is connected with an adaptive biasing circuit. The first one provides a conventional class AB operation. It can set well controlled quiescent currents but when a large differential in put signal is sense it automatically boosts dynamic currents above these quiescent currents. Often these bias current are chosen small in order to save power consumption however, they deteriorate the small signal performance. the flipped voltage follower (FVF) [23-24] including the transistors $(M_{1a}, M_{1b}, M_{2a}, M_{2b}, M_{3a}, M_{3b})$ is utilized as an adaptive biasing circuit which help increase the SR .In figure 2, V_0 and V_{0UT} are the output voltages of the first and second stages, respectively.Source of M_1 is connected to the drain of M_{3b} and to the gate of M_{10} . similarly, Source of M_2 is connected to the drain of M_{3a} and to the gate of M_9 . Therefore, the input signal appears at the gates of active loads transistors M_9 and M_{10} enhancing the transconductance of the OTA.



Fig. 1 The conventional OTA [22].

The nonlinear current mirrors have been used for the output active loads including transistor sets $(M_{11}M_{13}M_{15}M_{17})$ and $(M_{12}M_{14}M_{16}M_{18})$. The gates of M_{11} and M_{12} are connected to the first stage outputs V_{0^+} and V_{0^-} , respectively. The transistors M_{15} and M_{16} are biased near the ohmic region so that their drain-source voltages are a bit higher than $V_{DS sat}$.

Consider a condition in which input voltages Vi+ and Vi- increase and decrease, respectively. The voltages of the nodes Vo- and Vo+ are then decreased and increased, respectively. Decreasing the voltage of the node Vo- increases the current of M_{12} .In order to change the drain

voltage of M_{12} that is actually the gate voltage of M_{18} . Therefore, the current flowing through M_{18} increases significantly.

2.1 DC Gain

In this architecture, the input signal also appear at the gaete-source of M_9 and M_{10} using the Flipped Voltage Followers (FVF). This increases the effective transconductance of the proposed OTA. Figure 3 shows a small-signal model for calculating the voltages of the V_x and V_y nodes.



Fig.2 Proposed OTA structure.



Fig. 3 Small- signal model for calculating the voltages of the V_x and V_y nodes.

$$V_X = \frac{V_i}{2} \tag{1}$$

$$V_Y = -\frac{g_{m2}}{g_{m3a}} V_i \tag{2}$$

However, in the proposed OTA, trans-conductance of the first stage is

$$g_{meff\,1} = g_{m1,2} + g_{m9,10}$$
(3)

The DC-gain of the proposed OTA can be improved compared to the conventional OTA. Neglecting the body effect, DC-gain is found as follows: $A_{DC} = A_1 \times A_2(4)$

in which A_1 represents the DC-gain of the first stage as shown below:

$$A_1 = g_{meff1} \times R_{out1} \tag{4}$$

Where R_{out1} denotes the output resistance of the first stage.

$$R_{out1} = g_{m7} r_{ds7} r_{ds9} \parallel (g_{m5} r_{ds5} (r_{ds1} \parallel r_{ds3}))$$
(5)

Where

$$A_{1} = (g_{m1} + g_{m9}) \times [g_{m7}r_{ds7}r_{ds9} \parallel (g_{m5}r_{ds5}(r_{ds1} \parallel r_{ds3}))]$$
(6)

where, r_{ds} is the drain-source resistance of the transistors and g_{mi} denotes the small-signal transconductance of the corresponding transistors.

In equation (7), A_2 is the DC-gain of the second stage can be calculated as follows:

$$A_2 = g_{meff2} \times R_{out2} \tag{7}$$

where g_{meff2} represents the effective transconductance of the second stage and R_{out2} is the output resistance of the second stage as given below

$$R_{out2} = r_{ds15} \parallel r_{ds17} \parallel r_{ds21} \tag{8}$$

Finally, G_{meff2} is obtained as follows

$$g_{meff2} = \left(g_{m17} + g_{m11}g_{m15}\left(r_{ds11} \parallel \frac{1}{g_{m15}}\right)\right)(9)$$

Hence, the amplifier's DC gain is given by:

$$A_{DC} = (g_{m1} + g_{m9}) \times [g_{m7}r_{ds7}r_{ds9} \parallel (g_{m5}r_{ds5}(r_{ds1} \parallel r_{ds3}))] \times (g_{m19} + g_{m11}g_{m17}(r_{ds11} \parallel \frac{1}{g_{m13}})) \times (r_{ds17} \parallel r_{ds19} \parallel r_{ds21})$$
(10)

Thus, the unity-gain bandwidth of the proposed amplifier is obtained as:

$$UGBW = \frac{G_{meff1}}{C_c} = \frac{g_{m1} + g_{m9}}{C_c}$$
(11)

where Cc represent the Miller compensation capacitor. Note that due to increased trans-conductance, the enhancement of UGBW is also obtained.

2.2 Input-referred noise



Fig.4 Noise of the proposed 0TA

According to Figure 4, the noise referenced to the input can be calculated in this figure, The noise current i'_n is given by

$$v_x = \frac{g_{m1a} \times V_{n1a}}{g_{m2a}} \tag{12}$$

$$\dot{i_n} = \frac{v_x}{1/g_{m2}}$$
 (13)

where

$$\dot{i_n} = \frac{\frac{g_{m1a} \times V_{n1a}}{g_{m2a}}}{\frac{1}{g_{m2}}}$$
(14)

The output noise voltage per unit bandwidth can be found as follows:

$$\overline{V_{no1a}^2} = i_n^{\prime 2} \times R_{out1}^2 \tag{15}$$

$$\overline{V_{no1a}^2} = \left(\frac{g_{m1a} \times g_{m2}}{g_{m2a}}\right)^2 \times \overline{V_{n1a}^2} \times R_{out1}^2 \tag{16}$$

$$\overline{V_{no1a}^2} = A_V^2 \times \overline{V_{ni1a}^2} \tag{17}$$

$$\overline{V_{n\iota 1a}^2} = \frac{\overline{V_{n01a}^2}}{A_V^2} \tag{18}$$

where

$$A_V = g_{meff} \times R_{out1} \tag{19}$$

The input-referred thermal noise of transistor M_{1a} , is explained as follows:

$$\overline{V_{nlM1a}^2} = \frac{\left(\frac{g_{m1a} \times g_{m2}}{g_{m2a}}\right)^2 \times \overline{V_{n1a}^2} \times R_{out1}^2}{g_{meff}^2 \times R_{out1}^2}$$
(20)

The input-referred thermal noise of transistors M_1 , M_3 and, M_9 are given by:

$$\overline{V_{nlM1}^2} = \left(\frac{g_{m1}}{g_{meff}}\right)^2 \times \overline{V_{n1}^2}$$
(21)

$$\overline{V_{n\iota M3}^2} = \left(\frac{g_{m3}}{g_{meff}}\right)^2 \times \overline{V_{n3}^2}$$
(22)

$$\overline{V_{nlM9}^2} = \left(\frac{g_{m9}}{g_{meff}}\right)^2 \times \overline{V_{n9}^2}$$
(23)

Finally by considering

$$\overline{V_{n1a}^2} = \left(\frac{4KT\gamma}{g_{m1a}}\right), \overline{V_{n1}^2} = \left(\frac{4KT\gamma}{g_{m1}}\right), \overline{V_{n3}^2} = \left(\frac{4KT\gamma}{g_{m3}}\right)$$
$$\overline{V_{n9}^2} = \left(\frac{4KT\gamma}{g_{m9}}\right) \tag{24}$$

in the above equations, the total input-referred thermal noise voltage per unit bandwidth of the OTA can be found as follows:

$$\overline{V_{n\iota OTA}^2} = \frac{_{8KT\gamma}}{g_{meff}} (g_{m1a} + g_{m1} + g_{m3} + g_{m9}) \quad (25)$$

Therefore, increasing g_{meff} can significantly reduce the total input-referred thermal noise voltage of the proposed OTA.

2.3Output current of FVFCS

The architecture is a source degeneration current mirror topology formerly used for applications like input offset cancellation in amplifiers.

In these applications a degeneration transistor operating only in the ohmic region was used, thus implementing an approximately linear voltagecontrolled resistance. However, in this paper we make the degeneration transistor enter saturation region for large input currents. Hence, a strongly nonlinear equivalent resistance is achieved which yields a large output current boosting.

that transistor M_{16} is biased using a constant gate voltage in ohmic region but near the boundary of saturation region, and M_{14} is in saturation region. Given that M_{16} is constant, when the drain current I_{in} of M_{16} increases M_{16} enters saturation and develops a very large drain-source saturation voltage. This causes a large increase in the gate-source voltage of M_{18} given by $V_{GS18} = V_{DS16} + V_{GS14}$ which leads to a large increase in the output current. The current through M_{18} is

$$I_{18} = \frac{\beta_{18}}{2} \left(\sqrt{\frac{2I_{in}}{\beta_{14}}} + \frac{2I_{in}}{\lambda_{14}\beta_{14}(V_b - V_{th})^2} - \frac{1}{\lambda_{16}} \right)^2$$
(26)

where $\lambda_{16\neq 0}$ and $V_b > V_{th}$

The OTA in Figure. 2 is built using this adaptive load. When V_{in+} decreases $V_{id} < 0$, the Class-AB input stage generates a current through transistor M_2 much larger.

$$I_{20} = \frac{\beta_{18}}{2} \left(\sqrt{\frac{\beta_{12}}{\beta_{14}}} \left[\sqrt{\frac{2I_B}{\beta_{12}}} - V_{id} \right] + \frac{\beta_{12}}{\lambda_{16}\beta_{16}(V_b - V_{th})^2} \left[\sqrt{\frac{2I_B}{\beta_{12}}} - V_{id} \right] - \frac{1}{\lambda_{16}} \right)^2$$
For a large V_{id} (27) can be simplified to

$$I_{out} \approx \frac{\beta_{18}}{2} \left(\frac{\beta_{12}}{\lambda_{16}\beta_{16}(V_b - V_{th})^2} - V_{id}^2 \right)^2$$
(28)

From (28) it is clear that for a large V_{id} the output current increases with V_{id}^4 , that would enhance the current boosting provided by the Class-AB, quadratically.

2.4 Input Offset

Manufacturing process variations across the chip lead to mismatch in devices, which are otherwise identical by design. A mismatch model [11] based on the study of equal area rectangular devices, states that the variance of a parameter ΔP can be expressed as:

$$\sigma^2(\Delta P) = \frac{A_P^2}{WL} + S_P^2 D_X \tag{29}$$

Where A_P is the area proportionality constant for parameter, S_P is the variation of P with spacing, and D_X is the distance between two devices alongx. Since critical devices, such as the input pair or current mirrors, are interdigitated or cross-coupled, D_X approaches zero, and the second term of (29) can be neglected. Using (30), the drain-current variance due to process variation can be expressed as:

$$I_D = \frac{1}{2} \mu C_{ox} \frac{W}{L} (V_{GS} - V_T)^2$$
(30)

$$\sigma^{2}(I_{D}) = 4I_{D}^{2} \frac{\sigma^{2}(V_{T})}{(V_{GS} - V_{T})} + I_{D}^{2} \frac{\sigma^{2}(\beta)}{\beta^{2}}$$
(31)

Assuming $\sigma^2(V_T)$ and $\sigma^2(\beta)$ are uncorrelated. Here represents $\mu_n c_{ox} \underline{w}$.

Equation (31) is very useful, because from a circuit analysis stand point, the drain-current variance can be treated as a small signal that can be referred to the gate of the MOS device through its transconductance, g_m . The result is

$$\sigma^{2}(V_{GS}) = \sigma^{2}(V_{T}) + \frac{l_{D}^{2}}{g_{m}^{2}} \frac{\sigma^{2}(\beta)}{\beta^{2}}$$
(32)

and since in analog design $\frac{g_m}{I_D}$ is generally maximized, the effect of the second term of (31) is diminished. Therefore

$$\sigma^{2}(V_{GS}) \cong \sigma^{2}(V_{T}) = \frac{A_{VT}^{2}}{WL}$$
(33)

Here A_{VT} is the area proportionality constant for the threshold voltage, V_T , which is provided by process characterization.

Using (33), the input offset variance can be expressed as the sum of all device drain-current variances seen at the output, and then referred to the input using the G_m amplifier's. The drain currents of transistors, M_{3b} , M_1 , and M_9 , are chosen as I_1I , $\alpha_1 \times I$, and $\alpha_2 \times I$. It should be noted that α 1 and α 2 are positive constants. The input offset variance of the proposed OTA is calculated using the method proposed in [20].

$$\sigma^2(I_{DM3}) = \frac{g_{m3}^2 A_{VTN}^2}{W_3 L_3}$$
(34)

$$\sigma^{2}(I_{DM1}) = \frac{g_{m1}^{2}A_{VTP}^{2}}{W_{1}L_{1}}$$
(35)

$$\sigma^2(I_{D M9}) = \frac{g_{m9}^2 A_{VTN}^2}{W_9 L_9}$$
(36)

$$\sigma^{2}(V_{OS}) = \frac{2A_{VTP}^{2}}{W_{1}L_{1}} \left[1 + \frac{(\alpha_{1} + \alpha_{2})\mu_{N}}{\alpha_{1}\mu_{p}} \left(\frac{L_{1}}{L_{3}}\right)^{2} \frac{A_{VTN}^{2}}{A_{VTP}^{2}} + \frac{\alpha_{1}}{\alpha_{2}} \left(\frac{L_{1}}{L_{9}}\right)^{2} \right] (37)$$

In the above equations, A_{VTP} and A_{VTN} are the area proportionality constant for threshold voltage of PMOS and NMOS, respectively.

3 Simulation Results

In order to verify the performance of the proposed two-stage class-AB OTA several simulations are performed in a 0.18 μ m CMOS process with 1.8V supply voltage using cadence software.

The frequency responses of the proposed OTA are shown in the Figure 5. As can be seen form the results, DC-gain of the OTA is 96 dB.UGBW and phase margin of the proposed OTA are 305 MHz and 65° , Respectively. For the slew rate calculation, a square wave, 1 Vpp at 5 MHz was applied to the OTA and the result is given in Figure. The OTA specifications in the three processes and temperature corners are summarized in Table 1. As seen from the results, the OTA presents high DC-gain. In addition, the proposed OTA is stable in the three.

The proposed OTA simulation results are compared with the existing methods in Table 2. The results indicat e that the proposed OTA has the highest DCgain compared to the other techniques. also, it has the lo west inputreferred noise due to the improved input stage transconductance. To compare the other performance parame ters, the traditional couple of figures of merits in (38), (39) which for a given load indicate a tradeoff between speed performance and total bias current (L between the traditional couple of figures of merits in (38) and the tradeoff between speed performance and total bias current (

 I_T)are utilized [25].

$$FOM_s = \frac{UGBW C_L}{I_r}$$
(38)

$$FOM_{L} = \frac{SR.C_{L}}{I_{T}}$$
(39)

As can be seen from Table 2, the proposed OTA has proper values for both of FOMs and FOML.



Figure 5.Frequency responses for both OTAs: (a) magnitude and (b) phase.



Fig.6 Large signal step response of OTA

4. Conclusion

In this paper a new two-stage class-AB OTA in a 0.18 μ m CMOS process with a 1.8 V supply voltage has been presented. The proposed OTA was based on the simultaneous application of class-AB operation in both of the stages. Using active loads, the first stage trans-conductance has been increased. The nonlinear current mirror in the output stage has been employed to enhance the slew rate of the OTA. In order to evaluate the effectiveness of the proposed method, some simulations have been performed. The results indicated the better performance of the proposed OTA in terms of DC-gain, UGBW and SR compared to the existing methods.

Table	1	Specifications	of	the	proposed	OTA.
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Specification		Proposed OTA				
Technology	TT(27° C) 0.18μm	FF(-40° C) 0.18μm	SS(90° C) 0.18μm			
DC-Gain (dB)	96	88	96.5			
Input-Referredise@100kHz $(\mu V / \sqrt{Hz})$	0.21	0.19	0.30			
Output Voltage Swing (peak to peak) (V)	3.2	3.2	3.2			
Phase Margin (°)	65	62	67			
Power Dissipation (mW)	2.9	4	2.1			
Slew Rate $(V/\mu s)$	172	252	102			
UGBW (MHz)	305	440	201			
C _L (pF)	10	10	10			

	This work	[7]	[8]	[9]	[12]	[17]	
Technology	0.18µ1	0.35µ1	0.18µ1	0.13µm	0.5µ1	0.181	
Supply Voltage (V)	1.8	0.6	1	0.25	1	1.8	
DC-Gain (dB)	96	69	64	60	30	72	
Input-RefferedNoise@100kHz $(\mu v / \sqrt{Hz})$	0.21				144	144	
Differential Output Swing (pea k to peak) (V)	3.2						
Phase Margin (°)	65	65	45	53	90	50	
Power Dissipation (mW)	2.9	0.000 54	0.13	0.0000 18	0.08	11.9	
Slew Rate (V/µs)	169	0.015	0.7	0.0007	0.35	74.1	
UGBW (MHz)	305	0.011	2	0.002	0.2	86.5	
Loading Capacitance (pF)	10	15	1	15	80	200	
Operating Mode ^a	SI	SUB, BD	SI, B D	SUB, BD	SI	SI	
$FOM_s = \frac{MHz.pF}{mA}$	2000	183	15	417	200	261 3	
$FOM_L = \frac{V.pF}{us m\Delta}$	1012	250	5	146	350	223	

Table 2 Performance Comparison of the Proposed OTA and the Existing Methods.

^aSUB: subthresold; BD: bulk driven; SI: strong inversion.

^bOnly Schematic level simulation

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