Measuring the Overall Performances of Decision-Making Units in the Presence of Imprecise Data

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Abstract

Data envelopment analysis (DEA) is a method for measuring the relative efficiencies of a set of decision-making units (DMUs) that use multiple inputs to produce multiple outputs. In this paper, we study the measurement of DMU performances in DEA in situations where input and/or output values are given as imprecise data. By imprecise data we mean situations where we only know that the actual values lie in certain intervals, or cases in which data are given only as ordinal relationships. In this paper, we present two distinct approaches obtaining the upper and lower bounds of efficiency which the DMU under evaluation can have with imprecise data. The optimistic approach seeks the best score among the various values of the efficiency score, while the pessimistic approach seeks the worst score. The main idea of the paper is illustrated using an example. Also, two real-world cases are presented to demonstrate how the efficiency interval is interpreted. The efficiency interval not only describes the actual situation in more detail, but also relieves the psychological pressure on all the evaluated DMUs and the decision-maker.

Keywords: Data envelopment analysis; imprecise data; optimistic efficiency interval; pessimistic efficiency interval; overall efficiency interval.

1. Introduction

Data Envelopment Analysis (DEA) is widely used for evaluation and estimation of efficiency. DEA, first developed by Charnes et al. (2000), has been extensively applied to measurement and benchmarking of relative efficiency for various decision-making entities in the public and private sectors. In recent years, numerous articles and reports have investigated the application of DEA in educational centers, industry, and so on.

DEA computes an efficiency score for each decisionmaking unit (DMU) under evaluation against a set of DMUs. DEA efficiency score indicates the maximum radial (proportional) decrease in all inputs (increase in all outputs) which can cause an increase in the efficiency of a DMU similar to the most efficient DMUs in the evaluated set. In other words, it chooses the most favorable weights for each DMU under evaluation. For this reason, it is said that the method proposed by Charnes et al. (2000) measures the performance of the DMUs from the optimistic point of view. The efficiency measured in this way is called the best relative efficiency or the optimistic efficiency. Its value, in the input-oriented mode, is restricted to values less than or equal to one. If the value

of the optimistic efficiency of a DMU is equal to one, that DMU is said to be DEA-efficient or optimistic efficient; otherwise, it is said to be DEA-non-efficient or optimistic non-efficient. It is usually held that optimistic efficient DMUs have a better performance than optimistic nonefficient DMUs.

On the other hand, another approach has been proposed by Parkan and Wang (2000) that measures the performances of DMUs from the pessimistic point of view. This approach selects the most unfavorable weights for each DMU under evaluation. The efficiency measured from the pessimistic point of view is called the worst relative efficiency or the pessimistic efficiency. Its value, in the input-oriented mode, is restricted to values greater than or equal to one. If the value of the pessimistic efficiency of a DMU is equal to one, that DMU is said to be pessimistic inefficient or DEA-inefficient; otherwise, it is said to be pessimistic non-inefficient or DEA-noninefficient. It is usually believed that pessimistic inefficient DMUs have a worse performance than pessimistic non-inefficient DMUs.

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Optimistic and pessimistic efficiencies measure two extremes of the performance of each DMU. Any evaluation method that considers only one of these two efficiencies is bound to be biased. For determination of the overall performance of each DMU, both of them should be considered simultaneously.

Entani et al. (2002) proposed a pair of DEA models with interval efficiencies that are measured from both optimistic and pessimistic points of view. Their pair of DEA models was first developed for crisp data and was then extended to interval and fuzzy data. These models are theoretically able to work with interval and fuzzy data, but they have some drawbacks. Namely, these models use only one input and one output for computation of lower bound efficiency regardless of the number of inputs and outputs in the problem. As a result, their model leads to loss of input and output information of the DMU under consideration. Furthermore, their DEA models use variable production frontiers for measurement of efficiency intervals of various DMUs. Before Entani et al. (2002), Doyle et al. (1995) were the first to study DMU performance from both optimistic and pessimistic perspectives. They obtained three pairs of models for evaluation of the upper and lower bounds for crisp data. Their models have a structure similar to Entani et al.'s (2002) models.

Wang and Yang (2007) presented a pair of bounded DEA models for crisp data. The pair of bounded DEA models makes the most use of all input and output information and measures the best and worst relative efficiencies of each DMU by including a virtual DMU called the anti-ideal DMU. The anti-ideal DMU is a DMU which consumes the most input only to produce the lowest amount of output, and when there is a zero value in each output, it has efficiency zero. As a result, their pair of DEA models faces problems in computation of the overall efficiency interval of each DMU. Recently, Azizi and Wang developed improved bounded DEA models that measure DMU efficiencies under any circumstances.

Wang et al. (2008) developed a pair of interval DEA models for dealing with crisp data. Interval DEA models determine the overall efficiency interval of each DMU using the pessimistic efficiency of a virtual DMU called anti-ideal DMU, which consumes the most amount of inputs and produces the least amount of outputs, and compute the optimistic and pessimistic efficiencies of each DMU. Azizi and Jahed (2011) pointed out that their interval DEA models face problems in determining the lower bound interval efficiency when there are zero values in each input. To fix this drawback, they developed a pair of improved interval DEA models that assess the overall efficiency of DMUs under any conditions.

Wang and Luo (2006) combined the Technique for Order Preference by Similarity to Ideal Solution (TOPSIS), which is a technique in multiple attribute decision making, with DEA. They defined two virtual DMUs, called the ideal DMU and the anti-ideal DMU, and built two DEA models for computation of the best and the worst relative efficiencies. Combining these two distinct efficiencies, they obtained a relative closeness index which was used as a basis for ranking DMUs. Their proposed DEA models have two basic drawbacks: (1) In most cases, their DEA models use constant weights for all DMUs, and (2) when there are zero values in every input and in every output, their DEA models are infeasible.

Azizi and Fathi Ajirlu (2010) used the optimistic efficiency of the ideal DMU and the pessimistic efficiency of the anti-ideal DMU for determination of the lower bound of the overall efficiency interval for crisp data. Their DEA models also face difficulties in determining the lower bound of the overall efficiency interval when there are zero values in every input and in every output.

Amirteimoori (2007) presented an efficiency measure using two ideal and anti-ideal indices that are formed based on the efficiency and inefficient DEA frontiers. The logic of these two indices is maximization of the weighted

 $L₁$ distance from a particular DMU to the efficient and inefficient DEA frontiers.

Wang et al. (2007) proposed a geometric average efficiency measure for evaluation of the overall performance of each DMU. The geometric average efficiency combines both measures of optimistic efficiency and pessimistic efficiency for each DMU and as such, is a more comprehensive measure of performance. Recently, Wang and Chin (2009) proposed a new overall performance measure for DMU ranking. Their proposed DEA approach considers the optimistic and pessimistic efficiencies of the DMUs simultaneously. The overall performance measure defined by these authors considers not only the magnitude of the two efficiencies, but also their direction. Consequently, it appears to be more comprehensive than the geometric average efficiency of Wang et al. (2007).

According to this review of the literature, it is evident that considerable attempts should be made for assessment of the overall performance of the DMUs, since the overall performance of the DMUs should be considered in the more general case of imprecise data. Of course, Entani et al. (2002) have studied the DEA structure in the presence of interval data. However, their DEA models have some drawbacks that will be presented in Section 3. Besides, the main focus of the present paper, under the general topic of DEA, will be simultaneous consideration of crisp, ordinal, and interval data for measurement of the overall performance of the DMUs. The upper bound of overall efficiency interval is obtained from the optimistic perspective, i.e. according to the most favorable condition of each DMU and using the most favorable weights. Its lower bound is determined from the pessimistic point of view, i.e. according to the most unfavorable condition of each DMU and by using the most unfavorable weights. The overall efficiency interval provides the decision maker with all possible values of efficiency which reflect various perspectives. Three numerical examples will be used for illustrating the proposed method.

This article is organized as follows. In Section 2, we present the basic DEA models for measurement of the best and the worst relative efficiencies of the DMUs. In Section 3, first we will review Entani et al.'s (2002) DEA models and then we will present the adjusted pessimistic efficiency interval. The numerical examples will be discussed in Section 4. Section 5 will conclude the paper.

2. Interval DEA Models for Measurement of the Best and the Worst relative Efficiencies

2.1. Interval DEA models for measurement of the best relative efficiencies of DMUs

In DEA analysis, it is usually assumed that there are *n* production units that consume *m* different inputs and produce *s* different outputs. Specifically, the *j* th production unit consumes x_{ij} units of input i ($i = 1,...,m$) and produces y_{ri} units of output *r* ($r = 1, \ldots, s$). In interval DEA, it is assumed that some exact values of input x_{ij} and output y_{ri} are not known. It is only known that they are in the range of the upper and lower bounds specified by intervals $[x_{ij}^L, x_{ij}^U]$ x_{ij}^L, x_{ij}^U and $[y_{rj}^L, y_{rj}^U]$ y_{rj}^L , y_{rj}^U], and each DMU has a positive lower bound input and a positive lower bound output.

To deal with such an uncertain situation, Wang et al. (2005) presented the following pair of linear programming (LP) models that measure the best relative efficiencies of DMUs:

min
$$
\theta_o^U = \sum_{i=1}^m v_i x_{io}^U
$$

s.t. $\sum_{i=1}^s u_i y_{rj}^U - \sum_{i=1}^m v_i x_{ij}^L \le 0, \quad j = 1,...,n,$ (1)

$$
\sum_{r=1}^{r=1} u_r y_{ro}^L = 1,
$$

$$
u_r, v_i \ge \varepsilon, \quad r = 1, ..., s; \quad i = 1, ..., m.
$$

min
$$
\theta_o^L = \sum_{i=1}^m v_i x_{io}^L
$$

s.t. $\sum_{r=1}^s u_r y_{rj}^U - \sum_{i=1}^m v_i x_{ij}^L \le 0, \quad j = 1,..., n,$
 $\sum_{r=1}^s u_r y_{ro}^U = 1,$
 $u_r, v_i \ge \varepsilon, \quad r = 1,..., s; \quad i = 1,..., m.$ (2)

where DMU_o is the DMU under evaluation, v_i ($i = 1,...,m$) and u_r ($r = 1,...,s$) are decision variables, and ε is the non-Archimedean infinitesimal. θ_0^U is the best relative efficiency under the most favorable conditions and θ_o^L is the best relative efficiency under the most unfavorable conditions for DMU_o. They form the optimistic efficiency interval $[\theta_o^L, \theta_o^U]$. If there is a set of positive weights u_r^* ($r = 1,...,s$) and v_i^* ($i = 1,...,m$) that make $\theta_o^{U^*} = 1$, then DMU_o is called DEA-efficient or optimistic efficient; otherwise, it is called DEA-nonefficient or optimistic non-efficient.

2.2. Interval DEA models for measurement of the worst relative efficiencies of DMUs

The input-oriented framework, which is based on the set of input requirement and its inefficiency frontier, tries to increase input values as much as possible, while keeping the output at most at its current level. This emphasizes the fact that output is kept constant and input values are increased proportionally, until the inefficient production frontier is obtained. DEA estimator for inefficient production possibility set is called the pessimistic efficiency or the worst relative efficiency. For a particular DMU, such as DMU_o, relative efficiencies can be calculated form the following pessimistic DEA models Azizi et al (2011):

$$
\max \quad \varphi_o^L = \sum_{i=1}^m v_i x_{io}^L
$$
\n
$$
\text{s.t.} \quad \sum_{r=1}^s u_r y_{rj}^L - \sum_{i=1}^m v_i x_{ij}^U \ge 0, \quad j = 1, ..., n, \quad (3)
$$
\n
$$
\sum_{r=1}^s u_r y_{ro}^U = 1,
$$
\n
$$
u_r, v_i \ge \varepsilon, \quad r = 1, ..., s; \quad i = 1, ..., m.
$$

max
$$
\varphi_o^U = \sum_{i=1}^m v_i x_{io}^U
$$

s.t. $\sum_{r=1}^s u_r y_{rj}^L - \sum_{i=1}^m v_i x_{ij}^U \ge 0, \quad j = 1,...,n,$
 $\sum_{r=1}^s u_r y_{ro}^L = 1,$
 $u_r, v_i \ge \varepsilon, \quad r = 1,...,s; \quad i = 1,...,m.$ (4)

In models (3) and (4), φ_o^L is the worst relative efficiency under the most unfavorable conditions and φ ^{*u*} is the worst relative efficiency under the most favorable conditions for DMU_o. They give the pessimistic efficiency interval $[\varphi_o^L, \varphi_o^U]$ for DMU_o . When there is a set of positive weights u_r^* ($r = 1,...,s$) and v_i^* ($i = 1, \ldots, m$) that satisfy $\varphi_o^{L^*} = 1$, we say that DMU_o is DEA-inefficient or pessimistic inefficient; otherwise, we say that DMU_o is DEA-non-inefficient or pessimistic non-inefficient.

3. The Overall Efficiency Interval

3.1. A review of Entani et al.'s DEA models

To provide an overall efficiency interval for each DMU, Entani et al. (2002) proposed the following mathematical programming model for determination of the upper bound of the overall efficiency interval of DMU_o:

$$
\max \Theta_o^U = \max_{y_{ij}, x_{ij}} \frac{\sum_{i=1}^m v_i x_{io} / \sum_{r=1}^s u_r y_{ro}}{\max_j \left\{ \sum_{i=1}^m v_i x_{ij} / \sum_{r=1}^s u_r y_{rj} \right\}}
$$
(5)
s.t. $u_r, v_i \ge 0$, $r = 1,..., s$; $i = 1,..., m$,

where $x_{ij} \in [x_{ij}^L, x_{ij}^U]$ $x_{ij} \in [x_{ij}^L, x_{ij}^U]$ and $y_{ij} \in [y_{ij}^L, y_{ij}^U]$. To obtain the optimal value of model (5), Entani et al. (2002) simplified model (5) to model (6):

max
$$
\Theta_o^U = \sum_{i=1}^m v_i x_{i_o}^U / \sum_{r=1}^s u_r y_{r_o}^L
$$

\ns.t. max
$$
\begin{cases}\n\max_{j \neq o} \left\{ \sum_{i=1}^m v_i x_{i_j}^L / \sum_{r=1}^s u_r y_{r_j}^U \right\} \\
\sum_{i=1}^m v_i x_{i_o}^U / \sum_{r=1}^s u_r y_{r_o}^L\n\end{cases} = 1,
$$
\n
$$
u_r, v_i \ge 0, \quad r = 1, ..., s; \quad i = 1, ..., m,
$$
\n(6)

The upper bound of overall efficiency interval for DMU_o can be found using the following LP model:

max
$$
\Theta_o^U = \sum_{i=1}^m v_i x_{io}^U
$$

\ns.t. $\sum_{r=1}^s u_r y_{rj}^U - \sum_{i=1}^m v_i x_{ij}^L \ge 0, \quad j = 1,...,n; j \ne 0$
\n $\sum_{r=1}^s u_r y_{ro}^L - \sum_{i=1}^m v_i x_{io}^U \ge 0$ (7)
\n $\sum_{r=1}^s u_r y_{ro}^L = 1,$
\n $u_r, v_i \ge 0, \quad r = 1,...,s; \quad i = 1,...,m.$

In models (6) and (7), the upper bounds of input intervals x_{io}^U and the lower bounds of output intervals y_{ro}^L are used for DMU_o, and lower bounds of input intervals x_{ij}^L and the upper bounds of output intervals y_{ri}^U are used for other DMUs. The main drawback of using different sets of constraints for efficiency measurement of DMUs is the lack of possibility of comparison between efficiencies, since different production frontiers have been used in the process of efficiency measurement. We use LP model (4) for obtaining the upper bound of overall efficiency interval for each DMU. To obtain the lower bound of overall efficiency interval for DMU_s, Entani et al. (2002) proposed the following mathematical programming model for DMU_o:

$$
\min \quad \phi_o^L = \min_{y_g, x_{ij}} \frac{\sum_{i=1}^m v_i x_{io} / \sum_{r=1}^s u_r y_{ro}}{\max_j \left\{ \sum_{i=1}^m v_i x_{ij} / \sum_{r=1}^s u_r y_{rj} \right\}}
$$
\ns.t. $u_r, v_i \ge 0, \quad r = 1, ..., s; \quad i = 1, ..., m,$ \n
$$
(8)
$$

For obtaining the optimal value of Model (8), Entani et al. (2002) converted model (8) into model (9):

$$
\begin{aligned}\n\min \quad & \phi_o^L = \sum_{i=1}^m v_i x_{i_o}^L / \sum_{r=1}^s u_r y_{i_o}^U \\
\text{s.t.} \quad & \max \left\{ \frac{\max\left\{ \sum_{j \neq o}^m v_i x_{ij}^U / \sum_{r=1}^s u_r y_{i_j}^L \right\} \right\}}{\sum_{i=1}^m v_i x_{i_o}^L / \sum_{r=1}^s u_r y_{i_o}^U} \right\} = 1, \quad (9) \\
& u_r, v_i \ge 0, \quad r = 1, \dots, s; \quad i = 1, \dots, m,\n\end{aligned}
$$

In model (9), the lower bounds of input intervals x_{io}^L and the upper bounds of output intervals y_{ro}^U have been used for DMU_o, while the upper bounds of input intervals x_{ij}^U and the lower bounds of output intervals y_{rj}^L have been used for other DMUs. Model (9) cannot be converted into an LP model. To obtain the optimal value of model (9), Entani et al. (2002), after assuming $\sum_{i=1}^{m} v_i x_{ij}^U / \sum_{r=1}^{s} u_r y_{rj}^L = 1$ *r* $\sum_{i=1}^{L}$ *m i* $v_i x_i^U / \sum_{r=1}^s u_r y_{rj}^L = 1$ for each DEA-inefficient DMU, divided model (9) into k_1 sub-optimization problems $j = J_1, \dots, J_{k_1}$, where k_1 is the number of DEA-inefficient units, and J_1, \ldots, J_{k_1} are units that are DEA-inefficient:

$$
\min \quad \phi_{oj}^L = \sum_{r=1}^s u_r y_{r}^L / \sum_{i=1}^m v_i x_{i_o}^U
$$
\n
$$
\text{s.t.} \quad \sum_{r=1}^s u_r y_{rj}^U / \sum_{i=1}^m v_i x_{ij}^L = 1,
$$
\n
$$
u_r, v_i \ge 0, \quad r = 1, \dots, s; \quad i = 1, \dots, m,
$$
\n
$$
(10)
$$

Model (10) can be simplified by converting into k_1 LP models as follows:

$$
\min \quad \phi_{oj}^{L} = \sum_{r=1}^{s} u_r y_{r}^{L}
$$
\n
$$
\text{s.t.} \quad \sum_{r=1}^{s} u_r y_{rj}^{U} - \sum_{i=1}^{m} v_i x_{rj}^{L} = 0,
$$
\n
$$
\sum_{i=1}^{m} v_i x_{r}^{U} = 1,
$$
\n
$$
u_r, v_i \ge 0, \quad r = 1, ..., s; \quad i = 1, ..., m,
$$
\n(11)

Assume that $\phi_{oj}^{L^*}$ is the optimal objective function value for model (11). Therefore, the lower-bound efficiency of DMU_c is finally computed as follows:

$$
\phi_o^{L^*} = 1 \wedge \min_{j \neq o} {\{\phi_{oj}^{L^*}\}}
$$
\n(12)

where $a \wedge b = \min\{a, b\}$. Accordingly, the overall efficiency interval for DMU_o is denoted as $[\phi_o^{L^*}, \Theta_o^{U^*}]$, where $\Theta_{\alpha}^{U^*}$ is the optimal value of the upper-bound model (7).

Model (10) has only one fractional constraint. Therefore, regardless of the number of inputs and outputs in the problem under consideration, only two decision variables can be non-zero, one for the input weight and the other for the output weight. As such, Entani et al.'s (2002) DEA models measure the optimistic efficiency of each DMU by taking into account only one input and one output. Furthermore, an important feature of measurement of the optimistic efficiency of DMUs is identification of DEA-efficient DMUs, which have the best performance among the DMUs from the optimistic point of view and form the efficiency frontier. Consequently, the decision maker can know which DMUs are DEA-efficient and which DMUs are not. In this regard, model (11) is not able to accurately identify DEA-efficient DMUs and the efficiency frontier. Compared with model (11), model (2) is able to accurately identify the optimistic efficient units and the efficiency frontier.

The pessimistic efficiency score is the opposite of the optimistic efficiency score. It is a score that each DMU obtains in its most unfavorable situation (or the most favorable situation) using *the most unfavorable weights*. Theoretically, the best and the worst relative efficiencies should be calculated in a common range and should form an interval for each DMU. For example, they can be measured in the interval $[\beta,1]$, where $\beta > 0$ is a parameter. In the nest section, we will find a suitable value for β .

3.2. Adjustment of the worst relative efficiencies

Theoretically, the best and the worst relative efficiencies should form an interval. For this purpose, the best relative efficiencies obtained from model (1) and (2) must be adjusted. Suppose that β ($0 < \beta \le 1$) is the adjustment factor. Then the adjusted best relative efficiencies can be written as $\beta \theta_j^* = \beta [\theta_j^{L^*}, \theta_j^{U^*}] = \hat{\theta}_j^* = [\hat{\theta}_j^{L^*}, \hat{\theta}_j^{U^*}]$ (*j* = 1,…, *n*), which should satisfy $\hat{\theta}_j^* = \beta \theta_j^* = [\hat{\theta}_j^{L^*}, \hat{\theta}_j^{U^*}] \le \varphi_j^* = [\varphi_j^{L^*}, \varphi_j^{U^*}]$ $j = 1, ..., n$, or $\beta \le \min_{j=1,...,n} {\{\phi_j^{L^*}/\theta_j^{U^*}\}}$ $\beta \le \min_{j=1,...,n} {\{\phi_j^{L^*}/\theta_j^{U^*}\}}$. Then assuming max $\{\theta_i^{U^*}\}$ $1, \ldots$ $\theta_{\max}^{U^*} = \max_{j=1,...,n} \{\theta_j^U\}$ $=\max_{j=1,...,n} \{\theta_j^{U^*}\}\$ and $\varphi_{\min}^{L^*} = \min_{j=1,...,n} \{\varphi_j^{L^*}\}\$ $1, \ldots$ $\varphi_{\min}^{L^*} = \min_{j=1,\dots,n} {\varphi_j^{L^*}}$, we have $\mathcal{P}_{\text{min}}^{L^*} / \theta_{\text{max}}^{U^*}$ $1, \ldots$ * $1, \ldots$ * Λ ^{*} $\min_{j=1,...,n} \{ {\phi}^{L^*}_j / {\theta}^{U^*}_j \} \ge \min_{j=1,...,n} \{ {\phi}^{L^*}_j / \max_{j=1,...,n} \{ {\theta}^{U^*}_j \} = {\phi}^{L^*}_{\min} / {\theta}^{U}_{\min}$ If we set $\beta = \varphi_{\min}^{L^*} / \theta_{\max}^{U^*}$, then we will be guaranteed that $\beta \le \min_{j=1,...,n} {\{\varphi_j^{L^*}/\theta_j^{U^*}\}}$ $\beta \le \min_{j=1,\dots,n} {\{\varphi_j^{L^*}/\theta_j^{U^*}\}}$. Since the value of β is not zero, we can compute the best performance of DMUs in the range of the interval $[\beta,1]$ using the following models:

$$
\min \quad \psi_o^U = \frac{\sum_{i=1}^m v_i x_{io}^U}{\sum_{r=1}^s u_r y_{ro}^L}
$$
\n
$$
\text{s.t.} \quad \frac{\sum_{i=1}^m v_i x_{ij}^L}{\sum_{r=1}^s u_r y_{rj}^U} \ge \beta, \quad j = 1, ..., n, \quad (13)
$$
\n
$$
u_r, v_i \ge \varepsilon, \quad r = 1, ..., s; \quad i = 1, ..., m.
$$

$$
\min \quad \psi_o^L = \frac{\sum_{i=1}^m v_i x_{io}^L}{\sum_{r=1}^s u_r y_{ro}^U}
$$
\n
$$
\text{s.t.} \quad \frac{\sum_{i=1}^m v_i x_{ij}^L}{\sum_{r=1}^s u_r y_{rj}^U} \ge \beta, \quad j = 1, ..., n, \quad (14)
$$
\n
$$
u_r, v_i \ge \varepsilon, \quad r = 1, ..., s; \quad i = 1, ..., m.
$$

Models (13) and (14) can be converted into the following two LP models:

$$
\begin{aligned}\n\min \quad & \psi_o^U = \sum_{i=1}^m v_i x_{io}^U \\
\text{s.t.} \quad & \sum_{r=1}^s u_r (\beta y_{rj}^U) - \sum_{i=1}^m v_i x_{ij}^L \le 0, \quad j = 1, \dots, n, \\
& \sum_{r=1}^s u_r y_{ro}^L = 1 \\
& u_r, v_i \ge \varepsilon, \quad r = 1, \dots, s; \quad i = 1, \dots, m.\n\end{aligned}\n\tag{15}
$$

$$
\begin{aligned}\n\min \quad & \psi_o^L = \sum_{i=1}^m \nu_i x_{io}^L \\
\text{s.t.} \quad & \sum_{r=1}^s u_r (\beta y_{rj}^U) - \sum_{i=1}^m \nu_i x_{ij}^L \le 0, \quad j = 1, \dots, n, \\
& \sum_{r=1}^s u_r y_{ro}^U = 1 \\
& u_r, v_i \ge \varepsilon, \quad r = 1, \dots, s; \quad i = 1, \dots, m.\n\end{aligned}\n\tag{16}
$$

Let $\psi_o^{U^*}$ and $\psi_o^{L^*}$ be the optimal values of models (15) and (16), respectively. Then they form a optimistic efficiency interval, which we denote by $[\psi_c^{L^*}, \psi_c^{U^*}]$. By repeating models (15) and (16) for each DMU, we can

obtain the best performance of *n* DMUs. We denote their optimistic efficiency interval by $[\psi_j^{L^*}, \psi_j^{U^*}]$ ($j = 1, ..., n$).

DMUs can be evaluated relatively from various perspectives, and any method that considers only one of the optimistic and pessimistic viewpoints will be a onesided approach. In order to obtain more trustworthy results, we must consider both perspectives simultaneously for scoring a problem. Thus, by integrating the optimistic efficiency interval and the pessimistic efficiency interval of the DMUs, we obtain a new interval of efficiency called *the overall efficiency interval*, in which the upper and lower bounds, i.e. the extreme values, are from different perspectives. As a result, for DMU*^j* , the overall efficiency interval is defined as $[\psi_j^{L^*}, \varphi_j^{U^*}]$ ($j = 1,...,n$). The overall efficiency interval represents all possible evaluations from various perspectives.

Regarding the overall efficiency interval $[\psi_o^{L^*}, \varphi_o^{U^*}]$, we have the following definitions.

Definition 1. DMU_o is called DEA-inefficient or pessimistic inefficient, if $\varphi_o^{U^*} = 1$, otherwise it is called DEA–non-inefficient.

Definition 2. DMU_o is called DEA-efficient or optimistic efficient, if $\psi_o^{L^*} = \beta$, otherwise it is called DEA–non-efficient.

Definition 3. DMU_o is called DEA-unspecified if and only if it is neither DEA-efficient nor DEA-inefficient.

Regarding DEA-unspecified units, we could say that they are always circumscribed between the efficient and inefficient frontiers Entani et al. (2002).

4. Illustrative Examples

In this section, we present three numerical examples taken from the literature in order to illustrate the simplicity and usefulness of the DEA method with efficient and inefficient frontiers in evaluating DMU performances. In all three examples, the value of the non-Archimedean infinitesimal is assumed to be $\varepsilon = 10^{-10}$.

Example 1. Consider a problem involving performance measurement in the manufacturing industry in which seven manufacturing businesses from various cities are evaluated for performance. The DEA inputs are *capital* and *labor*, and the DEA output is *gross output value*. All data are imprecise and therefore estimated. They are given as bounds, which are shown in Table 1. Data for this analysis are from Wang et al. (2005).

Table 1 Data for seven DMUs with two inputs and one output.

DMU	Inputs		Output	
	Capital	Labor	Gross Output	
			Value	
	[564403,	[674111]	[806549]	
	6217551	7432811	8660631	
\overline{c}	[614371,	[685943,	[917507,	
	6696651	7423451	9854241	
3	[762203]	[762207]	[1117142]	
	7984271	8056771	1195562]	
4	[862016]	[779894,	[1206179, 1]	
	9370441	8464961	2610311	
5	[1016898,	[799714,	[1381315,	
	10826621	8771371	14625431	
6	[1164350,	[807172]	[1497679,	
	12679701	8894161	16527871	
7	[1731916]	[818090,	[1702249]	
	18160081	8957461	18126551	

Using interval DEA models (1) – (4) and (15) and (16) , we obtain the scoring results listed in Table 2. From Table 2, it can be seen four DMUs, namely DMU_2 , DMU_3 , DMU_6 , and DMU_7 , are DEA-efficient according to model (1). These four DEA-efficient units collectively form the efficiency frontier. Also, from the pessimistic efficiency perspective, two DMUs, namely $DMU₁$ and $DMU₂$, are DEA-inefficient. Together, they form an inefficiency frontier. Furthermore, units DMU_4 and DMU_s are DEA-unspecified units. Using Table 2, the value of β is obtained as $\beta = \varphi_{\text{max}}^{L^*} / \theta_{\text{min}}^{U^*} = 0.7325/1.2365 = 0.5924$.

Table 2

Interval efficiencies for the seven DMUs.

DMU	Optimistic efficiency	Pessimistic efficiency	Adjusted optimistic	Overall efficiency
	interval	interval	efficiency	interval
		$(\{\varphi_i^{\scriptscriptstyle L^*},\varphi_i^{\scriptscriptstyle U^*}\})$	interval	
	$[\theta_i^{L^*}, \theta_i^{U^*}]$		$([\psi_i^{L^*}, \psi_j^{U^*}])$	$[\psi_i^{L^*},\theta_j^{U^*}]$
$\mathbf{1}$	[1.0453]	[0.8450]	[0.6192,	[0.6192]
	1.2365]	1.0000]	0.7325]	1.0000]
\overline{c}	[1.0000,	[0.7835]	[0.5924,	[0.5924]
	1.1689]	0.9143]	0.6925]	0.9143]
3	[1.0000,	[0.7632]	[0.5924,	[0.5924,
	1.1230]	0.8589]	0.6653]	0.8589]
$\overline{4}$	[1.0406]	[0.7849]	[0.6164]	[0.6164]
	1.1821]	0.8915]	0.70031	0.8915]
5	[1.0185,	[0.7562]	[0.6033]	[0.6033]
	1.1571]	0.8620]	0.6855]	0.8620]
6	[1.0000,	[0.7325]	[0.5924,	[0.5924,
	1.2052]	0.88391	0.71391	0.88391
7	[1.0000,	[0.8956]	[0.5924,	[0.5924,
	1.1542]	1.0000]	0.6837]	1.0000]

The upper bound of the overall efficiency interval is computed from the optimistic point of view, i.e. according to the most favorable conditions for each DMU and based on the most favorable weights. The lower bound of the overall efficiency interval is computed from the

pessimistic point of view, i.e. according to the most unfavorable conditions for each DMU and based on the most unfavorable weights. The overall efficiency interval comprises all possible evaluations from various perspectives. As such, the overall efficiency interval provides the decision maker with all possible values of efficiency that reflect various perspectives.

Example 2. Consider the example discussed by Cooper et al. (1999). We have five DMUs that use two inputs, one crisp and the other interval, and produce two outputs, one crisp and the other ordinal. The data set is shown in Table 3.

Tab

Imprecise data and ordinal data converted for five DMUs.

DMU	Inputs		Outputs		Converted
	x_{1i}	x_{2i}	y_{1i}	y_{2i}	ordinal data
	(exact)	(interval)	(exact)	$($ ordinal l ¹ $)$	
1	100	[0.6, 0.7]	2000	4	[0.3456,
					0.8333]
\overline{c}	150	[0.8,	1000	2	[0.2400,
		0.91			0.5787]
3	150	[1, 1]	1200	5	[0.4147]
					1.0000]
4	200	[0.7, 0.8]	900	1	[0.2000,
					0.4823]
5	200	[1, 1]	600	3	[0.2880,
					0.6944]

1 ranking, such that $5 \equiv$ highest rank, ..., $1 \equiv$ lowest rank ($y_{23} > y_{21} > ... > y_{24}$.

For conversion of ordinal preference information into interval data, we used the approach proposed by Wang et al. (2005). For this example, the preference intensity parameter and the ratio parameter about the strong ordinal preference information were determined (or estimated) as $\chi_2 = 1.2$ and $\sigma_2 = 0.2$, respectively. Using the technique described in Wang et al. (2005), we can obtain an interval estimate for the second output of each DMU, which is shown in the last column of Table 3.

For the input and output data of Table 3, interval DEA models (1) and (2) are executed for each DMU, to obtain their optimistic efficiency interval. The results are shown in Table 4. In Table 4, it is evident that only one DMU, i.e. DMU₁, is DEA-efficient and determines the efficiency frontier. Also, by running interval DEA models (3) and (4) for each DMU, we obtain the pessimistic efficiency interval for the five DMUs. From the pessimistic point of view, two DMUs, i.e. DMU, and DMU_5 , are DEA-inefficient. Furthermore, we determine the adjusted optimistic interval efficiencies of the five DMUs by determining the value of β and by running interval DEA models (15) and (16) for each DMU. Using the pessimistic efficiency intervals and the adjusted optimistic efficiency intervals of the five DMUs, we obtain the overall performance score, i.e. the overall efficiency interval, of each DMU. The results are shown in Table 4.

Table 4

Interval efficiencies for the five DMUs.					
DMU	Optimistic efficiency interval $([\theta_i^{L^*}, \theta_i^{U^*}]$	Pessimistic efficiency interval $[\varphi_i^{L^*}, \varphi_i^{U^*}]$	Adjusted optimistic efficiency interval $([\psi_i^{L^*}, \psi_j^{U^*}])$	Overall efficiency interval $[\psi_i^{L^*}, \theta_i^{U^*}]$	
	1.0000.	[0.2033]	[0.0422]	[0.0422]	
	1.0000]	0.5064]	0.04221	0.50641	
\overline{c}	[1.9199]	[0.4800,	[0.0810,	[0.0810,	
	3.0000]	0.9549]	0.1266	0.9549]	
3	[1.2500,	[0.5000,	[0.0527,	[0.0527,	
	2.5000]	0.6608]	0.1055]	0.6608]	
4	[2.0157]	[0.6667]	[0.0851,	[0.0851,	
	2.9630]	1.0000]	0.1250]	1.0000]	
5	[2.0000]	[1.0000]	[0.0844,	[0.0844,	
	4.8223]	1.0000]	0.2035]	1.0000]	

It should be noted that Entani et al. (2002) have developed an approach for finding efficiency intervals for crisp data, interval data, and fuzzy data. However, they have not described the method of computation of the overall efficiency interval. Besides, they have not considered the overall efficiency interval for a mixture of crisp data, interval data, and fuzzy data. Furthermore, their upper and lower bound DEA models are not able to accurately identify DEA-efficient and DEA-inefficient units.

Example 3. Consider the problem of performance measurement of a set of 20 branches of a commercial bank in Taiwan (DMUs). Each branch was evaluated for three inputs (*total deposits*, *interest expenses*, and *non-*

Table 5

Inputs and outputs data for 24 bank branches.

interest expenses) and three outputs (*total loans*, *interest income*, and *non-interest income*). The data set for this analysis was borrowed from Kao and Liu (2004).

Tables 5 and 6 show the interval inputs and the interval outputs for these DMUs. Furthermore, Table 7 presents overall efficiency interval scores, optimistic efficiency intervals, pessimistic efficiency intervals, and adjusted optimistic efficiency intervals for these DMUs according to models (1) – (4) and (15) and (16) .

When we evaluate bank branches from the optimistic point of view, 11 DMUs achieve the efficiency score of 100% under the best conditions. These 11 DMUs are classified as optimistic efficient and are considered to have the best performance. (If they are in the best production conditions, they are DEA-efficient; otherwise they are DEA–non-efficient.) However, when the bank branches are evaluated form the pessimistic point of view, 4 DMUs obtain the smallest efficiency scores under the worst conditions. These 4 DMUs are classified as pessimistic inefficient and are considered to have the worst performance. (If they are in the worst production conditions, they are DEA-inefficient; otherwise they are DEA–non-inefficient.) These 4 DMUs are candidates for bankruptcy. Evaluation of the investment risk is an important issue for financial institutes or business investors in bank branches. Consequently, financial institutes or individual investors must definitely evaluate the performance of bank branches before investing in the banking industry.

Now taking joint advantage of the set of upper bound of pessimistic efficiency and lower bound of optimistic efficiency, we can determine the lower bound of the overall efficiency interval for each DMU, obtaining the value $\beta = \varphi_{\min}^{L^*} / \theta_{\max}^{U^*} = 0.5738/1.6865 = 0.3402$. The overall efficiency intervals for the DMUs are shown in

Table 7.

Consequently, our study makes it possible to provide the bank branch managers with more useful resources of information. It's for this reason that our study is necessary and desirable for dealing with imprecise data.

Table 7

Interval efficiencies of the 24 bank branches

DMU	Optimistic efficiency interval	Pessimistic efficiency interval	Adjusted optimistic efficiency interval	Overall efficiency interval
	$([\theta_i^{L^*}, \theta_i^{U^*}])$	$([\varphi_i^{L^*}, \varphi_i^{U^*}])$	$([\psi_i^{L^*}, \psi_i^{U^*}])$	$([\psi_i^{L^*}, \theta_i^{U^*}])$
	[1.0202, 1.1751]	[0.6102, 0.6976]	[0.3471, 0.3998]	[0.3471, 0.6976]
	[1.0302, 1.2639]	[0.6491, 0.7726]	[0.3497, 0.4300]	[0.3497, 0.7726]
	[1.0066, 1.2236]	[0.6431, 0.7947]	[0.3412, 0.4163]	[0.3412, 0.7947]
	[1.0000, 1.2418]	[0.5951, 0.7355]	[0.3402, 0.4225]	[0.3402, 0.7355]
	[1.0067, 1.2442]	[0.7903, 0.9767]	[0.3402, 0.4233]	[0.3402, 0.9767]
	[1.0000, 1.2359]	[0.7547, 0.9327]	[0.3402, 0.4204]	[0.3402, 0.9327]
	[1.1385, 1.3762]	[0.8420, 1.0000]	[0.3873, 0.4682]	[0.3873, 1.0000]
8	[1.4068, 1.6865]	[0.8390, 1.0000]	[0.4786, 0.5738]	[0.4786, 1.0000]
9	[1.0760, 1.2559]	[0.8595, 1.0000]	[0.3661, 0.4272]	[0.3661, 1.0000]
10	[1.0000, 1.2196]	[0.6635, 0.8085]	[0.3402, 0.4149]	[0.3402, 0.8085]
11	[1.0289, 1.2468]	[0.6128, 0.7574]	[0.3500, 0.4242]	[0.3500, 0.7574]
12	[1.0000, 1.2006]	[0.7618, 0.9398]	[0.3402, 0.4084]	[0.3402, 0.9398]
13	[1.0000, 1.2359]	[0.6646, 0.8214]	[0.3402, 0.4204]	[0.3402, 0.8214]
14	[1.0223, 1.2320]	[0.7734, 0.9287]	[0.3478, 0.4091]	[0.3478, 0.9287]
15	[1.1475, 1.4122]	[0.6959, 0.8601]	[0.3904, 0.4804]	[0.3904, 0.8601]
16	[1.0000, 1.2413]	[0.5738, 0.7159]	[0.3402, 0.4223]	[0.3402, 0.7159]
17	[1.0000, 1.2625]	[0.5883, 0.7843]	[0.3402, 0.4295]	[0.3402, 0.7843]
18	[1.0076, 1.2855]	[0.5813, 0.7574]	[0.3428, 0.4373]	[0.3428, 0.7574]
19	[1.0000, 1.2359]	[0.6869, 0.8489]	[0.3402, 0.4204]	[0.3402, 0.8489]
20	[1.0000, 1.1642]	[0.7807, 0.9648]	[0.3402, 0.3960]	[0.3402, 0.9648]
21	[1.1775, 1.3608]	[0.7132, 0.8223]	[0.4006, 0.4629]	[0.4006, 0.8223]
22	[1.0000, 1.2611]	[0.6077, 0.7664]	[0.3402, 0.4290]	[0.3402, 0.7664]
23	[1.3706, 1.6702]	[0.8137, 1.0000]	[0.4663, 0.5682]	[0.4663, 1.0000]
24	[1.0000, 1.1567]	[0.6535, 0.7523]	[0.3402, 0.3935]	[0.3402, 0.7523]

5. Conclusions

Measurement of DMU efficiencies is a complicated yet important decision-making problem which requires taking into account multiple quantitative and qualitative selection criteria. In the present article, we developed a new approach for dealing with interval data, ordinal preference data, and their mixtures in DEA. This approach provides more complete features for using the conventional DEA in working with imprecise data. The proposed method measures the efficiency of each DMU from both optimistic and pessimistic perspectives. This method leads to the creation of an upper bound and a lower bound for efficiency, which we call overall efficiency interval. The overall efficiency interval represents the whole range of imprecise efficiency for each DMU. Using the overall efficiency interval, we can further prioritize DMU performances. Compared with the overall efficiency interval developed by Entani et al. (2002), our proposed efficiency interval uses two constant and unified production frontiers (the efficient frontier and the inefficient frontier) as a benchmark for measurement of the efficiency of all DMUs. This causes our overall efficiency interval to be more logical, more reliable, and more usable. The overall efficiency interval not only describes the actual situation in more detail, it also diminishes the psychological pressure upon all DMUs under consideration and the people performing the evaluations. Three numerical examples were studied to illustrate the simplicity and utility of the proposed approach for measurement of DMU efficiencies.

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