

Super-Efficiency and Sensitivity Analysis in DEA for the Case of Exogenously Fixed Inputs

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1 Introduction

Data envelopment analysis is a non-parametric mathematical programming technique for measuring and evaluating the relative efficiencies of a set of entities, called decision making units (DMUs), with common inputs and outputs. Examples include agricultural productivity, banks, business firms, courts, hospitals, libraries, schools, universities, and others, including as well as the performance of countries, regions, etc. [3]. Being a non-parametric technique, DEA does not require a structural form for the production frontier and can handle multiple outputs quite easily. These attractive properties of the DEA approach have enabled its widespread use across many disciplines. See Seiford [13] and Emrouznejad et al. [8] for a survey of the literature on the development of DEA methodology since its introduction by Charnes et al. [4]. Standard data envelopment analysis implicitly assumes that all inputs and outputs are discretionary, i.e., can be controlled by the management of each DMU and varied at its discretion. However, there may exist exogenously fixed (or non-discretionary) factors that are beyond the control of a DMU's management, which also need to be considered [10,12,15]. On the other hand, data envelopment analysis identifies an empirical efficient frontier of a set of peer decision making units. In data envelopment analysis, extreme efficient units are of primary importance as they define the efficient frontier. The efficient frontier is characterized by the DMUs with an efficiency score of unity. An important problem in the DEA literature is that of ranking those DMUs called efficient by the DEA model, all of which have a score of unity. The super efficiency model involves executing the standard DEA models, but under the assumption that the DMU being evaluated is excluded from the reference set [1,5,6,14,16,18]. For the DEA sensitivity analysis based on the inverse of basis matrix, the reader is referred to [7,11]. Specifically, the super efficiency score in, say, the input-oriented model provides a measure of the proportional increase in the inputs for a DMU that could take place without destroying the "efficient" status of that DMU relative to the frontier created by the remaining DMUs.

The current research dedicated to apply the super-efficiency approach in data envelopment analysis (DEA) sensitivity analyses, when some inputs are non-discretionary. For this task, we first introduce the BM model [2], then by means of the modified BM model, in which the test DMU is excluded from the reference set, we determine what perturbations of data can be tolerated before frontier DMUs become nonfrontier. The sensitivity analysis approach developed in this paper can be applied to all DMUs on the entire frontier. This study attempts to generalize the results in [9] to a situation where variable percentage data changes are assumed for a test DMU and for the remaining DMUs. We consider the same worst-case analysis as in [9]. It is shown that a particular super-efficiency score can be decomposed into two data perturbation components of a particular test DMU and the remaining DMUs. Necessary and sufficient conditions for preserving a DMU's BM-efficiency classification are developed when variable percentage data changes are applied to all DMUs. Note that in this paper we assume that the factors are either fully discretionary or fully non-discretionary. Also we assume that none of the models have non-discretionary outputs.

The layout of this article is as follows. In Section 2, basic definitions, that will be used in the succeeding sections, are given. In Section 3 we will discuss super-efficiency and sensitivity analysis in the BM model. Section 4 is the main part of this study where we will discuss simultaneous changes in all the discretionary data. Section 5 provides a numerical example from DEA, where some of the ideas of the paper are illustrated. The last section provides a summary and some future research directions.

2 Definitions

The following standard notations and definitions are used in the paper. Consider a set of *n* DMUs, where each DMU_j ($j = 1, 2, \ldots, n$) uses *m* different discretionary inputs, x_{ij} , $(i = 1, 2, \ldots, m)$, and *p* different non-discretionary inputs z_{ij} , $(i = 1, 2, \ldots, p)$, to produce *s* different outputs, y_{rj} , $(r = 1, 2, \ldots, s)$. We assume that the data set are positive.

Assuming constant returns to scale, the BM model to evaluate the efficiency of any DMU **–** in the input-oriented case **–** is given by the following modification of the CCR model:

$$
\begin{aligned}\n\frac{\mathbf{BM_{CCR}}}{\theta_{ND}^{\text{CCR}*}} &= \min \theta \\
s.t. \sum_{j=1}^{n} x_{ij} \lambda_j \leq \theta x_{io}, \quad i \in \mathbf{D} \\
\sum_{j=1}^{n} z_{ij} \lambda_j \leq z_{io} \quad i \in \mathbf{ND} \\
\sum_{j=1}^{n} y_{rj} \lambda_j \geq y_{ro}, \quad r = 1, 2, \dots, s \\
\lambda_j \geq 0, \quad j = 1, 2, \dots, n.\n\end{aligned}
$$
\n(1)

Here the symbols **D** and **ND** refer to *Discretionary* and *Non-Discretionary*, respectively. Note that the variable *θ* is not applied to the non-discretionary input constraints, because these values are exogenously fixed and it is therefore not possible to vary them at the discretion of management. This is recognized by entering all z_{io} , $i \in \mathbf{ND}$, at their fixed (observed) values. If we add an additional convex constraint of $\sum_{j=1}^n\lambda_j=1$ to (1), we obtain an input-oriented VRS model. Based on the optimal solution of Model (1), we define a DMU as being BM_{CCR} -efficient as follows:

Definition 1. (BM_{CCR}-efficiency) A DMU_{*o*} is BM_{CCR}-efficient if and only if it satisfies the following two conditions:

i. $\theta_{ND}^{CCR*}=1$,

ii. In all alternative optimal solutions, all discretionary slacks are zero.

Furthermore, if in all alternative optima, all non-discretionary slacks are zero, then DMU_o is called Full-BM_{CCR}efficient.

Definition 2. (Extreme BM_{CCR}-efficient) A BM_{CCR}-efficient DMU_{*o*} is extreme BM_{CCR}-efficient if and only if it has a unique optimal solution in Model (1).

3 Super-efficiency and sensitivity analysis in the BM model

As in Charnes et al. [5], the DMUs can be partitioned into two groups: frontier DMUs and non-frontier DMUs. Furthermore, by Definition 1 the frontier DMUs consist of DMUs in set E (extreme Full-BM_{CCR}-efficient), set E' (Full-BM_{CCR}-efficient but not an extreme point), set E'' (BM_{CCR}-efficient but with non-zero non-discretionary slacks) and set F (weakly BM_{CCR} -efficient or frontier point but with non-zero discretionary slacks).

We may use a super-efficiency non-discretionary DEA model to identify the classification of DMU*o*. That is,

$$
\begin{aligned}\n\frac{\text{BMSuper}}{\theta_{\text{ND}}^{\text{super}}} &= \min \theta \\
s.t. \quad & \sum_{j=1, j \neq o}^{n} \lambda_j x_{ij} \leq \theta x_{io}, \quad i \in \mathbf{D} \\
& \sum_{j=1, j \neq o}^{n} \lambda_j z_{ij} \leq z_{io}, \quad i \in \mathbf{ND} \\
& \sum_{j=1, j \neq o}^{n} \lambda_j y_{rj} \geq y_{ro}, \quad r = 1, 2, \dots, s \\
& \sum_{j=1, j \neq o}^{n} \lambda_j y_{rj} \geq y_{ro}, \quad j = 1, 2, \dots, n; j \neq o\n\end{aligned}
$$
\n(2)

Suppose $\theta_{\texttt{ND}}^{sup*}$ is the optimal value to (2). Based on Hosseinzadeh et al. ([9], Theorem 4), we have:

i. $\theta_{\text{ND}}^{sup*} > 1$ or the [BM^{Super}] model is infeasible, if and only if DMU_{*o*} $\in E$,

ii.
$$
\theta_{\text{ND}}^{sup*} = 1
$$
 if and only if $DMU_o \in E' \cup E'' \cup F$, and

 ${\bf iii.}$ $\theta_{\texttt{ND}}^{sup*} < 1$ if and only if ${\rm DMU}_o$ is a non-frontier point or ${\rm DMU}_o$ belongs to the inefficient frontier.

Example 1. Consider a system with 6 units, each unit with two inputs and one output, where the first input is non-controllable. Table **1** exhibits the data and displays the BM-efficiency and the BM-super-efficiency of each unit.

DMU Input 1 Input 2 Output CCR*∗* ND *s −∗* 1 *s −∗* 2 *s* +*∗* **A** 2 3 1 1 0 0 0 1.5 **B** 4 1 1 1 0 0 0 1.4 **C** 6 1 1 1 2 0 0 1 **D** 6 3 1 0.3333 2 0 0 0.3333 **E** 2 4.5 1 0.6667 0 0 0 0.6667 **F** 3.5 1.5 1 1 0 0 0 1 \blacktriangleright Input 1 Input 2 Figure1: The diagram for Example 1. ▲ O 1 2 3 4 5 6 7 1 2 3 4 5 s**D E** s **C** s **B** s **A** s **F** \diagdown \diagdown ❅ ╲

Table 1: Results of the BM model for super efficiency.

The results presented in Table **1** indicate that **A** and **B** belong to set *E*, **F** belongs to set *E′* , **C** belongs to set *E′′* , and D , E are BM_{CCR} -inefficient.

θ sup∗ ND

4 Super-efficiency and non-discretionary data

The extreme DMUs in DEA are of primary importance as they define the DEA frontier. In this section we will discuss the stability of efficiency classification for such units. We consider the general case. That is, we are interested in whether DMU*^o* will still be a frontier point after data perturbations in all the DMUs. Our discussion is based on a worst-case scenario in which the BM_{CCR} -efficiency of DMU_o declines and the BM_{CCR} -efficiencies of all other DMU_j, $j \neq o$, improve.

Let $D_I \subseteq D$ and O denote, respectively, the discretionary input and output subsets in which we are interested. That is, we consider the data changes in set D_I and set O . Then the simultaneous data perturbations in discretionary inputs/outputs of DMU_o and all DMU_j, $j \neq o$, can be written as percentage data perturbation (variation):

$$
for DMUo \tfor DMUi(j \neq o):
$$

where (\hat{c}) represents adjusted data. Note that the data perturbations represented by α_i and $\tilde{\alpha}_i$ (or β_r and β_r) can be different for each $i \in \mathbf{D}_{\mathbf{I}}$ (or $r \in \mathbf{O}$).

Now we modify Model (2) to the following super-efficiency DEA model, when the same percentage changes of DMU_o and DMU_j , $j \neq o$, are assumed:

$$
\theta_{\text{ND}}^{\mathbf{I}^*} = \min_{\substack{n \\ j=1, j\neq o}} \theta_{\text{ND}}^{\mathbf{I}} \lambda_j x_{ij} \leq \theta_{\text{ND}}^{\mathbf{I}} x_{io}, \qquad i \in \mathbf{D}_{\mathbf{I}} \n\sum_{j=1, j\neq o} \lambda_j x_{ij} \leq x_{io}, \qquad i \notin \mathbf{D}_{\mathbf{I}} \n\sum_{j=1, j\neq o} \lambda_j z_{ij} \leq z_{io}, \qquad i \in \mathbf{ND} \n\sum_{j=1, j\neq o} \lambda_j y_{rj} \geq y_{ro}, \qquad r = 1, 2, ..., s \n\lambda_j \geq 0, j = 1, 2, ..., n; j \neq o
$$
\n(3)

By the optimal values of Models (2) and (3), we have:

Lemma 1. If Model (3) is feasible and $\theta_{\text{ND}}^{\text{Sup}^*} > 1$, then $\theta_{\text{ND}}^{\mathbf{I}^*} > 1$. Proof. See Hosseinzadeh et al. [9] for a proof.

Theorem 1. Let Model (3) be feasible and $\theta_{\text{ND}}^{\text{Supp}} > 1$. If $1 \leq \alpha_i \widetilde{\alpha}_i < \theta_{\text{ND}}^{\mathbf{I}^*}$, $i \in \mathbf{D}_{\mathbf{I}}$, then DMU_o remains as an extreme BM_{CCR} -efficient point. Furthermore, if equality holds for $\alpha_i \tilde{\alpha}_i = \theta_{ND}^{I^*}$, that is, $1 \leq \alpha_i \tilde{\alpha}_i \leq \theta_{ND}^{I^*}$, then DMU_o remains on the frontier, where $\theta_{ND}^{\mathbf{I}^*}$ is the optimal value to (3). In other words, any values of α_i and $\tilde{\alpha}_i$ within this range of variation for both x_{io} and x_{ij} will not affect the BM_{CCR}-efficiency status of DMU_{*o*}.

Proof. By Lemma 1, we have $\theta_{ND}^{\mathbf{I}^*} > 1$. Now suppose $1 \leq \alpha_i \widetilde{\alpha}_i < \theta_{ND}^{\mathbf{I}^*}$, but $DW_{\mathcal{O}}$ is not extreme BM_{CCR} efficient, when $\hat{x}_{io} = \alpha_i x_{io}$, $\hat{x}_{ij} = \frac{\hat{x}_{ij}}{\hat{\alpha}_i}$ $\overline{\alpha}_i^{i,j}$; $i \in \mathbf{D_I}$. Then Model (2) for evaluating $\text{DMU}_{\hat{o}}$ has an optimal solution $(\widehat{\theta}_{ND}^{Sup^*}, \widehat{\lambda}_j^*; j = 1, 2, \ldots, n, j \neq o)$ such that $\widehat{\theta}_{ND}^{Sup^*} \leq 1$. In the optimal solution, the constraints of Model (2) for evaluating $DMU_{\hat{o}}$ are as follows

$$
\begin{cases}\n\sum_{j=1,j\neq o}^{n} \hat{\lambda}_{j}^{*} \hat{x}_{ij} \leq \hat{\theta}_{ND}^{\text{Sup}^{*}} \hat{x}_{io}, & i \in \mathbf{D} \\
\sum_{j=1,j\neq o}^{n} \hat{\lambda}_{j}^{*} \hat{z}_{ij} \leq \hat{z}_{io}, & i \in \mathbf{ND} \\
\sum_{j=1,j\neq o}^{n} \hat{\lambda}_{j}^{*} \hat{y}_{rj} \geq \hat{y}_{ro}, & r = 1, 2, ..., s\n\end{cases}
$$

Or equivalently

$$
\sum_{\substack{j=1, j\neq o\\n}}^{n} \hat{\lambda}_{j}^{*} x_{ij} \leq \hat{\theta}_{\text{ND}}^{\text{Sup*}} \alpha_{i} \tilde{\alpha}_{i} x_{io} \leq \hat{\theta}_{\text{ND}}^{\text{Sup*}} \alpha_{k} \tilde{\alpha}_{k} x_{io}, \quad i \in \mathbf{D}_{\mathbf{I}}
$$
\n
$$
\sum_{\substack{j=1, j\neq o\\n}}^{n} \hat{\lambda}_{j}^{*} x_{ij} \leq \hat{\theta}_{\text{ND}}^{\text{Sup*}} x_{io} \leq x_{io}, \qquad i \notin \mathbf{D}_{\mathbf{I}}
$$
\n
$$
\sum_{\substack{j=1, j\neq o\\n}}^{n} \hat{\lambda}_{j}^{*} z_{ij} \leq z_{io}, \qquad i \in \mathbf{ND}
$$
\n
$$
\sum_{j=1, j\neq o}^{n} \hat{\lambda}_{j}^{*} y_{rj} \geq y_{ro}, \qquad r = 1, 2, ..., s,
$$

 $\text{where } \alpha_k \widetilde{\alpha}_k = \max_{i \in \mathbf{D_I}} \{ \alpha_i \widetilde{\alpha}_i \}.$

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This means that $(\alpha_k \widetilde{\alpha}_k \widehat{\theta}_{\text{ND}}^{\text{Sup}^*}, \widehat{\lambda}_j^*; j = 1, 2, \dots, n, j \neq o)$ is feasible to (3) for evaluating DMU_{*o*}. M oreover $\alpha_k \widetilde{\alpha}_k \widetilde{\theta}_{\text{ND}}^{\text{sup}}{}^* < \theta_{\text{ND}}^{\text{I}^*} \widetilde{\theta}_{\text{ND}}^{\text{sup}}{}^* \leq \theta_{\text{ND}}^{\text{I}^*},$ violating the optimality of $\theta_{\text{ND}}^{\text{I}^*}.$ Next suppose $1 \le \alpha_i \tilde{\alpha}_i \le \theta_{\text{ND}}^{\mathbf{I}^*}$, but $\text{DMU}_{\hat{\sigma}}$ is not a frontier point, when $\hat{x}_{io} = \alpha_i x_{io}$ and $\hat{x}_{ij} = \frac{x_{ij}}{\tilde{\alpha}_i}; i \in \mathbf{D}_{\mathbf{I}}$. Then

 $\frac{\widetilde{\alpha}_i}{\widehat{\alpha}}$ Model (2) for evaluating DMU $_{\widehat{o}}$ has an optimal solution $(\widehat{\theta}_{\mathtt{ND}}^{\mathtt{Sup}^*},\widehat{\lambda}_j^*;j=1,2,\ldots,n,\ j\neq o)$ such that $\widehat{\theta}_{\mathtt{ND}}^{\mathtt{Sup}^*}< 1.$ As can be seen above, $(\alpha_k \widetilde{\alpha}_k \widehat{\theta}_{ND}^{\text{Sup}^*}, \widehat{\lambda}_j^*; j = 1, 2, \ldots, n, j \neq o)$ is a feasible solution to (3). Now we get $\alpha_k \widetilde{\alpha}_k \widehat{\theta}_{ND}^{\text{Sup}^*} \leq \theta_{ND}^{\text{I*}} \widehat{\theta}_{ND}^{\text{Sup}^*} < \widehat{\theta}_{ND}^{\text{I*}}$ $\theta_{\text{ND}}^{\mathbf{I}^*}$, which is in contradiction to $\theta_{\text{ND}}^{\mathbf{I}^*}$ being the optimal value of Model (3).

In fact, Theorem 1 gives sufficient conditions for preserving BM_{CCR} -efficiency. The following theorem implies necessary conditions for preserving BM_{CCR} -efficiency of an extreme BM_{CCR} -efficient DMU_o .

Theorem 2. Suppose Model (3) is feasible and $\theta_{ND}^{Sup^*} > 1$. If $\alpha_i \tilde{\alpha}_i > \theta_{ND}^{I^*}$ for $i \in \mathbf{D_I}$, then DMU_{∂} is not extreme BM_{CCR} -efficient, where $\theta_{\text{ND}}^{\mathbf{I}^*}$ is the optimal value of Model (3). (DMU_∂ represents DMU_o after the perturbations).

Proof. By contradiction we assume that $\text{DMU}_{\hat{o}}$ is an extreme-BM_{CCR}-efficient point after the changes in the discretionary inputs of all units with $\alpha_i \tilde{\alpha}_i > \theta_{ND}^{I^*}$, $i \in \mathbf{D_I}$. Then $\hat{\theta}_{ND}^{Sup^*} > 1$, where $\hat{\theta}_{ND}^{Sup^*}$ is the optimal value to (2) for evaluating DMU₆. Now suppose $(\widehat{\theta_{\text{ND}}^*}, \widehat{\lambda}_j^*; j = 1, 2, \ldots, n, j \neq o)$ is an optimal solution to (3) for evaluating DMU₆. Then, by Lemma 1 we have $\widehat{\theta}_{ND}^{\mathbf{I}^*} > 1$. Also, in the optimal solution we have

$$
\begin{cases}\n\sum_{j=1, j\neq o}^{n} \hat{\lambda}_{j}^{*} \hat{x}_{ij} \leq \hat{\theta}_{\text{ND}}^{\mathbf{I}^{*}} \hat{x}_{io}, & i \in \mathbf{D}_{\mathbf{I}} \\
\sum_{j=1, j\neq o}^{n} \hat{\lambda}_{j}^{*} x_{ij} \leq x_{io}, & i \notin \mathbf{D}_{\mathbf{I}} \\
\sum_{j=1, j\neq o}^{n} \hat{\lambda}_{j}^{*} z_{ij} \leq z_{io}, & i \in \mathbf{ND} \\
\sum_{j=1, j\neq o}^{n} \hat{\lambda}_{j}^{*} y_{rj} \geq y_{ro}, & r = 1, 2, ..., s\n\end{cases}
$$

Or equivalently

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 $\begin{array}{c} \hline \end{array}$

$$
\sum_{\substack{j=1, j\neq o\\n}}^{n} \hat{\lambda}_{j}^{*} x_{ij} \leq \alpha_{i} \tilde{\alpha}_{i} \tilde{\theta}_{\text{ND}}^{\text{T}*} x_{io} \leq \alpha_{k} \tilde{\alpha}_{k} \tilde{\theta}_{\text{ND}}^{\text{T}*} x_{io}, \quad i \in \mathbf{D}_{\mathbf{I}}
$$
\n
$$
\sum_{\substack{j=1, j\neq o\\n}}^{n} \hat{\lambda}_{j}^{*} x_{ij} \leq x_{io}, \quad i \notin \mathbf{D}_{\mathbf{I}}
$$
\n
$$
\sum_{\substack{j=1, j\neq o\\n}}^{n} \hat{\lambda}_{j}^{*} z_{ij} \leq z_{io}, \quad i \in \mathbf{ND}
$$
\n
$$
\sum_{\substack{j=1, j\neq o\\n \equiv 1, j\neq o}}^{n} \hat{\lambda}_{j}^{*} y_{rj} \geq y_{ro}, \quad r = 1, 2, ..., s
$$

It can be easily verified that $\alpha_k \widetilde{\alpha}_k \widetilde{\theta}_{ND}^* = \theta_{ND}^{\mathbf{I}^*}$, where $\alpha_k \widetilde{\alpha}_k = \max_{i \in \mathbf{D_I}} \{ \alpha_i \widetilde{\alpha}_i \}.$

Thus,
$$
\widehat{\theta}_{ND}^{\mathbf{I}^*} = \frac{\theta_{ND}^{\mathbf{I}^*}}{\alpha_k \widetilde{\alpha}_k} < 1
$$
, violating $\widehat{\theta}_{ND}^{\mathbf{I}^*} > 1$.

The data perturbation can be expressed in a quadratic function, $\alpha_i \tilde{\alpha}_i = \theta_{\text{ND}}^{\mathbf{I}^*}$. This function gives an upper bound for discretionary input changes. Any data variations fall below this function and above lines $\alpha_i \geq 1$ and $\tilde{\alpha}_i \geq 1$, $i \in \mathbf{D_I}$ will preserve the frontier status of DMU*o*.

The above developments consider the input changes in all DMUs. Next, we consider the following modified DEA measure for simultaneous variations of inputs and outputs.

$$
\Omega_{\text{ND}}^{*} = \min \limits_{\substack{n \\ j=1, j\neq o}} \Omega_{\text{ND}} \quad (4)
$$
\n
$$
s.t. \sum_{\substack{j=1, j\neq o \\ n \\ j=1, j\neq o}}^n \mu_{j} x_{ij} \leq (1 + \Omega_{\text{ND}}) x_{io}, \quad i \in \mathbf{D}_{\mathbf{I}} \\
\sum_{\substack{j=1, j\neq o \\ n \\ j=1, j\neq o}}^n \mu_{j} x_{ij} \leq x_{io}, \quad i \in \mathbf{ND}
$$
\n
$$
\sum_{\substack{j=1, j\neq o \\ n \\ j=1, j\neq o}}^n \mu_{j} y_{rj} \geq (1 - \Omega_{\text{ND}}) y_{ro}, \quad r \in \mathbf{O}
$$
\n
$$
\sum_{\substack{j=1, j\neq o \\ n \\ j=1, j\neq o}}^n \mu_{j} y_{rj} \geq y_{ro}, \quad r \notin \mathbf{O}
$$
\n
$$
j = 1, 2, ..., n; j \neq o
$$
\n
$$
(4)
$$

Note that if DMU_o is a frontier point, then $\Omega_{\text{ND}} \geq 0$.

Theorem 3. Let DMU_o be a frontier point, and let Ω_{ND}^* be the optimal value to (4). If $1 \le \alpha_i \tilde{\alpha}_i \le 1 + \Omega_{\text{ND}}^*$, $i \in \mathbf{D_I}$, and $1 - \Omega_{ND}^* \leq \beta_r \beta_r \leq 1$, $r \in \mathbf{O}$, then DMU_{*o*} remains as a frontier point .

Proof. By contradiction we assume that $DMU_{\hat{o}}$ is not a frontier point. Suppose that Ω_{ND}^* is the optimal value to (4) for evaluating $DMU_{\widehat{o}}$, then we have $\Omega_{\text{ND}}^* < 0$. Consider the constraints of Model (4) in the optimal solution as follows:

$$
\sum_{j=1, j\neq o}^{n} \widehat{\mu}_{j}^{*} \widehat{x}_{ij} \leq (1 + \widehat{\Omega}_{\text{ND}}^{*}) \widehat{x}_{io}, \quad i \in \mathbf{D}_{\mathbf{I}} \n\sum_{j=1, j\neq o}^{n} \widehat{\mu}_{j}^{*} \widehat{x}_{ij} \leq \widehat{x}_{io}, \qquad i \notin \mathbf{D}_{\mathbf{I}} \n\sum_{j=1, j\neq o}^{n} \widehat{\mu}_{j}^{*} \widehat{x}_{ij} \leq \widehat{z}_{io}, \qquad i \in \mathbf{ND} \n\sum_{j=1, j\neq o}^{n} \widehat{\mu}_{j}^{*} \widehat{y}_{rj} \geq (1 - \widehat{\Omega}_{\text{ND}}^{*}) \widehat{y}_{ro}, \quad r \in \mathbf{O} \n\sum_{j=1, j\neq o}^{n} \widehat{\mu}_{j}^{*} \widehat{y}_{rj} \geq \widehat{y}_{ro}, \qquad r \notin \mathbf{O}
$$

Or equivalently

 $\sqrt{ }$

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$$
\begin{cases}\n\sum_{\substack{j=1, j\neq o \\ n}}^n \hat{\mu}_j^* x_{ij} \leq \alpha_i \tilde{\alpha}_i (1 + \hat{\Omega}_{\text{ND}}^*) x_{io} \leq [1 + (\alpha_k \tilde{\alpha}_k (1 + \hat{\Omega}_{\text{ND}}^*) - 1)] x_{io}, & i \in \mathbf{D}_{\mathbf{I}} \\
\sum_{\substack{n \\ n \\ n}}^n \hat{\mu}_j^* x_{ij} \leq x_{io}, & i \notin \mathbf{D}_{\mathbf{I}} \\
\sum_{\substack{j=1, j\neq o \\ n \\ j=1, j\neq o}}^n \hat{\mu}_j^* x_{ij} \leq z_{io}, & i \in \mathbf{ND} \\
\sum_{\substack{j=1, j\neq o \\ n \\ n}}^n \hat{\mu}_j^* y_{rj} \geq \beta_r \tilde{\beta}_r (1 - \hat{\Omega}_{\text{ND}}^*) y_{ro} \geq [1 - (1 - \beta_t \tilde{\beta}_t (1 - \hat{\Omega}_{\text{ND}}^*))] y_{ro}, & r \in \mathbf{O} \\
\sum_{\substack{j=1, j\neq o \\ n \\ n}}^n \hat{\mu}_j^* y_{rj} \geq y_{ro}, & r \notin \mathbf{O}\n\end{cases}
$$

where $\alpha_k \widetilde{\alpha}_k = \max_{i \in \mathbf{D_I}} \{ \alpha_i \widetilde{\alpha}_i \}$ and $\beta_t \beta_t = \min_{r \in \mathbf{O}} \{ \beta_r \beta_r \}.$ Set $\Omega = \max \{ (\alpha_k \widetilde{\alpha}_k (1 + \Omega_{ND}^*) - 1), (1 - \beta_t \beta_t (1 - \Omega_{ND}^*)) \}.$ Obviously $(\Omega, \hat{\mu}_j^*; j = 1, 2, \ldots, n, j \neq o)$ is a feasible solution of (4) for DMU_{*o*}. Therefore, $\Omega_{\text{ND}}^* \leq \Omega$. Now consider the following two cases:

Case 1: If $\Omega = (\alpha_k \tilde{\alpha}_k (1 + \Omega_{ND}^*) - 1)$, then from the assumptions we get $1 \leq \alpha_k \tilde{\alpha}_k \leq 1 + \Omega_{ND}^*$. Since $\Omega_{ND}^* < 0$, we have $0 < 1 + \Omega_{\text{ND}}^* < 1$. Thus, $(1 + \Omega_{\text{ND}}^*) \alpha_k \tilde{\alpha}_k \leq (1 + \Omega_{\text{ND}}^*) (1 + \Omega_{\text{ND}}^* < 1 + \Omega_{\text{ND}}^*$. This means that $\Omega = (1 + \Omega_{ND}^*) \alpha_k \widetilde{\alpha}_k - 1 < \Omega_{ND}^*$, which is a contradiction.

Case 2: If $\Omega = (1 - \beta_t \beta_t (1 - \Omega_{ND}^*))$, then from the assumptions we have $1 - \Omega_{ND}^* \leq \beta_t \beta_t \leq 1$. Since $\Omega_{ND}^* \leq 0$, we have $(1-\Omega_{\text{ND}}^*)>1$. So, $(1-\Omega_{\text{ND}}^*)\beta_t\beta_t\geq (1-\Omega_{\text{ND}}^*)(1-\Omega_{\text{ND}}^*)>1-\Omega_{\text{ND}}^*$. This means that $\Omega=(1-\beta_t\beta_t(1-\Omega_{\text{ND}}^*))<\Omega_{\text{ND}}^*$, which is in conflict with Ω *∗* $\frac{1}{N} \leq \Omega$.

Theorem 4. Suppose DMU_o is an extreme BM_{CCR}-efficient point, and Ω_{ND}^* is the optimal value to (4). If $\alpha_i \tilde{\alpha}_i >$ $1 + Ω_{ND}[*]$, *i* ∈ **D**_I and $1 − Ω_{ND}[*] > β_rβ_r$, $r ∈$ **O**, then DMU_{*o*} will not remain extreme-BM_{CCR}-efficient.

Proof. This is similar to the proof of Theorem 2 only with some minor modifications and, hence, omitted.

In fact, Theorem 3 gives sufficient conditions for preserving BM_{CCR} -efficiency, and Theorem 4 implies necessary conditions for preserving BM_{CCR} -efficiency of an extreme- BM_{CCR} -efficient DMU_o .

5 An application

To further clarify, we apply the above approach to the data set obtained from 16 hospitals: H1 to H16 (see Table 2). The data is taken from Tone [17]. Each hospital uses four inputs to produce two outputs. Table **2** shows the types of these inputs and outputs.

Input

Output

Table 3: Hospitals

In evaluating the efficiency of a hospital, the total hours worked by doctors in the survey period is an important (input) factor. But,"Doctor" is non-controllable and so we apply the BM model in order to evaluate the BM-efficiency and super-BM_{CCR}-efficieny of the hospitals. The results obtained by applying [BM_{CCR}], [BM^{Super}], and Model (3)

are given in Table 4. As can be seen, 10 of the hospitals are BM_{CCR}-efficient (see column 2 in Table 4). The 3rd Column of Table $\bm4$ reports the optimal value to Model (2), $\theta_{\tt ND}^{sup*}$. It can be seen that Model (2) is infeasible when hospitals H_5 , H_7 , and H_9 are under evaluation.

Table 4: BM-efficiency and BM-super-efficiency scores.

Now, we apply our sensitivity analysis to some hospitals. Assume that **H**2 is under evaluation. From column 4 in Table 4, if $\mathbf{D}_{I} = \{2, 4\}$ then $\theta_{ND}^{I^*} = 1.1339$. Using Theorem 2, if $1 \le \alpha_i \tilde{\alpha}_i < 1.1339$, $i \in \{2, 4\}$, then H2 remains as an extreme BM_{CCR}-efficient point when the discretionary inputs $i\in\{2,4\}$ of $\bf{H2}$ change from \bf{x}_2^D t to $\alpha_i\bf{x}_2^D$ and the discretionary inputs $i \in \{2, 4\}$ of other units change from $\mathbf{x}_{j}^{\mathbf{D}_{\mathbf{I}}}$ to $\mathbf{x}_j^{\mathbf{D}_{\mathbf{I}}}$ $\frac{1}{\alpha_i}$. Now consider **H**5 as the test DMU. It
der evaluation. This means that any values can be seen that both Models (2) and (3) are infeasible when **H**5 is under evaluation. This means that any values $a_i \geq 1$ and $\tilde{a}_i \geq 1$ of variation will not affect the BM-efficiency status of **H**₅ when Models (2) and (3) are applied, respectively.

6 Conclusions

The current paper develops a new super-efficiency DEA sensitivity analysis approach when some data are noncontrollable. This development is important since in any realistic situation there may exist "exogenously fixed" or non-discretionary factors that are beyond the control of a DMU's management, which also need to be considered. The new sensitivity analysis approach simultaneously considers the data perturbations in all DMUs. The data perturbation in the test DMU can be different from that in the remaining DMUs, where the BM_{CCR} -efficiency of the test DMU is deteriorating while the BM_{CCR} -efficiencies of other DMUs are improving. Necessary and sufficient conditions for preserving a DMU's BM_{CCR} -efficiency classification are developed when various data changes are applied to all DMUs. Because certain super-efficiency DEA models may be infeasible for some extreme-B M_{CCR} efficient DMUs, some direction for future research includes the study of super-efficiency and DEA sensitivity analysis for such DMUs with non-controllable factors.

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