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Hybrid Genetic for the Single-Source Capacitated Multi-Facility Weber Problem

S. Jahadi *∗†*, M. Solimanpur *‡*

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Abstract

In this paper, we investigate the Single-Source Capacitated Multi-Facility Weber Problem. The aim is to locate several new facilities among existing customers and simultaneously allocate customers to facilities, so that capacity constraints are met and each customer will provide all its demand from just one facility, and as a result, the total cost of transporting between new facilities and existing customers gets minimum. A Genetic Algorithm is proposed for solving the problem, in which a local search method is embedded. The proposed Genetic Algorithm is tested on existing data sets to evaluate its robustness over available methods in the literature.

Keywords : Weber Problem; Location-allocation, Metaheuristic, Local Search, Genetic Algorithm.

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1 Introduction

L ocation problems are considered to be crucial
L problems in decision making by governments, τ ocation problems are considered to be crucial organizations and companies. The simplest form of location problems is the single-facility location problem, which is known as the Weber Problem. An extension of the Weber Problem is the Multi-Source Weber Problem, which is known as the location-allocation problem. The objective of the location-allocation problem is to locate some new facilities among several customers with determined locations and fixed demands, and simultaneously allocate customer demands to facilities, so that the total cost of transportation between facilities and existing customers gets minimum. In a division, we can divide the locationallocation problem into three continuous, discrete, and on-network categories. In another division, it is divided to uncapacitated problem or capacitated problem. In this study another type of the problem known as the Single-Source Capacitated Multi-Facility Weber Problem (SSCM-FWP) is studied in which each customer must provide all of its demand only from one facility. In addition, taking into account the capacity constraints, one can study situations that are much closer to reality. In practice, there are certain situations where each customer must provide its demand only from one facility. In addition, working just with one facility is sometimes more attractive from a customer viewpoint because the customer can get a discount due to the economies of scale. This applies to locating factories, ware-

*[∗]*Corresponding author. saed.jahadi@gmail.com, Tel:+98(914)1907167.

*[†]*Department of Industrial Engineering, Urmia University of Technology, Urmia, Iran.

*[‡]*Department of Industrial Engineering, Urmia University, Urmia, Iran.

houses, public facilities [8], as well as industrial supplies, transportation planning, irrigation and oil pit location systems [36], hospitals, schools, industries, and the like. The optimal solution of the Multi-Source Weber Pro[bl](#page-10-0)em might be unusable in practice, as several facilities may be located in some forbidden area [su](#page-11-0)ch as a lake, a mountain, etc. [37]. In general, single-facility location problems are convex, and their optimal solution can be obtained either through exact methods or through some heuristic algorithms [13], while multi-facil[ity](#page-11-1) location problems are non-convex and non-linear, and exact algorithms cannot solve large-scale problems optimally in a polynomial time. In addition, Cooper [12] has pr[ove](#page-10-1)n that the objective function of these problems is neither concave nor convex, and may include several local optima. Hence, the Multi-Source Weber Problem has been located in the field [of](#page-10-2) general optimization problems [20]. In addition, even if all customers are on a straight line, the problem is NP-Hard [40, 37]. In the concept of the Multi-Source Weber Problem, the large-scale problem points to the existence of [hig](#page-10-3)h local optima, which makes it difficult if it is not impossible, to find the optimal soluti[on](#page-11-2) a[t a](#page-11-1) reasonable computational time. In addition, the complexity of the problem depends on a nonlinear behavior on the number of facilities and the number of customers [8]. If in any location-allocation problem the allocation of customers to the facility is assumed to be fixed, it will be reduced to a location problem and Similarly, if facility locations are determined, [it](#page-10-0) is reduced to an allocation problem.

2 Literature review

2.1 **Multi-Source Weber Problem**

The literature of the location-allocation problem focuses on solution methods, since this has a lot of local optima [20]. For the first time, Cooper [12] in 1963 studied the location-allocation problem and proposed an exact algorithm, as well as a method for testing all possible allocations. Cooper [13] pro[po](#page-10-3)sed the first heuristic algo[rith](#page-10-2)m for solving the continuous location allocation problem, which is known as the Alternate Location [Al](#page-10-1)location (ALA) algorithm, and is an interesting algorithm in the literature. Teitz and Bart [47] studied the location-allocation problem on network and presented a heuristic algorithm, swap of vertexes, in order to find an absolute median. Eilon et al. [17], for a problem with 5 [fa](#page-12-0)cility and 50 customer, according to 200 random initial solution, found 61 local optima, that the worst of them had 40.9 percent difference with the best of them. [Kue](#page-10-4)nne and Soland [27] presented an approximate algorithm and a branch and bound algorithm to solve the problem. Love and Juel [30], studied the locationallocation problem and presented five methods [for](#page-11-3) solving the problem. Moreno et al. [39] presented a drop heuristic algorithm that starts with an initial solution of [N](#page-11-4) customer, in which N is selected between m (number of facilities) and 2m. Then the extra facilities were remo[ved](#page-11-5) by a greedy method up to the point where exactly m facility remained. Love and Morris [31] presented the Set Reduction method and the P-median Algorithm to solve the location-allocation problem with Rectilinear distances. Liu et al. [29] used a Simulated Annealing algorithm wi[th R](#page-11-6)ectilinear distances to solve the problem. Bongartz et al. [5] presented the Projection method for solving the Multi-Source Weber Problem wit[h L](#page-11-7)p norm distances. Brimberg and Mladenovic [10] used the Tabu Search algorithm to solve the problem. [Br](#page-10-5)imberg and Mladenovic [11] presented a Neighborhood Search method. Hansen et al. [22], by considering the location of customers as [pot](#page-10-6)ential locations for the establishment of facilities, defined the P-median proble[m c](#page-10-7)orresponding to the main problem and solved it exactly. Br[im](#page-11-8)berg et al. [8], compared different algorithms for solving the Multi-Source Weber Problem. Gamal and Salhi [19] presented a constructive heuristic algorithm. Gamal and Salhi [18] presented a Cellular heuris[tic](#page-10-0) algorithm. Salhi and Gamal [46] also presented a Genetic Algorithm for solving the contin[uou](#page-10-8)s location-allocation problem without capacity constraints. Re[sen](#page-10-9)de and Werneck [44] introduced an application of Teitz and Ba[rts](#page-12-1) swap based local search [47] and Resende and Werneck [45] presented another application for the P-median problem, which is faster than the [pre](#page-12-2)vious one. Jabalameli and Ghaderi [26] presented three hybrid algorit[hm](#page-12-0)s for solving the continu-

ous location-allocation problem without capacity constraints. Neema et al. [41] proposed two Genetic Algorithms to solve the continuous locationallocation problem. Ghaderi and Jabalameli [20] presented two classic and hybrid PSO methods. Brimberg and Drezner [6] [pr](#page-12-3)esented a modified version of the ALA algorithm to solve the continuous problem. Brimberg et al. [7] presented [an](#page-10-3) innovative random method to produce a good initial solution to the conti[nu](#page-10-10)ous location-allocation problem. For further study on the uncapacitated location-allocation problems, rea[de](#page-10-11)rs can refer to review articles such as Mladenovic and Brimberg et al. [38] for the p-Median and Brimberg et al. [9] for the continuous problem. Arnaout [4] considered the location-allocation problem with unknown number of facilities and introduced an Ant Colon[y O](#page-11-9)ptimization (ACO) Algorithm. Drezner [et](#page-10-12) al. [15] proposed new heuristic algorit[hm](#page-10-13)s for solving the p-median problem. Also Drezner et al. [16] peresented new local searches for solving the Multi-Source Weber Problem. Dehkordi [42] pr[opo](#page-10-14)sed a modified version of Coopers ALA algo[rith](#page-10-15)m for solving the MSWP.

[2.2](#page-12-4) **Capacitated Multi-Source Weber Problem**

There are very few articles that have studied the problem with capacity constraints. First time, Cooper [14] studied this problem in 1972 and presented exact and heuristic algorithms to solve it. Aras et al. [3] proposed three heuristic algorithms to solve the problem with Euclidean and Squ[ared](#page-10-16) Euclidean distances. Zainuddin and Salhi [49] presented a Perturbation based heuristic algorithm. Lu[is](#page-10-17) et al. [33] presented a heuristic algorithm called Region-Rejection Based Algorithm (RRA) for Multi-Source Weber Problem with [cap](#page-12-5)acity constraints. Luis et al. [34] presented a random search al[gor](#page-11-10)ithm called Guided Reactive GRASP. Luis et al. [35] introduced fixed costs of opening facilities for the Capacitated Multi-Source Weber Problem and [prop](#page-11-11)osed a Greedy Randomized Adaptive Search Procedure (GRASP) for solving the p[rob](#page-11-12)lem. Akyuz et al. [1] proposed location and allocation based branch and bound algorithms for the Capacitated Multi-Source Weber Problem. Hosseininezhad et al. [2[3\]](#page-9-0) considered fixed cost for the Capacitated Multi-Source Weber Problem and proposed a Cross Entropy heuristic for solving the problem. Luis et al. [32] considered various capacity constraints to the Multi-Source Weber Problem and proposed a Greedy Randomised Adaptive Search Procedure (GRASP) to deal with the problem. Lara et al. [[28\]](#page-11-13) considered the Capacitated Multi-Source Weber Problem with fixed cost and proposed a Decomposition Algorithm. Akyuz et al. [2] proposed two branch and bound algorithms for exactly [sol](#page-11-14)ving multi-commodity extension of the Capacitated Multi-Source Weber Problem.

2.3 **Single-Source Capacitated Multi-Facility Weber Problem**

The number of studies considering the SSCM-FWP is very rare. Gong et al. [21] presented a hybrid evolutionary method. Manzour-al-Ajdad et al. [37] presented an iterative two-phase heuristic algorithm. Manzour-al-Ajdad et al. [36] presented two modified versions of th[e C](#page-10-18)ooper's ALA algorithm to solve the problem. Temel Oncan [40] st[udi](#page-11-1)ed the problem with Euclidean and Rectilinear distances, and presented severa[l m](#page-11-0)ethods to solve the problem. Irawan et al. [24] investigated the single-source location problems [wit](#page-11-2)h the presence of several possible capacities and fixed cost. By considering both the discrete and the continuous cases using Rectilin[ear](#page-11-15) and Euclidean distances, they proposed two solution methods. Irawan et al. [25] investigated the SSCCMFWP with setup cost of opening facilities and introduced a nonlinear mathematical model. They used Rectilinear and Euclidean distances and proposed two me[tah](#page-11-16)euristic algorithms based on Variable Neighbourhood Search and Simulated Annealing. They also constructed a new data set.

3 Mathematical formulation

The goal of the Single-Source Capacitated Multi-Facility Weber Problem (SSCMFWP) is to find optimal location of facilities among existing customers and simultaneously determine how customers are allocated to facilities, so that each customer must provide all its demand just from one facility, and the total cost of transporting between customers and facilities gets minimum. The following notations are used.

Parameters:

m: the number of facilities. *n*: the number of customers. *w^j* : the demand of customer *j*. *ci* : the capacity of facility *i*. $A_j = (a_j, b_j)$: coordinates of customer *j*.

Decision variables:

 $X_i = (x_i, y_i)$: coordinates of facility *i*.

 $z_{ij} =$ { 1;if customer j is assigned to facility i, 0;otherwise

Let $d(X_i, A_j)$ be the distance between facility *i* and customer *j* which is defined as follows:

$$
d(X_i, A_j) = \sqrt{(x_i - a_j)^2 + (y_i - b_j)^2}
$$

The mathematical model of the SSCMFWP can be formulated as follows:

$$
\min \sum_{i=1}^{m} \sum_{j=1}^{n} z_{ij} \times d(X_i, A_j)
$$
 (3.1)

subject to

$$
\sum_{i=1}^{m} z_{ij} = 1, \ \forall j = 1, 2, \dots, n
$$
 (3.2)

$$
\sum_{j=1}^{n} w_j \times z_{ij} \le c_i, \ \forall i = 1, 2, ..., m \tag{3.3}
$$

$$
z_{ij} \in \{0, 1\}, \ i = 1, 2, \dots, m, \ j = 1, 2, \dots, n
$$
\n
$$
(3.4)
$$

Eq. (3.1) minimizes the total transportation cost between the facilities and the customers. Eq. (3.2) states that each customer must provide all its demand only from one facility. Eq. (3.3) ensures that [the](#page-3-0) total demand, which is provided by each facility should not exceed its capacity limit. [Eq.](#page-3-1) (3.4) indicates that z_{ij} is a binary variable.

It is worth noting that, for a given set [of d](#page-3-2)etermined allocations, the SSCMFWP is reduced into m si[ngle-](#page-3-3)facility location problems, each of which can be separately solved exactly by the wellknown Weiszfeld's method [48]. It is reminded that, the proposed model is a non-convex mixed integer non-linear programming (MINLP) model. It is also noted that the SSCMFWP is much more complicated than the CMF[WP.](#page-12-6) In fact, after fixing the location of facilities, the CMFWP reduces to the Transportation Problem (TP), while the SSCMFWP after fixing facility locations reduces to the Generalized Assignment Problem (GAP) [37].

[4](#page-11-1) The proposed Genetic Algorithm

The Genetic Algorithm is a random search algorithm which acts based on the rules of natural evolution. A Genetic Algorithm is a set of initial solutions that each of them is called a chromosome in the population, which are produced during each generation, according to genetic crossover and mutation operators. Now, some of the best chromosomes are selected and some are selected randomly for the next generation. The process is repeated until stopping condition is satisfied. Unlike local search algorithms that usually get stuck in local optima, the Genetic Algorithm is able to search all of the solution space and find the optimal or near optimal solution. We will present a Hybrid Genetic Algorithm (HGA) in which a local search is embedded to solve the SSCMFWP. The main steps of the proposed Genetic Algorithm are as follows:

Require: *K*1, *K*2, *Imax*, *P*

1: **repeat**

- 2: Produce an initial solution.
- 3: Improve the produced initial solution by applying the local search approach.

4: **until** P times

```
5: repeat
```

```
6: for O = 1 to P do
```
- 7: Produce a new solution as a child of the solution O using the proposed mutation approach.
- 8: Improve the produced child by applying the proposed local search approach.

9: **end for**

10: Select among all parents and childeren, K_1 number of the best and K_2 number randomly and create the new population $(k_1 + k_2 = P)$ for the next iteration.

11: **until** I_{max} times

12: **return** the best solution

4.1 **Encoding**

Each chromosome in the population is made up of a number of genes with a particular sequence. Each gene can be represented by binary numbers, real numbers, integers, symbols and the like. Generally, in the Genetic Algorithm for representing the chromosomes the binary encoding is used. In practice, the use of binary encoding is not always appropriate. In addition, it is possible to produce infeasible solutions when using genetic operators. In this study, we use the real number encoding in which each chromosome is represented as follows:

$$
[(x_{k1}, y_{k1}), (x_{k2}, y_{k2}), \ldots, (x_{km}, y_{km})] \rightarrow f_k
$$

In which f_k represents the value of the objective function of the chromosome *k* and (x_{km}, y_{km}) is the coordinates of the facility *m* in the solution *k*. It represents the *m*th gene in the chromosome *k*.

4.2 **Initial solution**

Typically, randomly generated location of facilities are used to start the search process in solving location problems. But this method is not very suitable because facilities may be located in the same area of the solution space and are chosen very close together and the rest of the areas be vacant, which will be an inappropriate initial solution. Hence, we produce every initial solution in the primary population as follows:

Require: *m*, *n*

1: Denote:

- T_i : the set of allocated customers to facility $i, i = 1, 2, \ldots, m$,
- $q_i = |T_i|$: the amount of customer demands that are met by facility $i, i = 1, 2, \ldots, m$.
- 2: Set $z_{ij} = 0, q_i = 0$ *for* $i = 1, 2, ..., m, j =$ 1*,* 2*, , n*.
- 3: Select customer *j* randomly among all customers.
- 4: Locate facility 1 on the location of the customer j and set $X_1 = A_j$.
- 5: **repeat**
- 6: Let *j′* be index of the closest customer to the facility 1.
- 7: Allocate the customer *j′* to the facility 1 and set z_{1j} $\prime = 1$, $q_1 + w_j$ _{*j*}.
- 8: **until** $q_1 < c_1$
- 9: **for** *i* = 2 *to m* **do**

10: Set $D_{min} = \infty$.

- 11: **for** $j = 1$ *to n* **do**
- 12: **if** the customer *j* is an unallocated customer **then**
- 13: Let D_j be cumulative distance between the *j*th customer and all already located facilities and calculate $D_j = \sum_{k=1}^i d(X_k, A_j)$ 14: **if** $D_j \leq D_{min}$ **then**
- 15: Let j^* be index of the customer with minimum D_j and set $j \to j^*$.
- 16: **end if**
- 17: **end if**
- 18: **end for**
- 19: Locate the facility *i* on the location of the customer j^* and set $X_i = A_{j^*}$.
- 20: **repeat**
- 21: let *j′* be the index of nearest unallocated customer to the facility *i*.
- 22: Assign the customer *j′* to the facility *i* and set z_{ij} ^{*j*} = 1 and q_i ^{$+$} = w_j *j*.
- 23: **until** $q_i < c_i$.
- 24: **end for**
- 25: Calculate the total cost as:
- $f = \sum_{i=1}^{m} \sum_{j=1}^{n} z_{ij} \cdot w_j \cdot d(X_i, A_j).$ 26: \textbf{return} $\hat{f}, X_i, q_i, z_{ij}$ $for \quad i =$ $1, 2, \ldots, m, j = 1, 2, \ldots, n.$

4.3 **The proposed local search approach**

Local search algorithms start with a point in the solution space and try to move to a point in the neighborhood, which is more suitable than the initial starting point. The search ends when a more appropriate solution in the neighborhood can not be found [20]. We define $0 \le \theta_i \le 1$ as the priority of customer j's allocation. The closer

m	Previous methods								Presented method	
	SSALA		SSALA-VLSN		TPH-S		TPH-P		HGA	
	VALUE	CPU	VALUE	CPU	VALUE	CPU	VALUE	CPU	VALUE	CPU
$\,2$	135.80	1.2	135.80	0.1	135.80	0.7	135.80	0.3	135.79	0.15
3	106.35	2.1	106.74	0.1	106.36	0.6	106.69	0.5	106.33	0.45
$\overline{4}$	86.49	2.9	87.60	0.2	86.49	0.9	86.49	0.8	86.48	0.46
$\bf 5$	74.46	3.7	75.02	0.2	79.73	1.0	74.12	1.2	74.10	0.4
6	61.54	5.0	61.54	0.3	65.82	1.4	61.17	1.4	61.35	0.88
$\overline{7}$	56.37	5.7	57.39	0.3	56.37	1.8	56.37	1.7	56.36	0.66
$8\,$	51.17	7.1	51.85	0.4	54.28	1.9	54.28	2.0	51.17	0.76
9	47.31	8.2	47.47	0.5	51.09	2.7	51.09	2.7	47.29	0.83
10	42.56	9.8	43.08	0.5	43.45	3.0	46.02	2.9	42.42	0.78
11	40.36	11.2	43.05	0.6	40.86	3.1	40.42	2.8	40.39	0.49
12	36.56	12.9	38.29	0.6	35.99	3.2	35.99	3.1	35.76	0.46
13	35.18	14.9	37.92	0.8	35.72	6.2	35.72	5.9	35.25	0.63
14	31.49	16.4	32.65	0.6	34.50	7.1	34.50	6.5	31.07	1.35
15	28.10	18.6	30.52	0.7	28.95	6.5	28.95	6.7	28.07	0.57
16	26.54	20.5	27.91	0.8	29.19	7.5	29.19	7.8	25.86	0.58
17	26.07	22.8	26.81	0.7	26.66	4.0	25.84	3.8	25.91	0.28
18	23.79	24.4	25.41	0.7	24.24	3.8	24.20	3.4	23.73	1.36
19	22.13	26.6	24.29	0.6	22.54	4.1	22.54	4.1	21.69	1.08
20	21.09	29.3	23.00	0.7	23.02	4.0	23.02	3.6	20.00	0.63
21	20.80	31.9	21.72	0.8	20.85	4.9	20.85	4.0	18.77	0.69
22	19.36	34.7	19.59	0.7	19.93	4.3	19.36	4.2	17.27	0.6
23	18.48	37.4	19.82	0.8	17.48	5.2	17.48	5.3	16.18	0.55
24	16.36	40.6	18.46	0.7	20.13	5.0	15.52	4.8	14.78	1.30
25	15.66	43.4	16.38	0.7	17.06	4.5	17.06	4.3	13.81	0.44
Average	43.50	17.9	44.68	0.5	44.85	3.6	44.28	3.5	42.91	0.68

Table 1: Computational results of the test problem with 50 customers.

Table 2: Computational results of the test problem with 654 customers.

the parameter θ_j is to 1, it indicates that the customer j is a borderline customer, it means, the distance from first closest and second closest facility are almost equal. If the allocation of a borderline customer changes from the first closest facility to the second closest facility, the amount of change in the objective function will be very inconsiderable. Contrary to the uncapacitated problem, in the capacitated problem, the capacity of some facilities is completed and some are not. Completed capacity facilities are usually located in a place close to many customers. Therefore, with changing customer allocation, different solutions can be obtained.

m	Previous methods								Presented method	
	SSALA		SSALA-VLSN		TPH-S		TPH-P		HGA	
	VALUE	CPU	VALUE	CPU	VALUE	CPU	VALUE	CPU	VALUE	CPU
5	1870070	801.9	1982440	28.0	1870070	4.0	1870070	3.7	1870125.67	36.9
10	1282800	3487.5	1331420	31.5	1282490	18.9	1283840	21.8	1285856.54	81.7
15	996270	7589.7	1032960	34.0	1006820	51.7	1006190	31.7	999521.96	97.9
20	848121	12526.3	873307	36.5	854624	78.1	866235	109.4	851943.7	135.5
25	750596	20756.6	779328	41.5	764416	181.1	751215	123.7	758849.63	197.4
30	664243	27303.4	688912	46.5	671964	195.1	674342	157.6	669013.77	199.53
35	598097	40235.3	610757	63.5	598208	294.1	614270	157.3	599051.33	186.2
40	566357	56384.4	578769	74.0	583318	288.1	597698	398.6	569867.16	307.2
45	533346	67218.3	546675	87.0	546168	323.2	533241	480.3	536444.16	381.1
50	483096	74328	490115	104.5	488748	556.6	486715	503.7	482903.94	201.8
Average	859299.6	31063.2	891468.3	54.7	866682.6	199.1	868381.6	198.8	862357.87	182.5

Table 3: Computational results of the test problem with 1060 customers.

So some customers should be allocated to the second or even the third closest facility due to the capacity completion of the first closest facility. By releasing a borderline customer from a facility with completed capacity, we create an empty space so that another customer can be allocated to its first closest facility. The proposed local search algorithm is described as follows:

Required:
$$
m, n, f, X_i, q_i, c_i, z_{ij} for i = 1, 2, ..., m, j = 1, 2, ..., n.
$$

1: Denote:

 T_i : the set of allocated customers to facility $i, i = 1, 2, \ldots, m$,

 $q_i = |T_i|$: the amount of customer demands that are met by facility $i, i = 1, 2, \ldots, m$.

- 2: Calculate distances $d(X_i, A_j)$ for $i =$ $1, 2, \ldots, m, j = 1, 2, \ldots, n.$
- 3: Denote for $j = 1, 2, ..., n$: E_i : the index of the facility that the customer *j* is allocated to it.

 E'_{j} : the index of the first closest facility to the customer *j*.

 E''_j : the index of the second closest facility to the customer *j*.

θ^j : the priority of the customer *j*.

4: Set
$$
f \rightarrow f^*
$$
, $X_i \rightarrow X_i^*$, $T_i \rightarrow T_i^*$, $q_i \rightarrow q_i^*$ for $i = 1, 2, ..., m$.

5: **repeat**

6: Calculate
$$
\theta_j = \frac{d(X_{E'_j}, A_j)}{d(X_{E''_j}, A_j)}
$$
 for $j = 1, 2, ..., n$.

7: Set $\alpha_{min} = \infty$.

8: **for**
$$
k=1
$$
 to n **do**

9: Set
$$
T_i \rightarrow T'_i
$$
, $q_i \rightarrow q'_i$ for $i = 1, 2, ..., m$.

10: Denote $\alpha_k = 0$ be amount of difference in the total cost that is created by releasing a number of customers and reassigning each of them to a new facility.

11: if
$$
k \notin T'_{E'_k}
$$
 then

12: Release the customer k and set q'_{E_k} – = w_k . 13: Set $\alpha_k - \frac{d(X_{E_k}, A_k)}{dt}$. 14: **if** $c_{E'_{k}} - q'_{E'_{k}} < w_{k}$ then 15: Release the customer *j* with minimum θ_j among all allocated customers to the facility E'_{k} and set $q'_{E'_{k}} - = w_{j}$. 16: **end if** 17: **if** $c_{E'_j} - q'_{E'_j} < w_j$ then 18: **repeat** 19: Set $j \to j'$ 20: Release the customer *j* with minimum θ_i among all allocated customers to the facility $E'_{j'}$ and set $q'_{E'_{j'}} - = w_j.$ 21: Set $\alpha_k - = d(X_{E'_{j'}}, A_j)$. $\textbf{u} = \int_{E_j'} E_j - q'_{E_j'} \geq w_j$

23: **end if**

24: Assign the customer k to E'_{k} and set $q'_{E'_{k}} + = w_{k}$. 25: Set $\alpha_k + d(X_{E'_k}, A_k)$.

26: **repeat**

Figure 1: Summary of obtained results.

27: Let *j* be the index of the unallocated customer with minimum θ_j and *i* be the index of the nearest facility with enough capacity to the customer *j*. Assign the customer *j* to the facility *i* and set $q'_i + w_j = w_j$. 28: Set $\alpha_k + d(X_i, A_j)$. 29: **until** there is an unallocated customer 30: **if** $\alpha_k \leq \alpha_{min}$ **then** 31: Set $T'_i \rightarrow T^*$, $q'_i \rightarrow q^*$ for $i =$ 1*,* 2*, . . . , m*. 32: **end if** 33: **end if** 34: **end for** 35: **for** *i* = 1 *to m* **do**

Figure 2: Summary of Average results.

36: Determine the new coordinates of facility i using Weiszfeld's equations [48]:

$$
x_i^{\star} = \frac{\sum_{j \in T_i^{\star}} \frac{w_j \times a_j}{d(X_i, A_j)}}{\sum_{j \in T_i^{\star}} \frac{w_j}{d(X_i, A_j)}}
$$

$$
y_i^{\star} = \frac{\sum_{j \in T_i^{\star}} \frac{w_j \times b_j}{d(X_i, A_j)}}{\sum_{j \in T_i^{\star}} \frac{w_j}{d(X_i, A_j)}}
$$

37: **end for**

- 38: Calculate new distances $d(X_i^{\star}, A_j)$ *for* $i =$ $1, 2, \ldots, m, j = 1, 2, \ldots, n.$
- 39: Calculate total cost of obtained new solution as:

$$
f^* = \sum_{i=1}^m \sum_{j \in T_i^*} w_j \times d(X_i, A_j).
$$

40: **if** $f^* < f$ **then**
41: Set $f^* \rightarrow f$, $X_i^* \rightarrow X_i$, $T_i^* \rightarrow T_i$, $q_i^* \rightarrow$
 q_i for $i = 1, 2, ..., m$.
42: **end if**
43: **until** $f^* \leq f$
44: **return** f , X_i , q_i , z_{ij} for $i =$
 $1, 2, ..., m, j = 1, 2, ..., n$.

4.4 **The proposed mutation approach**

The mutation operator creates small random changes on one parent in the population, so as a result a new child is produced. We apply the mutation operator to all members of the population, so each individual of the population as a parent produces a new offspring. The main steps of the proposed mutation algorithm are as follows:

Require: m , n , f , c_i , q_i , X_i , z_{ij} for $i =$ $1, 2, \ldots, m, j = 1, 2, \ldots, n.$

1: Denote:

Ti : the set of allocated customers to facility $i, i = 1, 2, \ldots, m$,

 $q_i = |T_i|$: the amount of customer demands that are met by facility $i, i = 1, 2, \ldots, m$.

2: Calculate distances $d(X_i, A_j)$ for $i =$ $1, 2, \ldots, m, j = 1, 2, \ldots, n.$

3: Denote for $j = 1, 2, ..., n$:

 E_i : the index of the facility that the customer *j* is allocated to it.

 E'_{j} : the index of the first closest facility to the customer *j*.

 E''_j : the index of the second closest facility to the customer *j*.

 θ_i : the priority of the customer *j*.

- 4: **for** $i = 1$ *to* m **do**
- 5: **if** $q_i == c_i$ then
- 6: Select customer *j* randomly from the set T_i .
- 7: Move the facility *i* to the customer location and set $X_i = A_j$.
- 8: **end if**
- 9: **end for**
- 10: Calculate new distances $d(X_i, A_j)$ for $i =$ $1, 2, \ldots, m, j = 1, 2, \ldots, n.$

11: Calculate
$$
\theta_j = \frac{d(X_{E'_j}, A_j)}{d(X_{E''_j}, A_j)}
$$
 for $j = 1, 2, \ldots, n$.

- 12: Set $q_i = 0$, $y_{ij} = 0$ for $i = 1, 2, ..., m, j =$ $1, 2, \ldots, n$.
- 13: **repeat**
- 14: Let *j* be the index of the unallocated customer with minimum θ_i and *i* be the index of the nearest facility with enough capacity to the customer *j*. Assign the customer *j* to the facility *i* and set $q_i + w_j$, $Y_{ij} = 1$.
- 15: **until** there is an unallocated customer
- 16: Calculate total cost of obtained new solution as:
- $f = \sum_{i=1}^{m} \sum_{j=1}^{n} z_{ij} \times w_j \times d(X_i, A_j).$ 17: **return** f , X_i , q_i , z_{ij} for $i =$ $1, 2, \ldots, m, j = 1, 2, \ldots, n.$

4.5 **New population**

A new population must be created among the individuals and children of the current population. The method of selecting solutions to form the next population has a great influence on the performance of the Genetic Algorithm. In order to avoid trapping in a local optima, we form the next population in such a way that from all the individuals of the current population and the children produced from them, we select some of the best and some at random.

4.6 **Stopping condition**

The Genetic Algorithm is repeated from one population to another until it reaches the stopping condition. We use the maximum number of iterations in this study as a criterion to stop the search process.

4.7 **Computational experiments**

In this section, we present the computational results obtained from the experiments performed on the presented Hybrid Genetic Algorithm. The presented algorithm was coded with C++ and has been executed on a Core i5 Laptop with processor specifications of 2 GHZ and 4 GB RAM. Temel Oncan [40] presented heuristic algorithms to solve the SSCMFWP and compared obtained results with those of two-phase algorithm presented by Manzour-al-Ajdad et al. [37]. Given that there are [very](#page-11-2) few studies on the SSCMFWP, we compared the performance of our algorithm

with the results available in Temel Oncan [40]. We evaluated the performance of algorithms in terms of solution quality. Given that we did not have the pseudo code of previous methods to run on the same computer in the same conditions[, w](#page-11-2)e evaluated the performance of our method according to the average results. We used the proposed Genetic Algorithm 10 times on each sample problem and recorded the best obtained result.

4.8 **Sample Problems**

To do our computational experiments, we used the data set which had been used by Brimberg et al [8]. The first data set with 50 customers is available in Eilon et al. [17] and the second and third data sets with 654 and 1060 customers are listed in the TSP library [43]. In all data sets, custo[me](#page-10-0)r demand is equal to 1. The capacity of each facility is considere[d to](#page-10-4) be equal to:

$$
c_i = \lceil \frac{\sum_{j=1}^n w_j}{m} \rceil, \ i = 1, 2, \dots, m.
$$

4.9 **Parameters**

The following parameters were obtained by a preliminary experiment.

 $P = 5$: the population size.

 $k' = 2$: the number of best solutions to produce new population.

 $k'' = 3$: the number of random solutions to produce new population.

Maximum number of iterations:

$$
I_{max} = \begin{cases} 100; & \text{for } n = 50 \\ 40; & \text{for } n = 654 \\ 40; & \text{for } n = 1060 \end{cases}
$$

4.10 **Computational Results**

The computational results of the performed experiments on the test problems with 50, 654 and 1060 customers are presented in Table 1, Table 2 and Table 3, respectively. In all tables, the title "Previous methods" points to the previous available methods of this problem, and the title "presented method" describes the met[ho](#page-5-0)d pre[se](#page-5-1)nted in thi[s](#page-6-0) study. The second line in each table represents the name of each algorithm, in which the titles "HGA" refers to the presented Hybrid Genetic Algorithm. The title "VALUE" under the name of each algorithm represents the obtained results of each method, and the title "CPU" denotes the computational time of each method. The first column in each table entitled "m", represents the number of facilities. Figure 1 summarizes the obtained results of the computational experiments and Figure 2 summarizes the average of the obtained results of methods. In the first test problem with 50 customers, HG[A](#page-7-0) has obtained the lowest average results among all other methods. Although com[pu](#page-7-1)tational time is not considered as a comparative criterion, it is observed that the HGA obtained this result at a fairly reasonable time. In addition, in 20 instances, HGA has obtained the best result among the other methods. In the test problem with 654 customers, despite the fact that the HGA did not achieve the lowest average but it has a little variance with other methods. In the test problem with 1060 customers, among all methods except SSALA, the lowest average results has been obtained by HGA.

5 Conclusion

In this study, we considered the SSCMFWP and presented a Hybrid Genetic Algorithm. The presented algorithm was evaluated on three wellknown test problems in the literature and the results were compared with some available methods in the literature. In general, for all test problems in comparison with other methods, there was no distant point among the results obtained by the HGA. In addition, HGA obtained the best results among the other methods in some instances. Extending the exact and heuristic methods, taking into account the fixed cost of establishing facilities and a modified version of this problem, in which customers have different demands, can be attempted in future studies.

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Saeed Jahadi received his MSc degree from Urmia University of Technology in 2014. His research areas of interest include facility layout and location, transportation planning, optimization, and distribution systems.

Maghsud Solimanpur is a Professor of Industrial Engineering at the Department of Industrial Engineering, Urmia University, Urmia, Iran. He has received his BSc and MSc degrees from Sharif University of Technology in 1995 and

1997, respectively. He received his PhD degree from Indian Institute of Technology (IIT) Delhi, India in 2003. His research areas of interest include production and operations management, operations research, cellular manufacturing systems, facilities planning and layout, etc.