# Common fixed points for a pair of mappings in $b$-Metric spaces via digraphs and altering distance functions 

S. K. Mohanta ${ }^{\text {a,* }}$, D. Biswas $^{a}$<br>${ }^{\text {a }}$ Department of Mathematics, West Bengal State University, Barasat, 24 Parganas(North), Kolkata-700126, West Bengal, India.

Received 5 May 2018; Revised 5 June 2018; Accepted 15 June 2018.
Communicated by Tatjana Dosenović


#### Abstract

In this paper, we discuss the existence and uniqueness of points of coincidence and common fixed points for a pair of self-mappings satisfying some generalized contractive type conditions in $b$-metric spaces endowed with graphs and altering distance functions. Finally, some examples are provided to justify the validity of our results.


© 2018 IAUCTB. All rights reserved.

Keywords: $b$-metric, digraph, altering distance function, common fixed point.
2010 AMS Subject Classification: $54 \mathrm{H} 25,47 \mathrm{H} 10$.

## 1. Introduction

It is well known that Banach contraction principle [6] in metric spaces is one of the pivotal result in fixed point theory and nonlinear analysis. It remains a source of inspiration for researchers of this domain. Because of its simplicity and usefulness, it becomes an important tool in various research activities. In 1989, Bakhtin [8] introduced the concept of $b$-metric spaces as a generalization of metric spaces and generalized the famous Banach contraction principle in metric spaces to $b$-metric spaces. Recently, the study of fixed point theory with a graph takes a prominent place in many aspects. Many important results of $[2-4,10-12,16,17,20,25]$ have become the source of motivation for many researchers that do research in fixed point theory. Motivated by the work in [5, 14, 24], we will prove some common fixed point results for a pair of self-mappings satisfying some

[^0]new contractive conditions in the setting of $b$-metric spaces. More precisely, we discuss the existence and uniqueness of points of coincidence and common fixed points for mappings satisfying a generalized contractive condition in b-metric spaces endowed with a graph and altering distance functions. Our results extend and unify several existing results in the literature. Finally, we give some examples to justify the validity of our results.

## 2. Some Basic Concepts

In 1984, Khan et. al. [21] introduced the concept of altering distance functions as follows.

Definition 2.1 The function $\varphi:[0,+\infty) \rightarrow[0,+\infty)$ is called an altering distance function if the following properties hold:
(i) $\varphi$ is continuous and non-decreasing.
(ii) $\varphi(t)=0$ if and only if $t=0$.

Now, let us recall some basic notations and definitions in $b$-metric spaces.
Definition 2.2 [13] Let $X$ be a nonempty set and $s \geqslant 1$ be a given real number. A function $d: X \times X \rightarrow \mathbb{R}^{+}$is said to be a $b$-metric on $X$ if the following conditions hold:
(i) $d(x, y)=0$ if and only if $x=y$;
(ii) $d(x, y)=d(y, x)$ for all $x, y \in X$;
(iii) $d(x, y) \leqslant s(d(x, z)+d(z, y))$ for all $x, y, z \in X$.

The pair $(X, d)$ is called a $b$-metric space.
It is worth mentioning that the class of $b$-metric spaces is effectively larger than that of the ordinary metric spaces.

Example 2.3 [24] Let $(X, d)$ be a metric space and $\rho(x, y)=(d(x, y))^{p}$, where $p>1$ is a real number. Then $\rho$ is a $b$-metric with $s=2^{p-1}$.

Example 2.4 [23] Let $X=\{-1,0,1\}$. Define $d: X \times X \rightarrow \mathbb{R}^{+}$by $d(x, y)=d(y, x)$ for all $x, y \in X, d(x, x)=0, x \in X$ and $d(-1,0)=3, d(-1,1)=d(0,1)=1$. Then $(X, d)$ is a $b$-metric space, but not a metric space since the triangle inequality is not satisfied. Indeed, we have that $d(-1,1)+d(1,0)=1+1=2<3=d(-1,0)$. It is easy to verify that $s=\frac{3}{2}$.
Definition 2.5 [9] Let $(X, d)$ be a $b$-metric space, $x \in X$ and $\left(x_{n}\right)$ be a sequence in $X$. Then
(i) $\left(x_{n}\right)$ converges to $x$ if and only if $\lim _{n \rightarrow \infty} d\left(x_{n}, x\right)=0$. We denote this by $\lim _{n \rightarrow \infty} x_{n}=x$ or $x_{n} \rightarrow x$ as $n \rightarrow \infty$.
(ii) $\left(x_{n}\right)$ is Cauchy if and only if $\lim _{n, m \rightarrow \infty} d\left(x_{n}, x_{m}\right)=0$.
(iii) $(X, d)$ is complete if and only if every Cauchy sequence in $X$ is convergent.

Remark 1 [9] In a b-metric space ( $X, d$ ), the following assertions hold:
(i) A convergent sequence has a unique limit.
(ii) Each convergent sequence is Cauchy.
(iii) In general, a b-metric is not continuous.

Lemma 2.6 [3] Let $(X, d)$ be a $b$-metric space with $s \geqslant 1$ and suppose that $\left(x_{n}\right)$ and $\left(y_{n}\right)$ converge to $x, y \in X$, respectively. Then, we have

$$
\frac{1}{s^{2}} d(x, y) \leqslant \liminf _{n \rightarrow \infty} d\left(x_{n}, y_{n}\right) \leqslant \limsup _{n \rightarrow \infty} d\left(x_{n}, y_{n}\right) \leqslant s^{2} d(x, y)
$$

In particular, if $x=y$, then $\lim _{n \rightarrow \infty} d\left(x_{n}, y_{n}\right)=0$. Moreover, we have

$$
\frac{1}{s} d(x, z) \leqslant \liminf _{n \rightarrow \infty} d\left(x_{n}, z\right) \leqslant \limsup _{n \rightarrow \infty} d\left(x_{n}, z\right) \leqslant s d(x, z)
$$

for each $z \in X$.
Definition 2.7 [1] Let $T$ and $S$ be self mappings of a set $X$. If $y=T x=S x$ for some $x$ in $X$, then $x$ is called a coincidence point of $T$ and $S$ and $y$ is called a point of coincidence of $T$ and $S$.

Definition 2.8 [19] The mappings $T, S: X \rightarrow X$ are weakly compatible, if for every $x \in X, T(S x)=S(T x)$ whenever $S x=T x$.

Proposition 2.9 [1] Let $S$ and $T$ be weakly compatible selfmaps of a nonempty set $X$. If $S$ and $T$ have a unique point of coincidence $y=S x=T x$, then $y$ is the unique common fixed point of $S$ and $T$.
Lemma 2.10 [22] Every sequence $\left(x_{n}\right)$ of elements from a $b$-metric space $(X, d)$, having the property that there exists $\gamma \in[0,1)$ such that $d\left(x_{n+1}, x_{n}\right) \leqslant \gamma d\left(x_{n}, x_{n-1}\right)$ for every $n \in \mathbb{N}$, is Cauchy.

We next review some basic notions in graph theory. Let $(X, d)$ be a $b$-metric space. We consider a directed graph $G$ such that the set $V(G)$ of its vertices coincides with $X$ and the set $E(G)$ of its edges contains all the loops, i.e., $\Delta \subseteq E(G)$ where $\Delta=\{(x, x)$ : $x \in X\}$. We also assume that $G$ has no parallel edges. So we can identify $G$ with the pair $(V(G), E(G))$. By $G^{-1}$ we denote the conversion of a graph $G$ i.e., the graph obtained from $G$ by reversing the direction of edges i.e., $E\left(G^{-1}\right)=\{(x, y) \in X \times X:(y, x) \in$ $E(G)\}$. Let $\tilde{G}$ denote the undirected graph obtained from $G$ by ignoring the direction of edges. Actually, it will be more convenient for us to treat $\tilde{G}$ as a digraph for which the set of its edges is symmetric. Under this convention, $E(\tilde{G})=E(G) \cup E\left(G^{-1}\right)$.

Our graph theory notations and terminology are standard and can be found in all graph theory books, like $[7,15,18]$. If $x, y$ are vertices of the digraph $G$, then a path in $G$ from $x$ to $y$ of length $n(n \in \mathbb{N})$ is a sequence $\left(x_{i}\right)_{i=0}^{n}$ of $n+1$ vertices such that $x_{0}=x, x_{n}=y$ and $\left(x_{i-1}, x_{i}\right) \in E(G)$ for $i=1,2, \cdots, n$. A graph $G$ is connected if there is a path between any two vertices of $G$. $G$ is weakly connected if $\tilde{G}$ is connected.

## 3. Main results

Suppose that $(X, d)$ is a $b$-metric space with the coefficient $s \geqslant 1$ and $G$ is a reflexive digraph such that $V(G)=X$ and $G$ has no parallel edges. Let $f, g: X \rightarrow X$ be such that $f(X) \subseteq g(X)$. Let $x_{0} \in X$ be arbitrary. Since $f(X) \subseteq g(X)$, there exists an element $x_{1} \in X$ such that $f x_{0}=g x_{1}$. Continuing in this way, we can construct a sequence $\left(g x_{n}\right)$ such that $g x_{n}=f x_{n-1}, n=1,2,3, \cdots$.
Definition 3.1 [23] Let $(X, d)$ be a $b$-metric space endowed with a graph $G$ and $f, g$ : $X \rightarrow X$ be such that $f(X) \subseteq g(X)$. We define $C_{g f}$ the set of all elements $x_{0}$ of $X$ such that $\left(g x_{n}, g x_{m}\right) \in E(\tilde{G})$ for $m, n=0,1,2, \cdots$ and for every sequence $\left(g x_{n}\right)$ such that $g x_{n}=f x_{n-1}$.

Taking $g=I$, the identity map on $X, C_{g f}$ becomes $C_{f}$ which is the collection of all elements $x$ of $X$ such that $\left(f^{n} x, f^{m} x\right) \in E(\tilde{G})$ for $m, n=0,1,2, \cdots$.

Theorem 3.2 Let $(X, d)$ be a $b$-metric space endowed with a graph $G$ and let $f, g$ : $X \rightarrow X$ be mappings. Suppose that there exist two altering distance functions $\psi$ and $\varphi$ such that

$$
\begin{equation*}
\psi(s d(f x, f y)) \leqslant \psi\left(M_{s}(g x, g y)\right)-\varphi\left(M_{s}(g x, g y)\right) \tag{1}
\end{equation*}
$$

for all $x, y \in X$ with $(g x, g y) \in E(\tilde{G})$, where

$$
M_{s}(g x, g y)=\max \left\{d(g x, g y), d(g y, f y), \frac{d(g x, f y)}{2 s}\right\}
$$

Suppose $f(X) \subseteq g(X)$ and $g(X)$ is a complete subspace of $X$ with the following property:
$(*)$ If $\left(g x_{n}\right)$ is a sequence in $X$ such that $g x_{n} \rightarrow x$ and $\left(g x_{n}, g x_{n+1}\right) \in E(\tilde{G})$ for all $n \geqslant 1$, then there exists a subsequence $\left(g x_{n_{i}}\right)$ of $\left(g x_{n}\right)$ such that $\left(g x_{n_{i}}, x\right) \in E(\tilde{G})$ for all $i \geqslant 1$.
Then $f$ and $g$ have a point of coincidence in $X$ if $C_{g f} \neq \emptyset$. Moreover, $f$ and $g$ have a unique point of coincidence in $X$ if the graph $G$ has the following property:
$(* *)$ If $x, y$ are points of coincidence of $f$ and $g$ in $X$, then $(x, y) \in E(\tilde{G})$.
Furthermore, if $f$ and $g$ are weakly compatible, then $f$ and $g$ have a unique common fixed point in $X$.

Proof. Suppose that $C_{g f} \neq \emptyset$. We choose an $x_{0} \in C_{g f}$ and keep it fixed. Since $f(X) \subseteq g(X)$, there exists a sequence $\left(g x_{n}\right)$ such that $g x_{n}=f x_{n-1}, n=1,2,3, \cdots$ and $\left(g x_{n}, g x_{m}\right) \in E(\tilde{G})$ for $m, n=0,1,2, \cdots$.

We assume that $g x_{n} \neq g x_{n-1}$ for every $n \in \mathbb{N}$. If $g x_{n}=g x_{n-1}$ for some $n \in \mathbb{N}$, then $g x_{n}=f x_{n-1}=g x_{n-1}$ and hence $g x_{n}$ is a point of coincidence of $f$ and $g$. We now show that $\lim _{n \rightarrow \infty} d\left(g x_{n}, g x_{n+1}\right)=0$. Since $\frac{d\left(g x_{n-1}, g x_{n+1}\right)}{2 s} \leqslant \frac{d\left(g x_{n-1}, g x_{n}\right)+d\left(g x_{n}, g x_{n+1}\right)}{2}$, it follows that

$$
\begin{aligned}
M_{s}\left(g x_{n-1}, g x_{n}\right) & =\max \left\{d\left(g x_{n-1}, g x_{n}\right), d\left(g x_{n}, f x_{n}\right), \frac{d\left(g x_{n-1}, f x_{n}\right)}{2 s}\right\} \\
& =\max \left\{d\left(g x_{n-1}, g x_{n}\right), d\left(g x_{n}, g x_{n+1}\right), \frac{d\left(g x_{n-1}, g x_{n+1}\right)}{2 s}\right\} \\
& =\max \left\{d\left(g x_{n-1}, g x_{n}\right), d\left(g x_{n}, g x_{n+1}\right)\right\}
\end{aligned}
$$

For any natural number $n$, we have by using (1) that

$$
\begin{align*}
\psi\left(d\left(g x_{n}, g x_{n+1}\right)\right) \leqslant & \psi\left(s d\left(g x_{n}, g x_{n+1}\right)\right) \\
= & \psi\left(s d\left(f x_{n-1}, f x_{n}\right)\right) \\
\leqslant & \psi\left(M_{s}\left(g x_{n-1}, g x_{n}\right)\right)-\varphi\left(M_{s}\left(g x_{n-1}, g x_{n}\right)\right) \\
= & \psi\left(\max \left\{d\left(g x_{n-1}, g x_{n}\right), d\left(g x_{n}, g x_{n+1}\right)\right\}\right) \\
& -\varphi\left(\max \left\{d\left(g x_{n-1}, g x_{n}\right), d\left(g x_{n}, g x_{n+1}\right)\right\}\right) \\
< & \psi\left(\max \left\{d\left(g x_{n-1}, g x_{n}\right), d\left(g x_{n}, g x_{n+1}\right)\right\}\right) \tag{2}
\end{align*}
$$

If $\max \left\{d\left(g x_{n-1}, g x_{n}\right), d\left(g x_{n}, g x_{n+1}\right)\right\}=d\left(g x_{n}, g x_{n+1}\right)$, then it follows from (2) that

$$
\psi\left(d\left(g x_{n}, g x_{n+1}\right)\right) \leqslant \psi\left(d\left(g x_{n}, g x_{n+1}\right)\right)-\varphi\left(d\left(g x_{n}, g x_{n+1}\right)\right)<\psi\left(d\left(g x_{n}, g x_{n+1}\right)\right)
$$

which is a contradiction. Therefore, $\max \left\{d\left(g x_{n-1}, g x_{n}\right), d\left(g x_{n}, g x_{n+1}\right)\right\}=d\left(g x_{n-1}, g x_{n}\right)$. Thus, (2) reduces to

$$
\begin{equation*}
\psi\left(d\left(g x_{n}, g x_{n+1}\right)\right) \leqslant \psi\left(d\left(g x_{n-1}, g x_{n}\right)\right)-\varphi\left(d\left(g x_{n-1}, g x_{n}\right)\right)<\psi\left(d\left(g x_{n-1}, g x_{n}\right)\right) . \tag{3}
\end{equation*}
$$

Since $\psi$ is non-decreasing, $\left(d\left(g x_{n}, g x_{n+1}\right)\right)_{n \in \mathbb{N} \cup\{0\}}$ is a non-increasing sequence of positive numbers. Hence, there exists $r \geqslant 0$ such that $\lim _{n \rightarrow \infty} d\left(g x_{n}, g x_{n+1}\right)=r$. Taking limit as $n \rightarrow \infty$ in (3), we have $\psi(r) \leqslant \psi(r)-\varphi(r) \leqslant \psi(r)$, which implies that $\varphi(r)=0$ and so, $r=0$. Therefore,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} d\left(g x_{n}, g x_{n+1}\right)=0 . \tag{4}
\end{equation*}
$$

We now show that $\left(g x_{n}\right)$ is Cauchy in $g(X)$. If possible, suppose $\left(g x_{n}\right)$ is not a Cauchy sequence. Then there exists $\epsilon>0$ for which we can find two subsequences $\left(g x_{m_{i}}\right)$ and $\left(g x_{n_{i}}\right)$ of $\left(g x_{n}\right)$ such that $n_{i}$ is the smallest positive integer satisfying

$$
\begin{equation*}
d\left(g x_{m_{i}}, g x_{n_{i}}\right) \geqslant \epsilon \text { for } n_{i}>m_{i}>i . \tag{5}
\end{equation*}
$$

So, it must be the case that

$$
\begin{equation*}
d\left(g x_{m_{i}}, g x_{n_{i}-1}\right)<\epsilon . \tag{6}
\end{equation*}
$$

By using conditions (5) and (6), we obtain

$$
\begin{aligned}
\epsilon & \leqslant d\left(g x_{m_{i}}, g x_{n_{i}}\right) \\
& \leqslant s d\left(g x_{m_{i}}, g x_{m_{i}-1}\right)+s d\left(g x_{m_{i}-1}, g x_{n_{i}}\right) \\
& \leqslant s d\left(g x_{m_{i}}, g x_{m_{i}-1}\right)+s^{2} d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)+s^{2} d\left(g x_{n_{i}-1}, g x_{n_{i}}\right) .
\end{aligned}
$$

Taking the upper limit as $i \rightarrow \infty$ and using (4), we get $\frac{\epsilon}{s^{2}} \leqslant \limsup _{i \rightarrow \infty} d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)$. Again,

$$
d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right) \leqslant s d\left(g x_{m_{i}-1}, g x_{m_{i}}\right)+s d\left(g x_{m_{i}}, g x_{n_{i}-1}\right) .
$$

Taking the upper limit as $i \rightarrow \infty$ and using (4) and (6), then $\limsup _{i \rightarrow \infty} d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right) \leqslant$ $\epsilon s$. Therefore, we obtain

$$
\begin{equation*}
\frac{\epsilon}{s^{2}} \leqslant \limsup _{i \rightarrow \infty} d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right) \leqslant \epsilon s . \tag{7}
\end{equation*}
$$

From condition (5), we have

$$
\begin{aligned}
\epsilon & \leqslant d\left(g x_{m_{i}}, g x_{n_{i}}\right) \\
& \leqslant s d\left(g x_{m_{i}}, g x_{m_{i}-1}\right)+s d\left(g x_{m_{i}-1}, g x_{n_{i}}\right) \\
& \leqslant s d\left(g x_{m_{i}}, g x_{m_{i}-1}\right)+s^{2} d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)+s^{2} d\left(g x_{n_{i}-1}, g x_{n_{i}}\right) .
\end{aligned}
$$

Taking the upper limit as $i \rightarrow \infty$ and using condition (7), it follows that

$$
\begin{equation*}
\frac{\epsilon}{s} \leqslant \limsup _{i \rightarrow \infty} d\left(g x_{m_{i}-1}, g x_{n_{i}}\right) \leqslant \epsilon s^{2} . \tag{8}
\end{equation*}
$$

By using (1), we get

$$
\begin{align*}
\psi\left(s d\left(g x_{m_{i}}, g x_{n_{i}}\right)\right) & =\psi\left(s d\left(f x_{m_{i}-1}, f x_{n_{i}-1}\right)\right) \\
& \leqslant \psi\left(M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)\right)-\varphi\left(M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)\right) \tag{9}
\end{align*}
$$

where

$$
\begin{aligned}
M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right) & =\max \left\{\begin{array}{l}
d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right), d\left(g x_{n_{i}-1}, f x_{n_{i}-1}\right) \\
\frac{d\left(g x_{m_{i}-1}, f x_{n_{i}-1}\right)}{2 s}
\end{array}\right\} \\
& =\max \left\{d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right), d\left(g x_{n_{i}-1}, g x_{n_{i}}\right), \frac{d\left(g x_{m_{i}-1}, g x_{n_{i}}\right)}{2 s}\right\} .
\end{aligned}
$$

Taking the upper limit as $i \rightarrow \infty$ and using conditions (4), (7) and (8), we have

$$
\begin{align*}
\limsup _{i \rightarrow \infty} M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right) & =\max \left\{\begin{array}{l}
\limsup _{i \rightarrow \infty} d\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right), 0 \\
\frac{\limsup _{i \rightarrow \infty} d\left(g x_{m_{i}-1}, g x_{n_{i}}\right)}{2 s}
\end{array}\right\} \\
& \leqslant \max \left\{\epsilon s, \frac{\epsilon s^{2}}{2 s}\right\}=\epsilon s \tag{10}
\end{align*}
$$

From conditions (7) and (10), it follows that

$$
\frac{\epsilon}{s^{2}} \leqslant \limsup _{i \rightarrow \infty} d\left(g x_{m_{i}-1}, g x_{n_{i}-1} \leqslant \limsup _{i \rightarrow \infty} M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right) \leqslant \epsilon s\right.
$$

Therefore,

$$
\begin{equation*}
\frac{\epsilon}{s^{2}} \leqslant \limsup _{i \rightarrow \infty} M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right) \leqslant \epsilon s \tag{11}
\end{equation*}
$$

Similarly,

$$
\begin{equation*}
\frac{\epsilon}{s^{2}} \leqslant \liminf _{i \rightarrow \infty} M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right) \leqslant \epsilon s \tag{12}
\end{equation*}
$$

Taking the upper limit as $i \rightarrow \infty$ in (9) and using conditions (5), (11), it follows that

$$
\begin{aligned}
\psi(\epsilon s) & \leqslant \psi\left(s \limsup _{i \rightarrow \infty} d\left(g x_{m_{i}}, g x_{n_{i}}\right)\right) \\
& \leqslant \psi\left(\limsup _{i \rightarrow \infty} M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)\right)-\liminf _{i \rightarrow \infty} \varphi\left(M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)\right) \\
& \leqslant \psi(\epsilon s)-\varphi\left(\liminf _{i \rightarrow \infty} M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)\right)
\end{aligned}
$$

which gives that $\varphi\left(\liminf _{i \rightarrow \infty} M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)\right)=0$, i.e., $\liminf _{i \rightarrow \infty} M_{s}\left(g x_{m_{i}-1}, g x_{n_{i}-1}\right)=0$. This contradicts the condition (12). Thus, $\left(g x_{n}\right)$ is a Cauchy sequence in $g(X)$. As $g(X)$ is complete, there exists an $u \in g(X)$ such that $g x_{n} \rightarrow u=g v$ for some $v \in X$. As $x_{0} \in C_{g f}$, it follows that $\left(g x_{n}, g x_{n+1}\right) \in E(\tilde{G})$ for all $n \geqslant 0$ and so by property $(*)$, there exists a subsequence $\left(g x_{n_{i}}\right)$ of $\left(g x_{n}\right)$ such that $\left(g x_{n_{i}}, g v\right) \in E(\tilde{G})$ for all $i \geqslant 1$.

Again, using condition (1), we have

$$
\begin{equation*}
\psi\left(s d\left(f v, f x_{n_{i}}\right)\right) \leqslant \psi\left(M_{s}\left(g v, g x_{n_{i}}\right)\right)-\varphi\left(M_{s}\left(g v, g x_{n_{i}}\right)\right) \tag{13}
\end{equation*}
$$

where

$$
\begin{aligned}
M_{s}\left(g v, g x_{n_{i}}\right) & =\max \left\{d\left(g v, g x_{n_{i}}\right), d\left(g x_{n_{i}}, f x_{n_{i}}\right), \frac{d\left(g v, f x_{n_{i}}\right)}{2 s}\right\} \\
& =\max \left\{d\left(g v, g x_{n_{i}}\right), d\left(g x_{n_{i}}, g x_{n_{i}+1}\right), \frac{d\left(g v, g x_{n_{i}+1}\right)}{2 s}\right\} \rightarrow 0 \text { as } i \rightarrow \infty
\end{aligned}
$$

Taking the upper limit as $i \rightarrow \infty$ in (13), it follows that

$$
\psi\left(s \limsup _{i \rightarrow \infty} d\left(f v, f x_{n_{i}}\right)\right) \leqslant \psi(0)-\varphi(0)=0
$$

which implies that $\psi\left(s \limsup _{i \rightarrow \infty} d\left(f v, g x_{n_{i}+1}\right)\right)=0$. Using Lemma 2.6, we obtain that

$$
\psi(d(f v, g v))=\psi\left(s \frac{1}{s} d(f v, g v)\right) \leqslant \psi\left(s \limsup _{i \rightarrow \infty} d\left(f v, g x_{n_{i}+1}\right)\right)=0
$$

This gives that $d(f v, g v)=0$ and hence $f v=g v=u$. Therefore, $u$ is a point of coincidence of $f$ and $g$.

For uniqueness, assume that there is another point of coincidence $u^{*}$ in $X$ such that $f x=g x=u^{*}$ for some $x \in X$. By property $(* *)$, we have $\left(u, u^{*}\right) \in E(\tilde{G})$. Then,

$$
\begin{aligned}
M_{s}\left(u, u^{*}\right) & =M_{s}(g v, g x) \\
& =\max \left\{d(g v, g x), d(g x, f x), \frac{d(g v, f x)}{2 s}\right\} \\
& =\max \left\{d\left(u, u^{*}\right), d\left(u^{*}, u^{*}\right), \frac{d\left(u, u^{*}\right)}{2 s}\right\} \\
& =d\left(u, u^{*}\right)
\end{aligned}
$$

By using condition (1), we get

$$
\begin{aligned}
\psi\left(d\left(u, u^{*}\right)\right) & \leqslant \psi\left(s d\left(u, u^{*}\right)\right)=\psi(s d(f v, f x)) \\
& \leqslant \psi\left(M_{s}(g v, g x)\right)-\varphi\left(M_{s}(g v, g x)\right)=\psi\left(d\left(u, u^{*}\right)\right)-\varphi\left(d\left(u, u^{*}\right)\right)
\end{aligned}
$$

which gives that $\varphi\left(d\left(u, u^{*}\right)\right)=0$ i.e., $d\left(u, u^{*}\right)=0$ and hence, $u=u^{*}$. Therefore, $f$ and $g$ have a unique point of coincidence in $X$. If $f$ and $g$ are weakly compatible, then by Proposition 2.9, $f$ and $g$ have a unique common fixed point in $X$.

Corollary 3.3 Let $(X, d)$ be a $b$-metric space endowed with a graph $G$ and let $f, g$ : $X \rightarrow X$ be mappings. Suppose that there exists $k \in[0,1)$ such that

$$
d(f x, f y) \leqslant \frac{k}{s} \max \left\{d(g x, g y), d(g y, f y), \frac{d(g x, f y)}{2 s}\right\}
$$

for all $x, y \in X$ with $(g x, g y) \in E(\tilde{G})$. Suppose $f(X) \subseteq g(X)$ and $g(X)$ is a complete subspace of $X$ with the property ( $*$ ). Then $f$ and $g$ have a point of coincidence in $X$ if $C_{g f} \neq \emptyset$. Moreover, $f$ and $g$ have a unique point of coincidence in $X$ if the graph $G$ has the property $(* *)$. Furthermore, if $f$ and $g$ are weakly compatible, then $f$ and $g$ have a unique common fixed point in $X$.

Proof. The proof follows from Theorem 3.2 by taking $\psi(t)=t$ and $\varphi(t)=(1-k) t$ for all $t \in[0,+\infty)$.

Corollary 3.4 Let $(X, d)$ be a complete $b$-metric space endowed with a graph $G$ and let $f: X \rightarrow X$ be a mapping. Suppose that there exist two altering distance functions $\psi$ and $\varphi$ such that

$$
\psi(s d(f x, f y)) \leqslant \psi\left(M_{s}(x, y)\right)-\varphi\left(M_{s}(x, y)\right)
$$

for all $x, y \in X$ with $(x, y) \in E(\tilde{G})$, where $M_{s}(x, y)=\max \left\{d(x, y), d(y, f y), \frac{d(x, f y)}{2 s}\right\}$. Suppose the triple ( $X, d, G$ ) has the following property:
$(*)$ If $\left(x_{n}\right)$ is a sequence in $X$ such that $x_{n} \rightarrow x$ and $\left(x_{n}, x_{n+1}\right) \in E(\tilde{G})$ for all $n \geqslant 1$, then there exists a subsequence $\left(x_{n_{i}}\right)$ of $\left(x_{n}\right)$ such that $\left(x_{n_{i}}, x\right) \in E(\tilde{G})$ for all $i \geqslant 1$.
Then $f$ has a fixed point in $X$ if $C_{f} \neq \emptyset$. Moreover, $f$ has a unique fixed point in $X$ if the graph $G$ has the following property:

$$
(* *) \text { If } x, y \text { are fixed points of } f \text { in } X \text {, then }(x, y) \in E(\tilde{G}) \text {. }
$$

Proof. The proof can be obtained from Theorem 3.2 by considering $g=I$, the identity map on $X$.
Corollary 3.5 Let $(X, d)$ be a $b$-metric space and let $f, g: X \rightarrow X$ be mappings. Suppose that there exist two altering distance functions $\psi$ and $\varphi$ such that

$$
\psi(s d(f x, f y)) \leqslant \psi\left(M_{s}(g x, g y)\right)-\varphi\left(M_{s}(g x, g y)\right)
$$

for all $x, y \in X$. If $f(X) \subseteq g(X)$ and $g(X)$ is a complete subspace of $X$, then $f$ and $g$ have a unique point of coincidence in $X$. Moreover, if $f$ and $g$ are weakly compatible, then $f$ and $g$ have a unique common fixed point in $X$.

Proof. The proof follows from Theorem 3.2 by taking $G=G_{0}$, where $G_{0}$ is the complete graph $(X, X \times X)$.
Corollary 3.6 Let $(X, d)$ be a complete $b$-metric space and let $f: X \rightarrow X$ be a mapping. Suppose that there exist two altering distance functions $\psi$ and $\varphi$ such that

$$
\psi(s d(f x, f y)) \leqslant \psi\left(M_{s}(x, y)\right)-\varphi\left(M_{s}(x, y)\right)
$$

for all $x, y \in X$. Then $f$ has a unique fixed point in $X$.
Proof. It follows from Theorem 3.2 by putting $G=G_{0}$ and $g=I$.

Corollary 3.7 Let $(X, d)$ be a complete $b$-metric space endowed with a partial ordering $\preceq$ and let $f: X \rightarrow X$ be a mapping. Suppose that there exist two altering distance functions $\psi$ and $\varphi$ such that

$$
\psi(s d(f x, f y)) \leqslant \psi\left(M_{s}(x, y)\right)-\varphi\left(M_{s}(x, y)\right)
$$

for all $x, y \in X$ with $x \preceq y$ or, $y \preceq x$. Suppose the triple $(X, d, \preceq)$ has the following property:
$(\dagger)$ If $\left(x_{n}\right)$ is a sequence in $X$ such that $x_{n} \rightarrow x$ and $x_{n}, x_{n+1}$ are comparable for all $n \geqslant 1$, then there exists a subsequence $\left(x_{n_{i}}\right)$ of $\left(x_{n}\right)$ such that $x_{n_{i}}, x$ are comparable for all $i \geqslant 1$.
If there exists $x_{0} \in X$ such that $f^{n} x_{0}, f^{m} x_{0}$ are comparable for $m, n=0,1,2, \cdots$, then $f$ has a fixed point in $X$. Moreover, $f$ has a unique fixed point in $X$ if the following property holds:
( $\dagger \dagger$ ) If $x, y$ are fixed points of $f$ in $X$, then $x, y$ are comparable.
Proof. The proof can be obtained from Theorem 3.2 by taking $g=I$ and $G=G_{2}$, where the graph $G_{2}$ is defined by $E\left(G_{2}\right)=\{(x, y) \in X \times X: x \preceq y$ or $y \preceq x\}$.

Before presenting our second main theorem, we need the following definition.
Definition 3.8 Let $(X, d)$ be a $b$-metric space endowed with a graph $G$ and $f, T$ : $X \rightarrow X$ be two mappings. We define $C_{f \vee T}$ the set of all elements $x_{0}$ of $X$ such that $\left(x_{n}, x_{m}\right) \in E(\tilde{G})$ for $m, n=0,1,2, \cdots$ and for every sequence $\left(x_{n}\right)$ such that $x_{n}=f x_{n-1}$ if $n$ is odd and $x_{n}=T x_{n-1}$ if $n$ is even.

Taking $T=f, C_{f \vee T}$ reduces to $C_{f}$ which is the collection of all elements $x$ of $X$ such that $\left(f^{n} x, f^{m} x\right) \in E(\tilde{G})$ for $m, n=0,1,2, \cdots$.
Theorem 3.9 Let $(X, d)$ be a complete $b$-metric space endowed with a graph $G$ and let $f, T: X \rightarrow X$ be mappings. Suppose that there exist two altering distance functions $\psi$ and $\varphi$ such that

$$
\begin{equation*}
\psi\left(s^{4} d(f x, T y)\right) \leqslant \psi\left(N_{s}(x, y)\right)-\varphi\left(N_{s}(x, y)\right) \tag{14}
\end{equation*}
$$

for all $x, y \in X$ with $(x, y) \in E(\tilde{G})$, where

$$
N_{s}(x, y)=\max \left\{d(x, y), \min \{d(x, f x), d(y, T y)\}, \frac{1}{2 s} \min \{d(x, T y), d(y, f x)\}\right\}
$$

Suppose the triple $(X, d, G)$ has the property $(*)$. Then $f$ and $T$ have a common fixed point in $X$ if $C_{f \vee T} \neq \emptyset$. Moreover, $f$ and $T$ have a unique common fixed point in $X$ if the graph $G$ has the following property:
$(\ddagger)$ If $x, y$ are common fixed points of $f$ and $T$ in $X$, then $(x, y) \in E(\tilde{G})$.
Proof. We first prove that $u$ is a fixed point of $T$ if and only if $u$ is a fixed point of $f$. Suppose that $u$ is a fixed point of $T$ i.e., $T u=u$. Then, by using condition (14), we obtain

$$
\psi\left(s^{4} d(f u, u)\right)=\psi\left(s^{4} d(f u, T u)\right) \leqslant \psi\left(N_{s}(u, u)\right)-\varphi\left(N_{s}(u, u)\right)
$$

where

$$
N_{s}(u, u)=\max \left\{d(u, u), \min \{d(u, f u), d(u, T u)\}, \frac{1}{2 s} \min \{d(u, T u), d(u, f u)\}\right\}=0
$$

Therefore, $\psi\left(s^{4} d(f u, u)\right) \leqslant \psi(0)-\varphi(0)=0$, which implies that $d(f u, u)=0$ i.e., $f u=u$. By an argument similar to that used above, we can show that if $u$ is a fixed point of $f$, then $u$ is also a fixed point of $T$.

Suppose that $C_{f \vee T} \neq \emptyset$. We choose an $x_{0} \in C_{f \vee T}$ and keep it fixed. We can construct a sequence $\left(x_{n}\right)$ in $X$ such that $x_{n}=f x_{n-1}$ if $n$ is odd and $x_{n}=T x_{n-1}$ if $n$ is even, and $\left(x_{n}, x_{m}\right) \in E(G)$ for $m, n=0,1,2, \cdots$.

We assume that $x_{n} \neq x_{n-1}$ for every $n \in \mathbb{N}$. If $x_{2 n}=x_{2 n+1}$ for some $n \in \mathbb{N} \cup\{0\}$, then $x_{2 n}=f x_{2 n}$. So, $x_{2 n}$ is a fixed point of $f$. By our previous discussion, it follows that $x_{2 n}$ is also a fixed point of $T$. If $x_{2 n+1}=x_{2 n+2}$ for some $n \in \mathbb{N} \cup\{0\}$, then $x_{2 n+1}=T x_{2 n+1}$ which gives that, $x_{2 n+1}$ is a fixed point of $T$. Therefore, it follows from our previous observation that $x_{2 n+1}$ is a fixed point of $f$. We now show that $\lim _{n \rightarrow \infty} d\left(x_{n}, x_{n+1}\right)=0$. As $\left(x_{2 n}, x_{2 n+1}\right) \in E(\tilde{G})$, by using condition (14), we obtain

$$
\begin{aligned}
\psi\left(d\left(x_{2 n+1}, x_{2 n+2}\right)\right) & \leqslant \psi\left(s^{4} d\left(x_{2 n+1}, x_{2 n+2}\right)\right) \\
& =\psi\left(s^{4} d\left(f x_{2 n}, T x_{2 n+1}\right)\right) \\
& \leqslant \psi\left(N_{s}\left(x_{2 n}, x_{2 n+1}\right)\right)-\varphi\left(N_{s}\left(x_{2 n}, x_{2 n+1}\right)\right)
\end{aligned}
$$

where

$$
\begin{aligned}
N_{s}\left(x_{2 n}, x_{2 n+1}\right) & =\max \left\{\begin{array}{l}
d\left(x_{2 n}, x_{2 n+1}\right), \min \left\{d\left(x_{2 n}, f x_{2 n}\right), d\left(x_{2 n+1}, T x_{2 n+1}\right)\right\} \\
\frac{1}{2 s} \min \left\{d\left(x_{2 n}, T x_{2 n+1}\right), d\left(x_{2 n+1}, f x_{2 n}\right)\right\}
\end{array}\right\} \\
& =\max \left\{\begin{array}{l}
d\left(x_{2 n}, x_{2 n+1}\right), \min \left\{d\left(x_{2 n}, x_{2 n+1}\right), d\left(x_{2 n+1}, x_{2 n+2}\right)\right\}, \\
\frac{1}{2 s} \min \left\{d\left(x_{2 n}, x_{2 n+2}\right), d\left(x_{2 n+1}, x_{2 n+1}\right)\right\}
\end{array}\right\} \\
& =d\left(x_{2 n}, x_{2 n+1}\right) .
\end{aligned}
$$

Therefore,

$$
\begin{align*}
\psi\left(d\left(x_{2 n+1}, x_{2 n+2}\right)\right) & \leqslant \psi\left(d\left(x_{2 n}, x_{2 n+1}\right)\right)-\varphi\left(d\left(x_{2 n}, x_{2 n+1}\right)\right) \\
& <\psi\left(d\left(x_{2 n}, x_{2 n+1}\right)\right) \tag{15}
\end{align*}
$$

Similarly, since $N_{s}\left(x_{2 n}, x_{2 n-1}\right)=d\left(x_{2 n}, x_{2 n-1}\right)$, we have

$$
\begin{align*}
\psi\left(d\left(x_{2 n}, x_{2 n+1}\right)\right) & \leqslant \psi\left(s^{4} d\left(x_{2 n}, x_{2 n+1}\right)\right) \\
& =\psi\left(s^{4} d\left(f x_{2 n}, T x_{2 n-1}\right)\right) \\
& \leqslant \psi\left(N_{s}\left(x_{2 n}, x_{2 n-1}\right)\right)-\varphi\left(N_{s}\left(x_{2 n}, x_{2 n-1}\right)\right) \\
& =\psi\left(d\left(x_{2 n}, x_{2 n-1}\right)\right)-\varphi\left(d\left(x_{2 n}, x_{2 n-1}\right)\right) \\
& <\psi\left(d\left(x_{2 n-1}, x_{2 n}\right)\right) \tag{16}
\end{align*}
$$

Combining conditions (15) and (16), we get $\psi\left(d\left(x_{n}, x_{n+1}\right)\right)<\psi\left(d\left(x_{n-1}, x_{n}\right)\right)$ for all $n \in \mathbb{N}$. Since $\psi$ is non-decreasing, $\left(d\left(x_{n}, x_{n+1}\right)\right)_{n \in \mathbb{N}}$ is a non-increasing sequence of positive numbers. Hence there exists $r \geqslant 0$ such that $\lim _{n \rightarrow \infty} d\left(x_{n}, x_{n+1}\right)=r$. Taking limit as $n \rightarrow \infty$ in (15), we have $\psi(r) \leqslant \psi(r)-\varphi(r) \leqslant \psi(r)$, which implies that $\varphi(r)=0$ and so, $r=0$.

Therefore,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} d\left(x_{n}, x_{n+1}\right)=0 \tag{17}
\end{equation*}
$$

We shall show that $\left(x_{n}\right)$ is a Cauchy sequence in $X$. It is sufficient to show that $\left(x_{2 n}\right)$ is a Cauchy sequence. If possible, suppose that $\left(x_{2 n}\right)$ is not a Cauchy sequence. Then there exists $\epsilon>0$ for which we can find two subsequences $\left(x_{2 m_{i}}\right)$ and $\left(x_{2 n_{i}}\right)$ of $\left(x_{2 n}\right)$ such that $n_{i}$ is the smallest positive integer for which

$$
\begin{equation*}
d\left(x_{2 m_{i}}, x_{2 n_{i}}\right) \geqslant \epsilon \text { for } n_{i}>m_{i}>i . \tag{18}
\end{equation*}
$$

This implies that

$$
\begin{equation*}
d\left(x_{2 m_{i}}, x_{2 n_{i}-2}\right)<\epsilon \tag{19}
\end{equation*}
$$

By repeated use of the triangular inequality and by condition (19), we have

$$
\begin{aligned}
d\left(x_{2 n_{i}+1}, x_{2 m_{i}}\right) \leqslant & s d\left(x_{2 n_{i}+1}, x_{2 n_{i}}\right)+s d\left(x_{2 n_{i}}, x_{2 m_{i}}\right) \\
\leqslant & s d\left(x_{2 n_{i}+1}, x_{2 n_{i}}\right)+s^{2} d\left(x_{2 n_{i}}, x_{2 n_{i}-1}\right) \\
& +s^{3} d\left(x_{2 n_{i}-1}, x_{2 n_{i}-2}\right)+s^{3} d\left(x_{2 n_{i}-2}, x_{2 m_{i}}\right) \\
< & s d\left(x_{2 n_{i}+1}, x_{2 n_{i}}\right)+s^{2} d\left(x_{2 n_{i}}, x_{2 n_{i}-1}\right) \\
& +s^{3} d\left(x_{2 n_{i}-1}, x_{2 n_{i}-2}\right)+\epsilon s^{3} .
\end{aligned}
$$

Taking the upper limit as $i \rightarrow \infty$, then $\limsup _{i \rightarrow \infty} d\left(x_{2 n_{i}+1}, x_{2 m_{i}}\right) \leqslant \epsilon s^{3}$. From (18), we get

$$
\epsilon \leqslant d\left(x_{2 m_{i}}, x_{2 n_{i}}\right) \leqslant s d\left(x_{2 m_{i}}, x_{2 n_{i}+1}\right)+s d\left(x_{2 n_{i}+1}, x_{2 n_{i}}\right)
$$

Taking the upper limit as $i \rightarrow \infty$, we get $\frac{\epsilon}{s} \leqslant \limsup _{i \rightarrow \infty} d\left(x_{2 m_{i}}, x_{2 n_{i}+1}\right)$. Therefore,

$$
\begin{equation*}
\frac{\epsilon}{s} \leqslant \limsup _{i \rightarrow \infty} d\left(x_{2 m_{i}}, x_{2 n_{i}+1}\right) \leqslant \epsilon s^{3} \tag{20}
\end{equation*}
$$

Again,

$$
\begin{aligned}
d\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right) \leqslant & s d\left(x_{2 n_{i}}, x_{2 n_{i}-1}\right)+s d\left(x_{2 n_{i}-1}, x_{2 m_{i}-1}\right) \\
\leqslant & s d\left(x_{2 n_{i}}, x_{2 n_{i}-1}\right)+s^{2} d\left(x_{2 n_{i}-1}, x_{2 n_{i}-2}\right) \\
& +s^{3} d\left(x_{2 n_{i}-2}, x_{2 m_{i}}\right)+s^{3} d\left(x_{2 m_{i}}, x_{2 m_{i}-1}\right)
\end{aligned}
$$

Taking the upper limit as $i \rightarrow \infty$, we obtain $\limsup _{n \rightarrow \infty} d\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right) \leqslant \epsilon s^{3}$. Also,

$$
\epsilon \leqslant d\left(x_{2 n_{i}}, x_{2 m_{i}}\right) \leqslant s d\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)+s d\left(x_{2 m_{i}-1}, x_{2 m_{i}}\right)
$$

Taking the upper limit as $i \rightarrow \infty$, we get $\frac{\epsilon}{s} \leqslant \limsup _{i \rightarrow \infty} d\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)$. Thus,

$$
\begin{equation*}
\frac{\epsilon}{s} \leqslant \limsup _{i \rightarrow \infty} d\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right) \leqslant \epsilon s^{3} . \tag{21}
\end{equation*}
$$

Similarly, we can obtain

$$
\begin{equation*}
\epsilon \leqslant \limsup _{i \rightarrow \infty} d\left(x_{2 n_{i}}, x_{2 m_{i}}\right) \leqslant \epsilon s^{4} \tag{22}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\epsilon}{s^{2}} \leqslant \limsup _{i \rightarrow \infty} d\left(x_{2 n_{i}+1}, x_{2 m_{i}-1}\right) \leqslant \epsilon s^{4} . \tag{23}
\end{equation*}
$$

As $\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right) \in E(\tilde{G})$, by using condition (14), we obtain

$$
\begin{align*}
\psi\left(s^{4} d\left(x_{2 n_{i}+1}, x_{2 m_{i}}\right)\right) & =\psi\left(s^{4} d\left(f x_{2 n_{i}}, T x_{2 m_{i}-1}\right)\right) \\
& \leqslant \psi\left(N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)\right)-\varphi\left(N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)\right) \tag{24}
\end{align*}
$$

where

$$
\begin{align*}
N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right) & =\max \left\{\begin{array}{l}
d\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right), \min \left\{d\left(x_{2 n_{i}}, f x_{2 n_{i}}\right), d\left(x_{2 m_{i}-1}, T x_{2 m_{i}-1}\right)\right\}, \\
\frac{1}{2 s} \min \left\{d\left(x_{2 n_{i}}, T x_{2 m_{i}-1}\right), d\left(x_{2 m_{i}-1}, f x_{2 n_{i}}\right)\right\}
\end{array}\right\} \\
& =\max \left\{\begin{array}{l}
d\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right), \min \left\{d\left(x_{2 n_{i}}, x_{2 n_{i}+1}\right), d\left(x_{2 m_{i}-1}, x_{2 m_{i}}\right)\right\}, \\
\frac{1}{2 s} \min \left\{d\left(x_{2 n_{i}}, x_{2 m_{i}}\right), d\left(x_{2 m_{i}-1}, x_{2 n_{i}+1}\right)\right\}
\end{array}\right\} . \tag{25}
\end{align*}
$$

Taking the upper limit as $i \rightarrow \infty$ in (25) and using conditions (17), (21)-(23), we get

$$
\begin{aligned}
\frac{\epsilon}{2 s^{3}}=\min \left[\frac{\epsilon}{s}, \frac{\epsilon}{2 s}, \frac{1}{2 s} \frac{\epsilon}{s^{2}}\right] & \leqslant \limsup _{i \rightarrow \infty} N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right) \\
& =\max \left\{\begin{array}{l}
\limsup _{i \rightarrow \infty} d\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right), 0, \\
\frac{1}{2 s} \min \left\{\limsup _{i \rightarrow \infty} d\left(x_{2 n_{i}}, x_{2 m_{i}}\right),\right. \\
\left.\limsup _{i \rightarrow \infty} d\left(x_{2 m_{i}-1}, x_{2 n_{i}+1}\right)\right\}
\end{array}\right\} \\
& \leqslant \max \left\{\epsilon s^{3}, \frac{1}{2 s} \epsilon s^{4}\right\}=\epsilon s^{3} .
\end{aligned}
$$

Therefore,

$$
\begin{equation*}
\frac{\epsilon}{2 s^{3}} \leqslant \limsup _{i \rightarrow \infty} N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right) \leqslant \epsilon s^{3} . \tag{26}
\end{equation*}
$$

Similarly, we can obtain

$$
\begin{equation*}
\frac{\epsilon}{2 s^{3}} \leqslant \liminf _{i \rightarrow \infty} N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right) \leqslant \epsilon s^{3} . \tag{27}
\end{equation*}
$$

Taking the upper limit as $i \rightarrow \infty$ in (24) and using conditions (20), (26), (27), we get

$$
\begin{aligned}
\psi\left(\epsilon s^{3}\right)=\psi\left(s^{4} \frac{\epsilon}{s}\right) & \leqslant \psi\left(s^{4} \limsup _{i \rightarrow \infty} d\left(x_{2 n_{i}+1}, x_{2 m_{i}}\right)\right) \\
& \leqslant \psi\left(\limsup _{i \rightarrow \infty} N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)\right)-\liminf _{i \rightarrow \infty} \varphi\left(N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)\right) \\
& \leqslant \psi\left(\epsilon s^{3}\right)-\varphi\left(\liminf _{i \rightarrow \infty} N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)\right),
\end{aligned}
$$

which implies that $\varphi\left(\liminf _{i \rightarrow \infty} N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)\right)=0$. Consequently, it follows that $\liminf _{i \rightarrow \infty} N_{s}\left(x_{2 n_{i}}, x_{2 m_{i}-1}\right)=\stackrel{i \rightarrow \infty}{0}$, a contradiction to (27). Therefore, $\left(x_{n}\right)$ is a Cauchy sequence in $X$. Since $(X, d)$ is complete, there exists an $u \in X$ such that $x_{n} \rightarrow u$ as $n \rightarrow \infty$. As $\left(x_{n}, x_{n+1}\right) \in E(\tilde{G})$ for all $n \geqslant 0$, so by property $(*)$, there exists a subsequence $\left(x_{n_{i}}\right)$ of $\left(x_{n}\right)$ such that $\left(x_{n_{i}}, u\right) \in E(\tilde{G})$ for all $i \geqslant 1$. If $n_{i}$ is even, then $x_{n_{i}+1}=f x_{n_{i}}$. So, by using condition (14), we obtain

$$
\begin{equation*}
\psi\left(s^{4} d\left(x_{n_{i}+1}, T u\right)\right)=\psi\left(s^{4} d\left(f x_{n_{i}}, T u\right)\right) \leqslant \psi\left(N_{s}\left(x_{n_{i}}, u\right)\right)-\varphi\left(N_{s}\left(x_{n_{i}}, u\right)\right), \tag{28}
\end{equation*}
$$

where

$$
\begin{aligned}
N_{s}\left(x_{n_{i}}, u\right) & =\max \left\{\begin{array}{l}
d\left(x_{n_{i}}, u\right), \min \left\{d\left(x_{n_{i}}, f x_{n_{i}}\right), d(u, T u)\right\}, \\
\frac{1}{2 s} \min \left\{d\left(x_{n_{i}}, T u\right), d\left(u, f x_{n_{i}}\right)\right\}
\end{array}\right\} \\
& \leqslant \max \left\{\begin{array}{l}
d\left(x_{n_{i}}, u\right), d\left(x_{n_{i}}, x_{n_{i}+1}\right), \\
\frac{1}{2 s} d\left(u, x_{n_{i}+1}\right)
\end{array}\right\} \rightarrow 0 \text { as } i \rightarrow \infty .
\end{aligned}
$$

Therefore, taking the upper limit as $i \rightarrow \infty$ in (28), we have

$$
\begin{aligned}
\psi\left(s^{4} \limsup _{i \rightarrow \infty} d\left(x_{n_{i}+1}, T u\right)\right) & \leqslant \psi\left(\limsup _{i \rightarrow \infty} N_{s}\left(x_{n_{i}}, u\right)\right)-\varphi\left(\liminf _{i \rightarrow \infty} N_{s}\left(x_{n_{i}}, u\right)\right) \\
& =\psi(0)-\varphi(0)=0
\end{aligned}
$$

which gives that $\psi\left(s^{4} \limsup _{i \rightarrow \infty} d\left(x_{n_{i}+1}, T u\right)\right)=0$. By using Lemma 2.6, we have

$$
\psi\left(s^{3} d(u, T u)\right)=\psi\left(s^{4} \frac{1}{s} d(u, T u)\right) \leqslant \psi\left(s^{4} \limsup _{i \rightarrow \infty} d\left(x_{n_{i}+1}, T u\right)\right)=0
$$

which gives that $d(u, T u)=0$ i.e., $T u=u$ and hence by our previous observation, $u$ is also a fixed point of $f$. If $n_{i}$ is odd, then proceeding as above, we can show that $f u=u$. Therefore, $u$ is a common fixed point of $f$ and $T$.

For uniqueness, let $v$ be another common fixed point of $f$ and $T$ in $X$. By property
( $\ddagger$ ), we have $(u, v) \in E(\tilde{G})$. Then

$$
\begin{aligned}
N_{s}(u, v) & =\max \left\{\begin{array}{l}
d(u, v), \min \{d(u, f u), d(v, T v)\} \\
\frac{1}{2 s} \min \{d(u, T v), d(v, f u)\}
\end{array}\right\} \\
& =\max \left\{d(u, v), 0, \frac{1}{2 s} d(u, v)\right\} \\
& =d(u, v)
\end{aligned}
$$

As $(u, v) \in E(\tilde{G})$, we have

$$
\begin{aligned}
\psi(d(u, v)) & \leqslant \psi\left(s^{4} d(u, v)\right)=\psi\left(s^{4} d(f u, T v)\right) \\
& \leqslant \psi\left(N_{s}(u, v)\right)-\varphi\left(N_{s}(u, v)\right)=\psi(d(u, v))-\varphi(d(u, v))
\end{aligned}
$$

which implies that $\varphi(d(u, v))=0$ and hence $d(u, v)=0$ i.e., $u=v$. Therefore, $f$ and $T$ have a unique common fixed point in $X$.

Corollary 3.10 Let $(X, d)$ be a complete $b$-metric space endowed with a graph $G$ and let $f, T: X \rightarrow X$ be mappings. Suppose that there exists $k \in[0,1)$ such that

$$
d(f x, T y) \leqslant \frac{k}{s^{4}} \max \left\{d(x, y), \min \{d(x, f x), d(y, T y)\}, \frac{1}{2 s} \min \{d(x, T y), d(y, f x)\}\right\}
$$

for all $x, y \in X$ with $(x, y) \in E(\tilde{G})$. Suppose the triple $(X, d, G)$ has the property ( $*$ ). Then $f$ and $T$ have a common fixed point in $X$ if $C_{f \vee T} \neq \emptyset$. Moreover, $f$ and $T$ have a unique common fixed point in $X$ if the graph $G$ has the property ( $\ddagger$ ).
Proof. The proof follows from Theorem 3.9 by considering altering distance functions $\psi(t)=t$ and $\varphi(t)=(1-k) t$ for all $t \in[0,+\infty)$.
Corollary 3.11 Let $(X, d)$ be a complete $b$-metric space endowed with a graph $G$ and let $f: X \rightarrow X$ be a mapping. Suppose that there exists $k \in[0,1)$ such that

$$
d(f x, f y) \leqslant \frac{k}{s^{4}} \max \left\{d(x, y), \min \{d(x, f x), d(y, f y)\}, \frac{1}{2 s} \min \{d(x, f y), d(y, f x)\}\right\}
$$

for all $x, y \in X$ with $(x, y) \in E(\tilde{G})$. Suppose the triple ( $X, d, G$ ) has the property ( $*$ ). Then $f$ has a fixed point in $X$ if $C_{f} \neq \emptyset$. Moreover, $f$ has a unique fixed point in $X$ if the graph $G$ has the following property:
$(\ddagger)$ If $x, y$ are fixed points of $f$ in $X$, then $(x, y) \in E(\tilde{G})$.
Proof. The proof follows from Theorem 3.9 by considering $T=f$ and altering distance functions $\psi(t)=t$ and $\varphi(t)=(1-k) t$ for all $t \in[0,+\infty)$.

Corollary 3.12 Let $(X, d)$ be a complete $b$-metric space and let $f, T: X \rightarrow X$ be mappings. Suppose that there exist two altering distance functions $\psi$ and $\varphi$ such that

$$
\psi\left(s^{4} d(f x, T y)\right) \leqslant \psi\left(N_{s}(x, y)\right)-\varphi\left(N_{s}(x, y)\right)
$$

for all $x, y \in X$. Then $f$ and $T$ have a unique common fixed point in $X$.
Proof. The proof can be obtained from Theorem 3.9 by putting $G=G_{0}$.

Corollary 3.13 Let $(X, d)$ be a complete $b$-metric space endowed with a partial ordering $\preceq$ and let $f: X \rightarrow X$ be a mapping. Suppose that there exist two altering distance functions $\psi$ and $\varphi$ such that

$$
\psi\left(s^{4} d(f x, f y)\right) \leqslant \psi\left(N_{s}^{\prime}(x, y)\right)-\varphi\left(N_{s}^{\prime}(x, y)\right)
$$

for all $x, y \in X$ with $x \preceq y$ or, $y \preceq x$, where

$$
N_{s}^{\prime}(x, y)=\max \left\{d(x, y), \min \{d(x, f x), d(y, f y)\}, \frac{1}{2 s} \min \{d(x, f y), d(y, f x)\}\right\}
$$

Suppose the triple $(X, d, \preceq)$ has the property $(\dagger)$. If there exists $x_{0} \in X$ such that $f^{n} x_{0}, f^{m} x_{0}$ are comparable for $m, n=0,1,2, \cdots$, then $f$ has a fixed point in $X$. Moreover, $f$ has a unique fixed point in $X$ if the property ( $\dagger \dagger$ ) holds.

Proof. The proof can be obtained from Theorem 3.9 by taking $G=G_{2}$ and $T=f$.
Remark 2 If we take $\psi(t)=t$ and $\varphi(t)=(1-k) t$ for all $t \in[0,+\infty)$, where $k \in[0,1)$ is a constant, then conditions (1) and (14) reduce to

$$
d(f x, f y) \leqslant \frac{k}{s} M_{s}(g x, g y) \text { andd }(f x, T y) \leqslant \frac{k}{s^{4}} N_{s}(x, y)
$$

respectively. Corollaries 3.3 and 3.10 give a unique common fixed point of a pair of mappings satisfying above mentioned contractive type conditions. However, it is valuable to note that without altering distance functions, one can finds a unique common fixed point of a pair of mappings satisfying above types of contractive conditions by using Lemma 2.10.

We furnish some examples in favour of our results.
Example 3.14 Let $X=\mathbb{R}$ and define $d: X \times X \rightarrow \mathbb{R}^{+}$by $d(x, y)=|x-y|^{2}$ for all $x, y \in X$. Then $(X, d)$ is a $b$-metric space with the coefficient $s=2$. Let $G$ be a digraph such that $V(G)=X$ and $E(G)=\Delta \cup\{(x, y): x \leqslant y$ with $x, y \in[0, \infty)\}$.

Let $f, g: X \rightarrow X$ be defined by $f x=\frac{x}{2}$ if $x \in 2 \mathbb{Z}$ and otherwise, $f x=0$, and $g x=3 x$ if $x \in[0, \infty)$ and otherwise, $g x=[x]$ if $x \in(-\infty, 0)$. Obviously, $f(X) \subseteq g(X)$ and $g(X)$ is a complete subspace of $X$. Also, define altering distance functions $\psi, \varphi:[0, \infty) \rightarrow[0, \infty)$ by $\psi(t)=t, \varphi(t)=(1-k) t$ where $k=\frac{1}{8}$. We now verify that condition (1) holds for all $x, y \in X$ with $(g x, g y) \in E(\tilde{G})$. Let $x, y \in X$ with $(g x, g y) \in E(\tilde{G})$.
Case-I: If $x, y \in X \backslash 2 \mathbb{Z}$, then

$$
\psi(s d(f x, f y))=0 \leqslant \psi\left(M_{s}(g x, g y)\right)-\varphi\left(M_{s}(g x, g y)\right)
$$

Case-II: If $x, y \in 2 \mathbb{Z}$, then

$$
\begin{aligned}
\psi(s d(f x, f y)) & =\psi\left(2 d\left(\frac{x}{2}, \frac{y}{2}\right)\right)=2\left(\frac{x}{2}-\frac{y}{2}\right)^{2} \\
& =\frac{1}{2}(x-y)^{2} \leqslant \frac{9}{8}(x-y)^{2} \\
& =k d(g x, g y) \leqslant k M_{s}(g x, g y) \\
& =\psi\left(M_{s}(g x, g y)\right)-\varphi\left(M_{s}(g x, g y)\right)
\end{aligned}
$$

Thus,

$$
\psi(s d(f x, f y)) \leqslant \psi\left(M_{s}(g x, g y)\right)-\varphi\left(M_{s}(g x, g y)\right)
$$

for all $x, y \in X$ with $(g x, g y) \in E(\tilde{G})$.
We can verify that $0 \in C_{g f}$. In fact, $g x_{n}=f x_{n-1}, n=1,2,3, \cdots$ gives that $g x_{1}=$ $f 0=0 \Rightarrow x_{1}=0$ and so $g x_{2}=f x_{1}=0 \Rightarrow x_{2}=0$. Proceeding in this way, we get $g x_{n}=0$ for $n=0,1,2, \cdots$ and hence $\left(g x_{n}, g x_{m}\right)=(0,0) \in E(\tilde{G})$ for $m, n=0,1,2, \cdots$. Also, it is easy to verify that property ( $*$ ) holds. Furthermore, $f$ and $g$ are weakly compatible. Thus, we have all the conditions of Theorem 3.2 and 0 is the unique common fixed point of $f$ and $g$ in $X$.

The following example supports our Theorem 3.9.
Example 3.15 Let $X=[0, \infty)$ and define $d: X \times X \rightarrow \mathbb{R}^{+}$by $d(x, y)=|x-y|^{2}$ for all $x, y \in X$. Then $(X, d)$ is a complete $b$-metric space with the coefficient $s=2$. Let $G$ be a digraph such that $V(G)=X$ and $E(G)=\Delta \cup\{(x, y): x \leqslant y$ and $x, y \in \mathbb{N} \cup\{0\}\}$. Let $f, T: X \rightarrow X$ be defined by $f x=\ln \left(1+\frac{x}{8}\right)$ if $x \in \mathbb{N} \cup\{0\}$ and otherwise, $f x=2$, and $T x=\ln \left(1+\frac{x}{6}\right)$ if $x \in \mathbb{N} \cup\{0\}$ and otherwise, $T x=2$. Also, define altering distance functions $\psi, \varphi:[0, \infty) \rightarrow[0, \infty)$ by $\psi(t)=k t, \varphi(t)=(k-1) t$, where $1<k \leqslant \frac{25}{16}$.

We now verify that condition (14) holds for all $x, y \in X$ with $(x, y) \in E(\tilde{G})$. Let $x, y \in X$ with $(x, y) \in E(\tilde{G})$ and $y \leqslant x$.
Case-I: $(x, y) \in(\mathbb{N} \times \mathbb{N}) \cup\{(0,0)\}$. If $\frac{y}{6} \leqslant \frac{x}{8}$, then

$$
1 \leqslant \frac{1+\frac{x}{8}}{1+\frac{y}{6}} \leqslant \frac{1+\frac{x}{6}}{1+\frac{y}{6}}
$$

and so

$$
0 \leqslant \ln \left(\frac{1+\frac{x}{8}}{1+\frac{y}{6}}\right) \leqslant \ln \left(\frac{1+\frac{x}{6}}{1+\frac{y}{6}}\right) .
$$

By using the mean value theorem for the function $\ln (1+t)$, for $t \in\left[\frac{y}{6}, \frac{x}{6}\right]$, we have

$$
\begin{aligned}
\psi\left(s^{4} d(f x, T y)\right) & =16 k d(f x, T y)=16 k\left(\ln \left(1+\frac{x}{8}\right)-\ln \left(1+\frac{y}{6}\right)\right)^{2} \\
& =16 k\left(\ln \left(\frac{1+\frac{x}{8}}{1+\frac{y}{6}}\right)\right)^{2} \leqslant 16 k\left(\ln \left(\frac{1+\frac{x}{6}}{1+\frac{y}{6}}\right)\right)^{2} \\
& =16 k\left(\ln \left(1+\frac{x}{6}\right)-\ln \left(1+\frac{y}{6}\right)\right)^{2} \leqslant 16 k\left(\frac{x}{6}-\frac{y}{6}\right)^{2} \\
& \leqslant \frac{25}{36}(x-y)^{2} \leqslant d(x, y) \\
& \leqslant N_{s}(x, y)=\psi\left(N_{s}(x, y)\right)-\varphi\left(N_{s}(x, y)\right) .
\end{aligned}
$$

If $\frac{x}{8}<\frac{y}{6}$, then $0<\frac{y}{6}-\frac{x}{8} \leqslant \frac{y}{6} \Rightarrow\left(\frac{y}{6}-\frac{x}{8}\right)^{2} \leqslant \frac{y^{2}}{36}$. By using the mean value theorem for
the function $\ln (1+t)$, for $t \in\left[\frac{x}{8}, \frac{y}{6}\right]$, we have

$$
\begin{aligned}
\psi\left(s^{4} d(f x, T y)\right) & =16 k d(f x, T y)=16 k\left(\ln \left(1+\frac{x}{8}\right)-\ln \left(1+\frac{y}{6}\right)\right)^{2} \\
& \leqslant 16 k\left(\frac{y}{6}-\frac{x}{8}\right)^{2} \leqslant \frac{16}{36} k y^{2} \\
& \leqslant \frac{25}{36} y^{2}=\left(\frac{5 y}{6}\right)^{2} \\
& \leqslant\left(y-\ln \left(1+\frac{y}{6}\right)\right)^{2}=d(y, T y)
\end{aligned}
$$

Again,

$$
\begin{aligned}
\psi\left(s^{4} d(f x, T y)\right) & \leqslant 16 k\left(\frac{y}{6}-\frac{x}{8}\right)^{2} \leqslant 16 k\left(\frac{x}{6}-\frac{x}{8}\right)^{2} \\
& =16 k \frac{x^{2}}{24^{2}} \leqslant \frac{25}{24^{2}} x^{2} \\
& \leqslant \frac{49}{64} x^{2} \leqslant\left(x-\ln \left(1+\frac{x}{8}\right)\right)^{2} \\
& =d(x, f x)
\end{aligned}
$$

Thus,

$$
\begin{aligned}
\psi\left(s^{4} d(f x, T y)\right) & \leqslant \min \{d(x, f x), d(y, T y)\} \\
& \leqslant N_{s}(x, y) \\
& =\psi\left(N_{s}(x, y)\right)-\varphi\left(N_{s}(x, y)\right)
\end{aligned}
$$

Case-II: $x=y$ and $x \notin \mathbb{N} \cup\{0\}$. Then

$$
\begin{aligned}
\psi\left(s^{4} d(f x, T y)\right) & \leqslant \psi\left(s^{4} d(2,2)\right) \\
& =0 \\
& \leqslant N_{s}(x, y) \\
& =\psi\left(N_{s}(x, y)\right)-\varphi\left(N_{s}(x, y)\right)
\end{aligned}
$$

The case $(x, y) \in E(\tilde{G})$ with $x \leqslant y$ may be treated similarly.
Thus, condition (14) is satisfied. It is easy to verify that property (*) holds and $0 \in$ $C_{f \vee T}$ i.e., $C_{f \vee T} \neq \emptyset$. Thus, we have all the conditions of Theorem 3.9 and 0 is the unique common fixed point of $f$ and $T$ in $X$.

## Acknowledgements

The authors are grateful to the anonymous reviewers for their valuable comments and suggestions.

## References

[1] M. Abbas, G. Jungck, Common fixed point results for noncommuting mappings without continuity in cone metric spaces, J. Math. Anal. Appl. 341 (2008), 416-420.
[2] S. Aleomraninejad, S. Rezapour, N. Shahzad, Fixed point results on subgraphs of directed graphs, Math. Sci. (2013), 7:41.
[3] A. Aghajani, M. Abbas, J. R. Roshan, Common fixed point of generalized weak contractive mappings in partially ordered $b$-metric spaces, Math. Slovaca. 64 (2014), 941-960.
[4] M. R. Alfuraidan, M. A. Khamsi, Caristi fixed point theorem in metric spaces with a graph, Abstr. Appl. Anal. (2014), 2014:303484.
[5] V. Berinde, Some remarks on a fixed point theorem for Ćirić-type almost contractions, Carpath. J. Math. 25 (2009), 157-162.
[6] S. Banach, Sur les opérations dans les ensembles abstraits et leur application aux équations intégrales, Fund. Math. 3 (1922), 133-181.
[7] J. A. Bondy, U. S. R. Murty, Graph theory with applications, American Elsevier Publishing, New York, 1976.
[8] I. A. Bakhtin, The contraction mapping principle in almost metric spaces, Funct. Anal. Gos. Ped. Inst. Unianowsk. 30 (1989), 26-37.
[9] M. Boriceanu, Strict fixed point theorems for multivalued operators in b-metric spaces, Int. J. Mod. Math. 4 (2009), 285-301.
[10] I. Beg, A. R. Butt, S. Radojevic, The contraction principle for set valued mappings on a metric space with a graph, Comput. Math. Appl. 60 (2010), 1214-1219.
[11] F. Bojor, Fixed point of $\varphi$-contraction in metric spaces endowed with a graph, An. Uni. Cralova. 37 (2010), 85-92.
[12] F. Bojor, Fixed points of Kannan mappings in metric spaces endowed with a graph, An. St. Univ. Ovidius Constanta. 20 (2012), 31-40.
[13] S. Czerwik, Contraction mappings in b-metric spaces, Acta Math. Inform. Univ. Ostrav. 1 (1993), 5-11.
[14] L. Ćirić, M. Abbas, R. Saadati, N. Hussain, Common fixed points of almost generalized contractive mappings in ordered metric spaces, Appl. Math. Comput. 217 (2011), 5784-5789.
[15] G. Chartrand, L. Lesniak, P. Zhang, Graph and digraph, CRC Press, USA, 2011.
[16] F. Echenique, A short and constructive proof of Tarski's fixed point theorem, Internat. J. Game Theory. 33 (2005), 215-218.
[17] R. Espinola, W. A. Kirk, Fixed point theorems in R-trees with applications to graph theory, Topology Appl. 153 (2006), 1046-1055.
[18] J. I. Gross, J. Yellen, Graph theory and its applications, CRC Press, USA, 1999.
[19] G. Jungck, Common fixed points for noncontinuous nonself maps on non-metric spaces, Far East J. Math. Sci. 4 (1996), 199-215.
[20] J. Jachymski, The contraction principle for mappings on a metric space with a graph, Proc. Amer. Math. Soc. 136 (2008), 1359-1373.
[21] M. S. Khan, M. Swaleh, S. Sessa, Fixed point theorems by altering distances between the points, Bull. Aus. Math. Soc. 30 (1984), 1-9.
[22] R. Miculescu, A. Mihail, New Fixed point theorems for set-valued contractions in b-metric spaces, J. Fixed Point Theory Appl. 19 (2017), 2153-2163.
[23] S. K. Mohanta, Common fixed points in b-metric spaces endowed with a graph, Matematic. Vesnik. 68 (2016), 140-154.
[24] J. R. Roshan, V. Parvaneh, S. Sedghi, N. Shobkolaei, W. Shatanawi, Common fixed points of almost generalized $(\psi, \varphi)_{s}$-contractive mappings in ordered $b$-metric spaces, Fixed Point Theory Appl. (2013), 2013:159.
[25] W. Shatanawi, A. Pitea, R. Lazović, Contraction conditions using comparison functions on $b$-metric spaces, Fixed Point Theory Appl. (2014), 2014:135.


[^0]:    *Corresponding author.
    E-mail address: smwbes@yahoo.in (S. K. Mohanta); deepbiswas91@gmail.com (D. Biswas)

