

Common fixed point of four maps in S_b -metric spaces

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Abstract. In this paper is introduced a new type of generalization of metric spaces called S_b metric space. For this new kind of spaces it has been proved a common fixed point theorem for four mappings which satisfy generalized contractive condition. We also present example to confirm our theorem.

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1. Introduction

The Banach contraction principle is the most celebrated fixed point theorem and has been generalized in various directions, see ([1]-[12]). Fixed point problems for contractive mappings in metric spaces with a partially order have been studied by many authors. Sedghi and Shobe [12] proved a common fixed point of four maps in complete metric spaces. Abbas et al. in [1] proved a common fixed points of four mappings satisfying a generalized weak contractive condition in the partially ordered metric spaces. Roshan et al. [8] proved a common fixed point of four maps in b -metric spaces.

The aim of this paper is to present some common fixed point results for four mappings satisfying generalized contractive condition in a S_b -metric space, where the S_b -metric is

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not necessary continuous. First we recall some notions, lemmas and examples which will be useful later.

Definition 1.1 [10] Let X be a nonempty set. A S -metric on X is a function $S : X^3 \rightarrow [0, \infty)$ that satisfies the following conditions for all $x, y, z, a \in X$.

- (S1) $0 < S(x, y, z)$ for all $x, y, z \in X$ with $x \neq y \neq z \neq x$,
- (S2) $S(x, y, z) = 0 \Leftrightarrow x = y = z$,
- (S3) $S(x, y, z) \leq S(x, x, a) + S(y, y, a) + S(z, z, a)$ for all $x, y, z, a \in X$.

The pair (X, S) is called a S -metric space.

Example 1.2 [10] Let $X = \mathbb{R}^2$ and d be an ordinary metric on X . Therefore $S(x, y, z) = d(x, y) + d(x, z) + d(y, z)$ for all $x, y, z \in \mathbb{R}^2$, is a S -metric on X .

Lemma 1.3 [9] In a S -metric space we have $S(x, x, y) = S(y, y, x)$.

Definition 1.4 [11] Let (X, S) be a S -metric space. For $r > 0$ and $x \in X$ we define the open ball $B_S(x, r)$ and closed ball $B_S[x, r]$ with center x and radius r as follows respectively:

$$B_s(x, r) = \{y \in X : S(y, y, x) < r\},$$

$$B_s[x, r] = \{y \in X : S(y, y, x) \leq r\}.$$

Definition 1.5 [11] Let (X, S) be a S -metric space and $A \subseteq X$.

- (1) If for every $x \in X$ there exists $r > 0$ such that $B_s(x, r) \subseteq A$, then the subset A is called open subset of X .
- (2) Subset A of X is said to be S -bounded if there exists $r > 0$ such that $S(x, x, y) < r$ for all $x, y \in A$.
- (3) A sequence $\{x_n\}$ in X convergents to x if and only if $S(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow \infty$. That is for each $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that for each $n \geq n_0$, $S(x_n, x_n, x) < \varepsilon$ and we denote by $\lim_{n \rightarrow \infty} x_n = x$.
- (4) Sequence $\{x_n\}$ in X is called a Cauchy sequence if for each $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that for each $n, m \geq n_0$, $S(x_n, x_n, x_m) < \varepsilon$.
- (5) The S -metric space (X, S) is said to be complete if every Cauchy sequence is convergent.
- (6) Let τ be the of all $A \subseteq X$ witch $x \in A$ if and only if there exists $r > 0$ such that $B_s(x, r) \subseteq A$. Then τ is a topology on X .

Lemma 1.6 [11] Let (X, S) be a S -metric space. If there exist sequence $\{x_n\}, \{y_n\}$ such that $\lim_{n \rightarrow \infty} x_n = x$ and $\lim_{n \rightarrow \infty} y_n = y$, then $\lim_{n \rightarrow \infty} S(x_n, x_n, y_n) = S(x, x, y)$.

Following the results of Czerwik [3] and Bakhtin [2] in the next definition we introduced the notion of S_b -metric space, as a generalization of S - metric space in which the triangular inequality has been replaced by weaker one.

Definition 1.7 Let X be a nonempty set and $b \geq 1$ be a given real number. Suppose that a mapping $S : X^3 \rightarrow [0, \infty)$ satisfies :

- (S_b1) $0 < S(x, y, z)$ for all $x, y, z \in X$ with $x \neq y \neq z \neq x$,
- (S_b2) $S(x, y, z) = 0 \Leftrightarrow x = y = z$,
- (S_b3) $S(x, y, z) \leq b(S(x, x, a) + S(y, y, a) + S(z, z, a))$ for all $x, y, z, a \in X$

Then S is called a S_b -metric and the pair (X, S) is called a S_b -metric space.

Remark 1 It should be noted that, the class of S_b -metric spaces is effectively larger than that of S -metric spaces. Indeed each S -metric space is a S_b -metric space with $b = 1$.

Following example shows that a S_b -metric on X need not be a S -metric on X .

Example 1.8 Let (X, S) be a S -metric space, and $S_*(x, y, z) = S(x, y, z)^p$, where $p > 1$ is a real number. Note that S_* is a S_b -metric with $b = 2^{2(p-1)}$. Obviously, S_* satisfies condition (S_b1) , (S_b2) of Definition 1.7, so it suffice to show (S_b3) holds. If $1 < p < \infty$, then the convexity of the function $f(x) = x^p$, ($x > 0$) implies that $(a+b)^p \leq 2^{p-1}(a^p + b^p)$. Thus, for each $x, y, z, a \in X$, we obtain

$$\begin{aligned} S_*(x, y, z) &= S(x, y, z)^p \\ &\leq ([S(x, x, a) + S(y, y, a)] + S(z, z, a))^p \\ &\leq 2^{p-1}([S(x, x, a) + S(y, y, a)]^p + S(z, z, a)^p) \\ &\leq 2^{p-1}(2^{p-1}(S(x, x, a)^p + S(y, y, a)^p) + S(z, z, a)^p) \\ &\leq 2^{(p-1)}(2^{p-1}(S(x, x, a)^p + S(y, y, a)^p) + 2^{p-1}S(z, z, a)^p) \\ &= 2^{2(p-1)}(S(x, x, a)^p + S(y, y, a)^p + S(z, z, a)^p) \\ &= 2^{2(p-1)}(S_*(x, x, a) + S_*(y, y, a) + S_*(z, z, a)) \end{aligned}$$

so, S_* is a S_b -metric with $b = 2^{2(p-1)}$.

Also in the above example, (X, S_*) is not necessarily a S -metric space. For example, let $X = \mathbb{R}$ and $S_*(x, y, z) = (|y + z - 2x| + |y - z|)^2$ is a S_b -metric on \mathbb{R} , with $p = 2$, $b = 2^{2(2-1)} = 4$, for all $x, y, z \in \mathbb{R}$. But it is not a S -metric on \mathbb{R} .

To see this, let $x = 3, y = 5, z = 7, a = \frac{7}{2}$. Hence, we get

$$\begin{aligned} S_*(3, 5, 7) &= (|5 + 7 - 6| + |5 - 7|)^2 = 8^2 = 64 \\ S_*(3, 3, \frac{7}{2}) &= \left(\left| 3 + \frac{7}{2} - 6 \right| + \left| 3 - \frac{7}{2} \right| \right)^2 = 1^2 = 1 \\ S_*(5, 5, \frac{7}{2}) &= \left(\left| 5 + \frac{7}{2} - 10 \right| + \left| 5 - \frac{7}{2} \right| \right)^2 = 3^2 = 9 \\ S_*(7, 7, \frac{7}{2}) &= \left(\left| 7 + \frac{7}{2} - 14 \right| + \left| 7 - \frac{7}{2} \right| \right)^2 = 7^2 = 49. \end{aligned}$$

Therefore, $S_*(3, 5, 7) = 64 \geq 59 = S_*(3, 3, \frac{7}{2}) + S_*(5, 5, \frac{7}{2}) + S_*(7, 7, \frac{7}{2})$.

Now we present some definitions and propositions in S_b -metric space.

Definition 1.9 Let (X, S) be a S_b -metric space. Then, for $x \in X, r > 0$ we defined the open ball $B_S(x, r)$ and closed ball $B_S[x, r]$ with center x and radius r as follows respectively:

$$\begin{aligned} B_S(x, r) &= \{y \in X : S(y, y, x) < r\}, \\ B_S[x, r] &= \{y \in X : S(y, y, x) \leq r\}. \end{aligned}$$

Example 1.10 Let $X = \mathbb{R}$. Denote $S(x, y, z) = (|y + z - 2x| + |y - z|)^2$ is a S_b -metric on \mathbb{R} with $b = 2^{2(2-1)} = 4$, for all $x, y, z \in \mathbb{R}$. Thus

$$\begin{aligned} B_S(1, 2) &= \{y \in \mathbb{R} : S(y, y, 1) < 2\} \\ &= \{y \in \mathbb{R} : |y - 1| < \frac{\sqrt{2}}{2}\} \\ &= \{y \in \mathbb{R} : 1 - \frac{\sqrt{2}}{2} < y < 1 + \frac{\sqrt{2}}{2}\} \\ &= (1 - \frac{\sqrt{2}}{2}, 1 + \frac{\sqrt{2}}{2}). \end{aligned}$$

Lemma 1.11 In a S_b -metric space, we have

$$S(x, x, y) \leq bS(y, y, x)$$

and

$$S(y, y, x) \leq bS(x, x, y)$$

Proof. By third condition of S_b -metric, we have

$$S(x, x, y) \leq b(2S(x, x, x) + S(y, y, x)) = bS(y, y, x)$$

and similarly

$$S(y, y, x) \leq b(2S(y, y, y) + S(x, x, y)) = bS(x, x, y).$$

■

Lemma 1.12 Let (X, S) be a S_b -metric space. Then

$$S(x, x, z) \leq 2bS(x, x, y) + b^2S(y, y, z).$$

Proof. By third condition of S_b -metric and lemma (1.3), we have

$$\begin{aligned} S(x, x, z) &\leq b(S(x, x, y) + S(x, x, y) + S(z, z, y)) \\ &\leq b(2S(x, x, y) + bS(y, y, z)) \\ &= 2bS(x, x, y) + b^2S(y, y, z). \end{aligned}$$

■

The notions of convergence and Cauchy sequence is introducing as in the case of S -metric spaces.

Definition 1.13 Let (X, S) be a S_b -metric space. A sequence $\{x_n\}$ in X is said to be :

(1) S_b -Cauchy sequence if, for each $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that $S(x_n, x_n, x_m) < \varepsilon$ for each $m, n \geq n_0$.

(2) S_b -convergent to a point $x \in X$ if, for each $\varepsilon > 0$, there exists a positive integer n_0 such that $S(x_n, x_n, x) < \varepsilon$ or $S(x, x, x_n) < \varepsilon$ for all $n \geq n_0$ and we denote by

$$\lim_{n \rightarrow \infty} x_n = x.$$

Definition 1.14 A S_b -metric space (X, S) is called complete if every S_b -Cauchy sequence is S_b -convergent in X .

Definition 1.15 Let (X, S) and (X', S') be S_b -metric spaces, and let $f : (X, S) \rightarrow (X', S')$ be a function. Then f is said to be continuous at a point $a \in X$ if and only if for every sequence x_n in X , $S(x_n, x_n, a) \rightarrow 0$ implies $S'(f(x_n), f(x_n), f(a)) \rightarrow 0$. A function f is continuous at X if and only if it is continuous at all $a \in X$.

The term of compatible mappings is introduced analogously as in the case of S -metric spaces.

Definition 1.16 Let (X, S) be a S_b -metric space. A pair $\{f, g\}$ is said to be compatible if and only if $\lim_{n \rightarrow \infty} S(fgx_n, fgx_n, gfx_n) = 0$, whenever $\{x_n\}$ is a sequence in X such that $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t$ for some $t \in X$.

Lemma 1.17 Let (X, S) be a S_b -metric space with $b \geq 1$, and suppose that $\{x_n\}$ is a S_b -convergent to x , then we have

$$\frac{1}{b^2}S(x, x, y) \leq \liminf_{n \rightarrow \infty} S(x_n, x_n, y) \leq \limsup_{n \rightarrow \infty} S(x_n, x_n, y) \leq b^2S(x, x, y).$$

In particular, if $x = y$, then we have $\lim_{n \rightarrow \infty} S(x_n, x_n, y) = 0$.

Proof. By (S_b3) and Lemma 1.12, we have

$$S(x_n, x_n, y) \leq 2bS(x_n, x_n, x) + b^2S(x, x, y),$$

and

$$\frac{1}{b^2}S(x, x, y) \leq 2S(x_n, x_n, x) + S(x_n, x_n, y).$$

Taking the upper limit as $n \rightarrow \infty$ in the first inequality and the lower limit as $n \rightarrow \infty$ in the second inequality we obtain the desired result. ■

Lemma 1.18 Let (X, S) be a S_b -metric space. If there exist two sequences $\{x_n\}$ and $\{y_n\}$ such that $\lim_{n \rightarrow \infty} S(x_n, x_n, y_n) = 0$, whenever $\{x_n\}$ is a sequence in X such that $\lim_{n \rightarrow \infty} x_n = t$ for some $t \in X$ then $\lim_{n \rightarrow \infty} y_n = t$.

Proof. By a triangle inequality in a S_b -metric space, we have

$$S(y_n, y_n, t) \leq b(2S(y_n, y_n, x_n) + bS(x_n, x_n, t)).$$

Now, by taking the upper limit when $n \rightarrow \infty$ in the above inequality we get

$$\limsup_{n \rightarrow \infty} S(y_n, y_n, t) \leq b^2(\limsup_{n \rightarrow \infty} 2S(x_n, x_n, y_n) + \limsup_{n \rightarrow \infty} S(x_n, x_n, t)) = 0.$$

Hence $\lim_{n \rightarrow \infty} y_n = t$.

2. Main results

Our first results is the following common fixed point theorem.

Theorem 2.1 Suppose that f, g, M and T are self mappings on a complete S_b -metric space (X, S) such that $f(X) \subseteq T(X)$, $g(X) \subseteq M(X)$. If

$$S(fx, fx, gy) \leq \frac{q}{b^4} \max\{S(Mx, Mx, Ty), S(fx, fx, Mx), S(gy, gy, Ty), \quad (1)$$

$$\frac{1}{2}(S(Mx, Mx, gy) + S(fx, fx, Ty))\}$$

holds for each $x, y \in X$ with $0 < q < 1$ and $b \geq \frac{3}{2}$, then f, g, M and T have a unique common fixed point in X provided that M and T are continuous and pairs $\{f, M\}$ and $\{g, T\}$ are compatible.

Proof. Let $x_0 \in X$. As $f(X) \subseteq T(X)$, there exists $x_1 \in X$ such that $fx_0 = Tx_1$. Since $gx_1 \in M(X)$, we can choose $x_2 \in X$ such that $gx_1 = Mx_2$. In general, x_{2n+1} and x_{2n+2} are chosen in X such that $fx_{2n} = Tx_{2n+1}$ and $gx_{2n+1} = Mx_{2n+2}$. Define a sequence y_n in X such that $y_{2n} = fx_{2n} = Tx_{2n+1}$, and $y_{2n+1} = gx_{2n+1} = Mx_{2n+2}$, for all $n \geq 0$. Now, we show that y_n is a Cauchy sequence. Consider

$$\begin{aligned} S(y_{2n}, y_{2n}, y_{2n+1}) &= S(fx_{2n}, fx_{2n}, gx_{2n+1}) \\ &\leq \frac{q}{b^4} \max \{S(Mx_{2n}, Mx_{2n}, Tx_{2n+1}), S(fx_{2n}, fx_{2n}, Mx_{2n}), \\ &\quad S(gx_{2n+1}, gx_{2n+1}, Tx_{2n+1}), \\ &\quad \frac{1}{2}(S(Mx_{2n}, Mx_{2n}, gx_{2n+1}) + S(fx_{2n}, fx_{2n}, Tx_{2n+1}))\} \\ &= \frac{q}{b^4} \max \{S(y_{2n-1}, y_{2n-1}, y_{2n}), S(y_{2n}, y_{2n}, y_{2n-1}), \\ &\quad S(y_{2n+1}, y_{2n+1}, y_{2n}), \\ &\quad \frac{1}{2}(S(y_{2n-1}, y_{2n-1}, y_{2n+1}) + S(y_{2n}, y_{2n}, y_{2n}))\} \\ &\leq \frac{q}{b^4} \max \{S(y_{2n-1}, y_{2n-1}, y_{2n}), bS(y_{2n-1}, y_{2n-1}, y_{2n}), \\ &\quad S(y_{2n+1}, y_{2n+1}, y_{2n}), \frac{S(y_{2n-1}, y_{2n-1}, y_{2n+1})}{2}\} \\ &\leq \frac{q}{b^4} \max \{S(y_{2n-1}, y_{2n-1}, y_{2n}), bS(y_{2n-1}, y_{2n-1}, y_{2n}), S(y_{2n+1}, y_{2n+1}, y_{2n}), \\ &\quad \frac{b}{2}(S(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n+1}, y_{2n+1}, y_{2n}))\} \\ &\leq \frac{q}{b^4} \max \{S(y_{2n-1}, y_{2n-1}, y_{2n}), bS(y_{2n-1}, y_{2n-1}, y_{2n}), bS(y_{2n}, y_{2n}, y_{2n+1}), \\ &\quad \frac{b}{2}(2S(y_{2n-1}, y_{2n-1}, y_{2n}) + bS(y_{2n+1}, y_{2n+1}, y_{2n}))\}. \end{aligned}$$

Now, since

$$\begin{aligned} S(y_{2n-1}, y_{2n-1}, y_{2n}) &\leq bS(y_{2n-1}, y_{2n-1}, y_{2n}) \\ &\leq bS(y_{2n-1}, y_{2n-1}, y_{2n}) + \frac{b^2}{2}S(y_{2n}, y_{2n}, y_{2n+1}) \end{aligned}$$

we have

$$\begin{aligned} S(y_{2n}, y_{2n}, y_{2n+1}) &\leq \max \left\{ bS(y_{2n}, y_{2n}, y_{2n+1}), \right. \\ &\quad \left. bS(y_{2n-1}, y_{2n-1}, y_{2n}) + \frac{b^2}{2}S(y_{2n}, y_{2n}, y_{2n+1}) \right\}. \end{aligned}$$

If $\max = bS(y_{2n}, y_{2n}, y_{2n+1})$ we obtain

$$S(y_{2n}, y_{2n}, y_{2n+1}) \leq \frac{q}{b^3}S(y_{2n}, y_{2n}, y_{2n+1}) < S(y_{2n}, y_{2n}, y_{2n+1}).$$

Contradiction. So, $\max = bS(y_{2n-1}, y_{2n-1}, y_{2n}) + \frac{b^2}{2}S(y_{2n}, y_{2n}, y_{2n+1})$ and we have

$$S(y_{2n}, y_{2n}, y_{2n+1}) \leq \frac{q}{b^4} \left(bS(y_{2n-1}, y_{2n-1}, y_{2n}) + \frac{b^2}{2}S(y_{2n}, y_{2n}, y_{2n+1}) \right)$$

i.e.,

$$S(y_{2n}, y_{2n}, y_{2n+1}) \leq \frac{2q}{2b^3 - qb} S(y_{2n-1}, y_{2n-1}, y_{2n}).$$

Let $\lambda = \frac{2q}{2b^3 - qb}$. Since $b \geq \frac{3}{2}$ we have that $0 < \lambda < 1$. Now,

$$\begin{aligned} S(y_{2n}, y_{2n}, y_{2n+1}) &\leq \lambda S(y_{2n-1}, y_{2n-1}, y_{2n}) \leq \lambda^2 S(y_{2n-2}, y_{2n-2}, y_{2n-1}) \\ &\leq \dots \leq \lambda^n S(y_0, y_0, y_1). \end{aligned}$$

Hence, for all $n \geq 2$, we obtain

$$S(y_{n-1}, y_{n-1}, y_n) \leq \dots \leq \lambda^{n-1} S(y_0, y_0, y_1). \quad (2)$$

Using Lemma 1.11 and (S_b3) , and (2) for all $n > m$, we have

$$\begin{aligned}
 S(y_m, y_m, y_n) &\leq b(2S(y_m, y_m, y_{m+1}) + S(y_n, y_n, y_{m+1})) \\
 &\leq 2bS(y_m, y_m, y_{m+1}) + b^2S(y_{m+1}, y_{m+1}, y_n) \\
 &\leq 2bS(y_m, y_m, y_{m+1}) + 2b^3S(y_{m+1}, y_{m+1}, y_{m+2}) \\
 &\quad + b^4S(y_{m+2}, y_{m+2}, y_n) \leq \dots \\
 &\leq 2b(S(y_m, y_m, y_{m+1}) + b^2S(y_{m+1}, y_{m+1}, y_{m+2}) \\
 &\quad + \dots + b^{2(n-m-1)}S(y_{n-1}, y_{n-1}, y_n)) \\
 &\leq 2b(\lambda^m + b^2\lambda^{m+1} + \dots + b^{2(n-m-1)}\lambda^{n-1})S(y_0, y_0, y_1) \\
 &\leq 2bS(y_0, y_0, y_1)(\lambda^m + b^2\lambda^{m+1} + \dots) \\
 &\leq \frac{2b\lambda^m}{1 - b^2\lambda}S(y_0, y_0, y_1).
 \end{aligned}$$

On taking limit as $m, n \rightarrow \infty$, we have $S(y_m, y_m, y_n) \rightarrow 0$ as $b^2\lambda < 1$. Therefore $\{y_n\}$ is a Cauchy sequence. Since X is a complete S_b -metric space, there is some y in X such that

$$\lim_{n \rightarrow \infty} f x_{2n} = \lim_{n \rightarrow \infty} T x_{2n+1} = \lim_{n \rightarrow \infty} g x_{2n+1} = \lim_{n \rightarrow \infty} M x_{2n+2} = y.$$

We show that y is a common fixed point of f , g , M and T . Since M is continuous, therefore

$$\lim_{n \rightarrow \infty} M^2 x_{2n+2} = My \quad \text{and} \quad \lim_{n \rightarrow \infty} M f x_{2n} = My.$$

Since a pair $\{f, M\}$ is compatible, $\lim_{n \rightarrow \infty} S(f M x_{2n}, f M x_{2n}, M f x_{2n}) = 0$. So by Lemma 1.18, we have $\lim_{n \rightarrow \infty} f M x_{2n} = My$. Putting $x = M x_{2n}$ and $y = x_{2n+1}$ in (1) we obtain

$$\begin{aligned}
 S(f M x_{2n}, f M x_{2n}, g x_{2n+1}) &\leq \frac{q}{b^4} \max \{S(M^2 x_{2n}, M^2 x_{2n}, T x_{2n+1}), \\
 &\quad S(f M x_{2n}, f M x_{2n}, M^2 x_{2n}), S(g x_{2n+1}, g x_{2n+1}, T x_{2n+1}), \\
 &\quad \frac{1}{2}(S(M^2 x_{2n}, M^2 x_{2n}, g x_{2n+1}) + S(f M x_{2n}, f M x_{2n}, T x_{2n+1}))\}.
 \end{aligned} \tag{3}$$

Taking the upper limit as $n \rightarrow \infty$ in (3) and using Lemma 1.17, we get

$$\begin{aligned} \frac{S(My, My, y)}{b^2} &\leq \limsup_{n \rightarrow \infty} S(fMx_{2n}, fMx_{2n}, gx_{2n+1}) \\ &\leq \frac{q}{b^4} \max \left\{ \limsup_{n \rightarrow \infty} S(M^2x_{2n}, M^2x_{2n}, Tx_{2n+1}), \right. \\ &\quad \limsup_{n \rightarrow \infty} S(fMx_{2n}, fMx_{2n}, M^2x_{2n}), \\ &\quad \limsup_{n \rightarrow \infty} S(gx_{2n+1}, gx_{2n+1}, Tx_{2n+1}), \\ &\quad \left. \frac{1}{2} \left(\limsup_{n \rightarrow \infty} S(M^2x_{2n}, M^2x_{2n}, gx_{2n+1}) \right. \right. \\ &\quad \left. \left. + \limsup_{n \rightarrow \infty} S(fMx_{2n}, fMx_{2n}, Tx_{2n+1}) \right) \right\} \\ &\leq \frac{q}{b^4} \max \left\{ b^2 S(My, My, y), 0, 0, \frac{b^2}{2} (S(My, My, y) + S(My, My, y)) \right\} \\ &= \frac{q}{b^4} b^2 S(My, My, y) = \frac{q}{b^2} S(My, My, y). \end{aligned}$$

Consequently, $S(My, My, y) \leq qS(My, My, y)$. As $0 < q < 1$, so $My = y$. Using continuity of T , we obtain $\lim_{n \rightarrow \infty} T^2x_{2n+1} = Ty$ and $\lim_{n \rightarrow \infty} Tgx_{2n+1} = Ty$. Since g and T are compatible, $\lim_{n \rightarrow \infty} S(gTx_n, gTx_n, Tgx_n) = 0$. So, by Lemma 1.18, we have $\lim_{n \rightarrow \infty} gTx_{2n} = Ty$. Putting $x = x_{2n}$ and $y = Tx_{2n+1}$ in (1), we obtain

$$\begin{aligned} S(fx_{2n}, fx_{2n}, gTx_{2n+1}) &\leq \frac{q}{b^4} \max \left\{ S(Mx_{2n}, Mx_{2n}, T^2x_{2n+1}), \right. \\ &\quad S(fx_{2n}, fx_{2n}, Mx_{2n}), S(gTx_{2n+1}, gTx_{2n+1}, T^2x_{2n+1}), \\ &\quad \left. \frac{1}{2} (S(Mx_{2n}, Mx_{2n}, gTx_{2n+1}) + S(fx_{2n}, fx_{2n}, T^2x_{2n+1})) \right\}. \end{aligned} \tag{4}$$

Taking upper limit as $n \rightarrow \infty$ in (4) and using Lemma 1.17, we obtain

$$\begin{aligned} \frac{S(y, y, Ty)}{b^2} &\leq \limsup_{n \rightarrow \infty} S(fx_{2n}, fx_{2n}, gTx_{2n+1}) \\ &\leq \frac{q}{b^4} \max \left\{ b^2 (S(y, y, Ty)), 0, 0, \frac{b^2}{2} (S(y, y, Ty) + S(y, y, Ty)) \right\} \\ &= \frac{qS(y, y, Ty)}{b^2}, \end{aligned}$$

which implies that $Ty = y$. Also, we can apply condition (1) to obtain

$$\begin{aligned} S(fy, fy, gx_{2n+1}) &\leq \frac{q}{b^4} \max \left\{ S(My, My, Tx_{2n+1}), S(fy, fy, My), \right. \\ &\quad S(gx_{2n+1}, gx_{2n+1}, Tx_{2n+1}), \frac{1}{2} (S(My, My, gx_{2n+1}) \\ &\quad \left. + S(fy, fy, Tx_{2n+1})) \right\}. \end{aligned} \tag{5}$$

Taking upper limit $n \rightarrow \infty$ in (5), and using $My = Ty = y$, we have

$$\begin{aligned} \frac{S(fy, fy, y)}{b^2} &\leq \frac{q}{b^4} \max\{b^2 S(My, My, y), b^2 S(fy, fy, My), b^2 S(y, y, y)\}, \\ &\quad \frac{b^2}{2} (S(My, My, y) + S(fy, fy, y)) \\ &= \frac{q}{b^2} S(fy, fy, y), \end{aligned}$$

which implies that $S(fy, fy, y) = 0$ and $fy = y$ as $0 < q < 1$. Finally, from condition (1), and the fact $My = Ty = fy = y$, we have

$$\begin{aligned} S(y, y, gy) &= S(fy, fy, gy) \\ &\leq \frac{q}{b^4} \max\{S(My, My, Ty), S(fy, fy, My), S(gy, gy, Ty)\}, \\ &\quad \frac{1}{2} (S(My, My, gy) + S(fy, fy, Ty)) \\ &\leq \frac{q}{b^3} S(y, y, gy) \\ &\leq q S(y, y, gy), \end{aligned}$$

which implies that $S(y, y, gy) = 0$ and $gy = y$. Hence $My = Ty = fy = gy = y$. If there exists another common fixed point x in X for f, g, M and T , then

$$\begin{aligned} S(x, x, y) &= S(fx, fx, gy) \\ &\leq \frac{q}{b^4} \max\{S(Mx, Mx, Ty), S(fx, fx, Mx), S(gy, gy, Ty)\}, \\ &\quad \frac{1}{2} (S(Mx, Mx, gy) + S(fx, fx, Ty)) \\ &= \frac{q}{b^4} \max\{S(x, x, y), S(x, x, x), S(y, y, y), \frac{1}{2} (S(x, x, y) + S(x, x, y))\} \\ &= \frac{q}{b^4} S(x, x, y) \\ &\leq q S(x, x, y), \end{aligned}$$

which further implies that $S(x, x, y) = 0$ and hence, $x = y$. Thus, y is a unique common fixed point of f, g, M and T . ■

Example 2.2 Let $X = [0, 1]$ be endowed with S_b -metric $S_*(x, y, z) = (|y + z - 2x| + |y - z|)^2$, where $b = 4$. Define f, g, M and T on X by $f(x) = (\frac{x}{4})^8$, $g(x) = (\frac{x}{8})^4$, $M(x) = (\frac{x}{4})^4$, $T(x) = (\frac{x}{8})^2$.

Obviously, $f(X) \subseteq T(X)$ and $g(X) \subseteq M(X)$. Furthermore, the pairs $\{f, M\}$ and $\{g, T\}$

are compatible. For each $x, y \in X$, we have

$$\begin{aligned} S(fx, fx, gy) &= (|gy - fx| + |fx - gy|)^2 \\ &= (2|fx - gy|)^2 \\ &= 4\left(\left(\frac{x}{4}\right)^8 - \left(\frac{y}{8}\right)^4\right)^2 \\ &= 4\left(\left(\frac{x}{4}\right)^4 + \left(\frac{y}{8}\right)^2\right)^2 \cdot \left(\left(\frac{x}{4}\right)^4 - \left(\frac{y}{8}\right)^2\right)^2 \\ &\leq \left(\frac{1}{4^4} + \frac{1}{8^2}\right)^2 S(Mx, Mx, Ty) \\ &= \frac{25}{4^4} S(Mx, Mx, Ty), \end{aligned}$$

where $\frac{25}{4^4} \leq q \leq 1$ and $b = 4$. Thus, f, g, M and T satisfy all condition of Theorem 2.1. Moreover 0 is the unique common fixed point of f, g, M and T .

Corollary 2.3 Let (X, S) be a complete S_b -metric space and $f, g : X \rightarrow X$ two mappings such that

$$S(fx, fx, gy) \leq \frac{q}{b^4} \max\{S(x, x, y), S(fx, fx, x), S(gy, gy, y), \frac{1}{2}(S(x, x, gy) + S(fx, fx, y))\},$$

holds for all $x, y \in X$ with $0 < q < 1$ and $b \geq \frac{3}{2}$. Then, there exists a unique point $y \in X$ such that $fy = gy = y$.

Proof. If we take $M = T = I_X$ (identity mapping on X), then theorem (2.1) gives that f and g have a unique common fixed point. ■

Proof. If we take f and g as identity maps on X , then Theorem 2.1 gives that M and T have a unique common fixed point. ■

Corollary 2.4 Let (X, S) be a complete S_b -metric space and $f : X \rightarrow X$ mapping such that

$$S(fx, fx, fy) \leq \frac{q}{b^4} \max\{S(x, x, y), S(fx, fx, x), S(fy, fy, y), \frac{1}{2}(S(x, x, fy) + S(fx, fx, y))\},$$

holds for all $x, y \in X$ with $0 < q < 1$ and $b \geq \frac{3}{2}$. Then f has a unique fixed point in X .

Proof. Take M and T as identity maps on X and $f = g$ and then apply Theorem 2.1. ■

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